



(12) **United States Patent**
von Flotow et al.

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(54) **ROTORCRAFT-ASSISTED SYSTEM FOR LAUNCHING AND RETRIEVING A FIXED-WING AIRCRAFT INTO AND FROM FREE FLIGHT**

1/222 (2013.01); *B64C 2201/082* (2013.01);
B64C 2201/182 (2013.01); *B64C 2201/20*
(2013.01)

(71) Applicant: **Hood Technology Corporation**, Hood River, OR (US)

(58) **Field of Classification Search**
CPC *B64C 2201/182*; *B64F 1/02*; *B64F 1/029*;
B64F 1/0295
See application file for complete search history.

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(73) Assignee: **Hood Technology Corporation**, Hood River, OR (US)

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Related U.S. Application Data

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(51) **Int. Cl.**
B64D 5/00 (2006.01)
B64F 1/02 (2006.01)
B64F 1/04 (2006.01)
B64F 1/22 (2006.01)
B64C 39/02 (2006.01)

Primary Examiner — Joseph W Sanderson

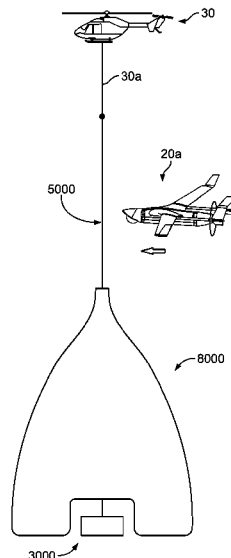
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(52) **U.S. Cl.**
CPC *B64D 5/00* (2013.01); *B64C 39/024*
(2013.01); *B64F 1/029* (2020.01); *B64F 1/0295* (2020.01); *B64F 1/04* (2013.01); *B64F*

(57) **ABSTRACT**

A rotorcraft-assisted system for launching and retrieving a fixed-wing aircraft into and from free flight. The launch and retrieval system is usable with a rotorcraft to launch a fixed-wing aircraft into free, wing-borne flight and to retrieve the fixed-wing aircraft from free, wing-borne flight.

22 Claims, 54 Drawing Sheets



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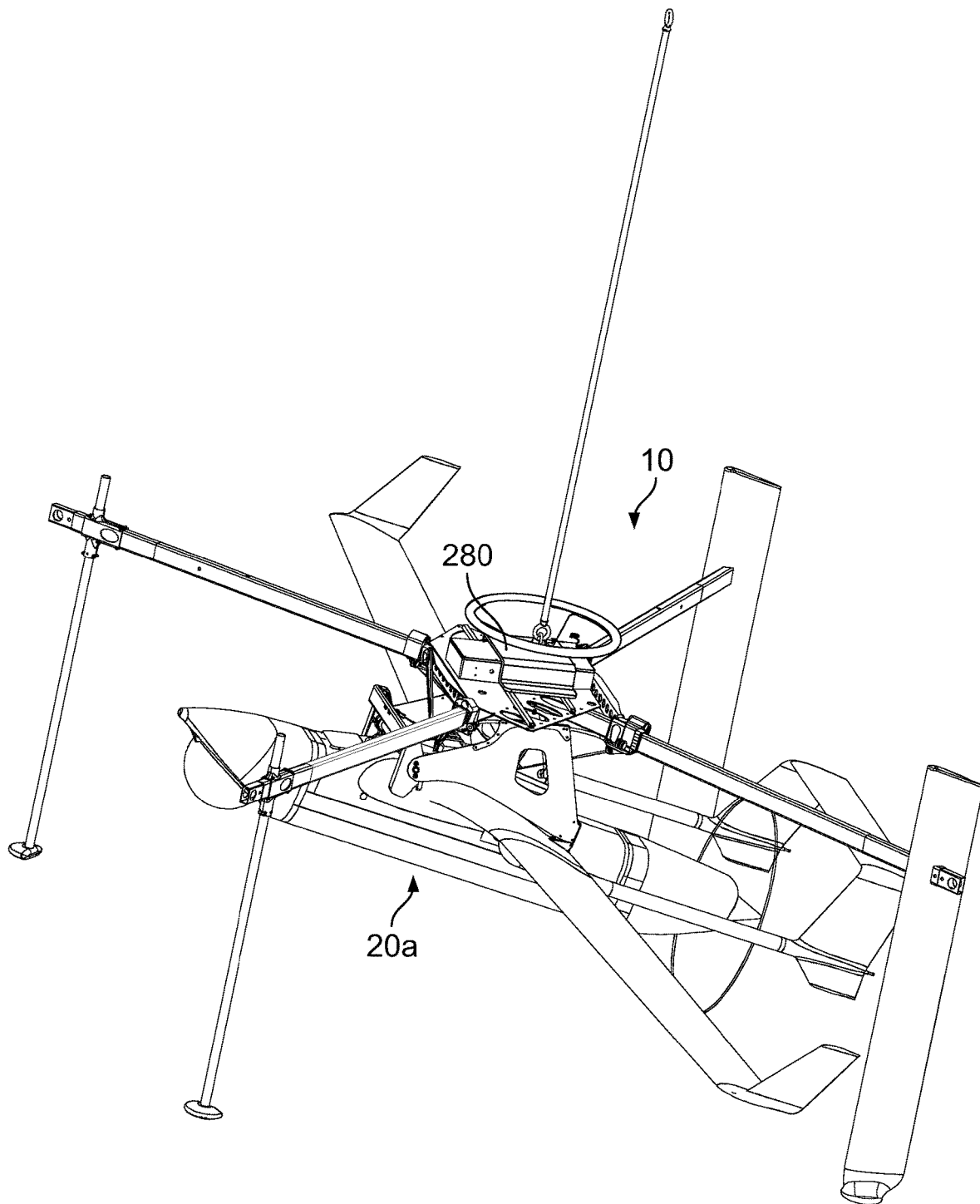


FIG. 1A

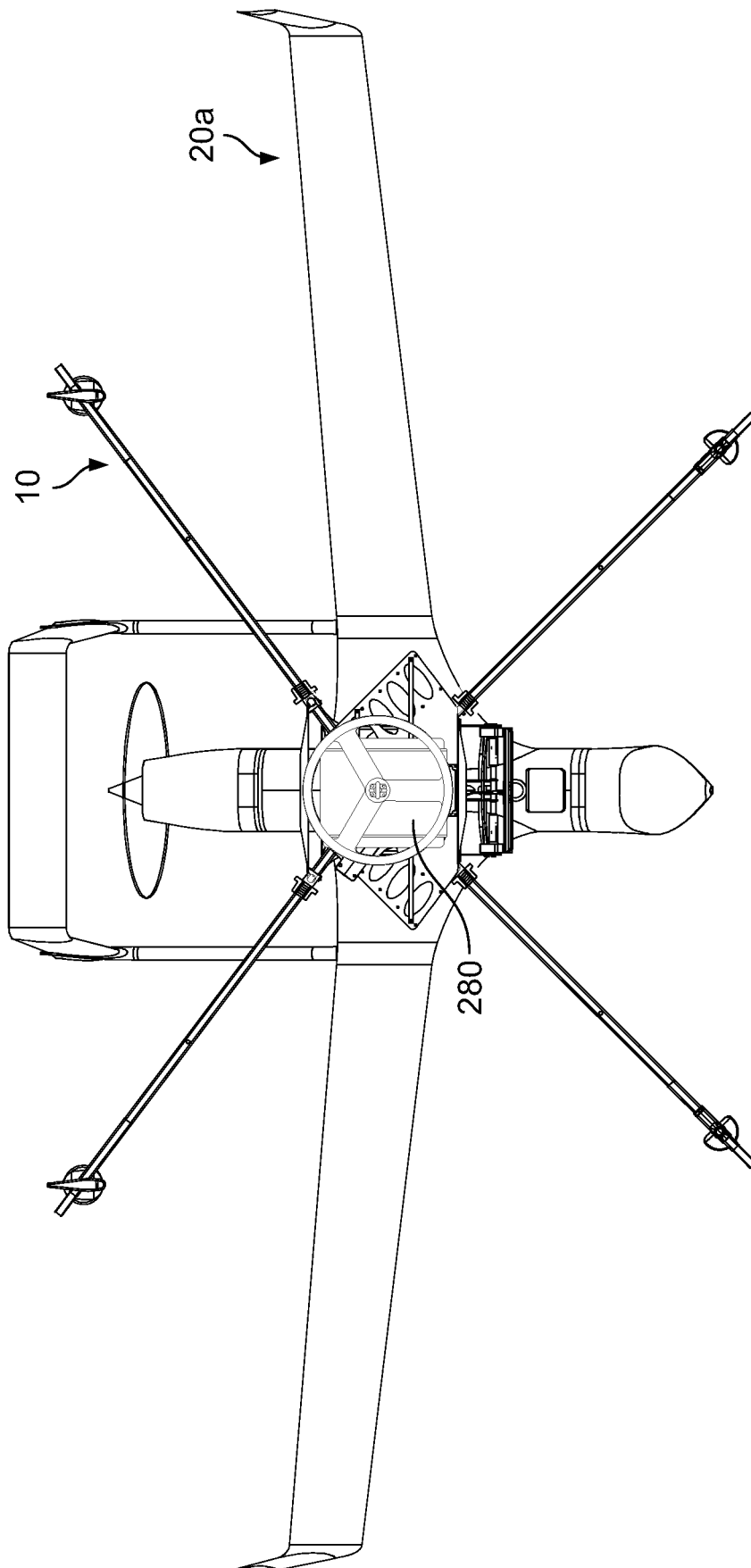
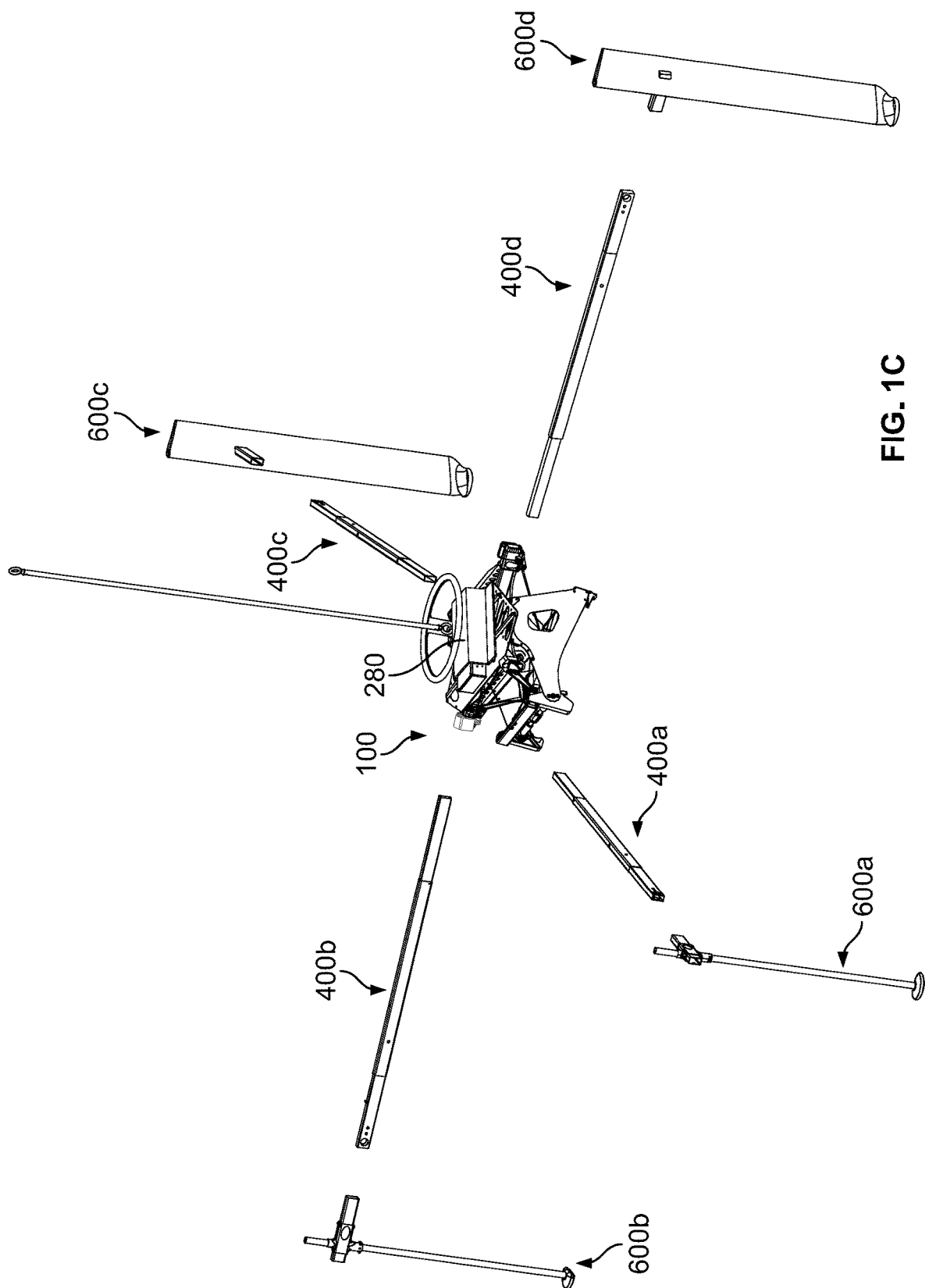


FIG. 1B



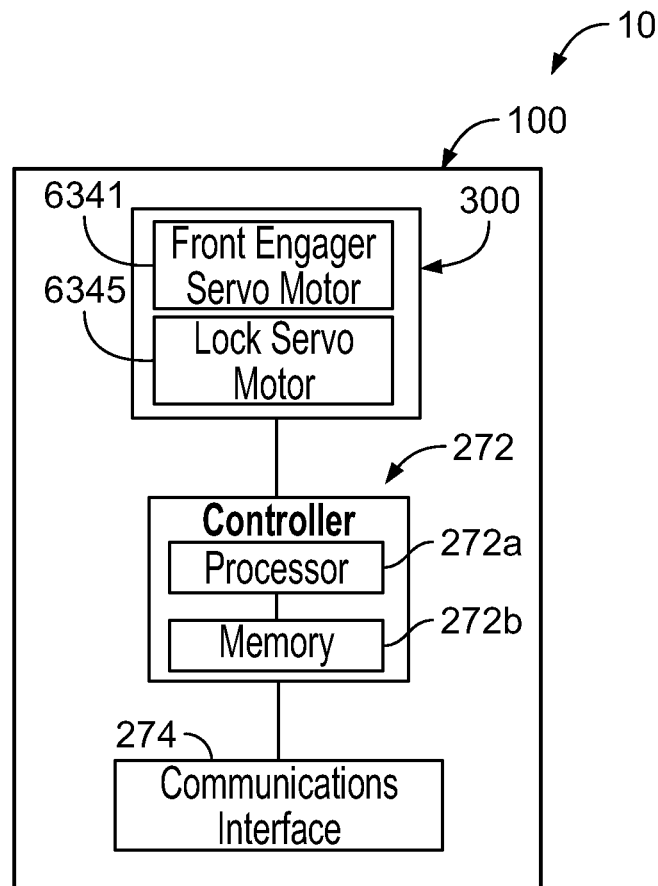


FIG. 1D

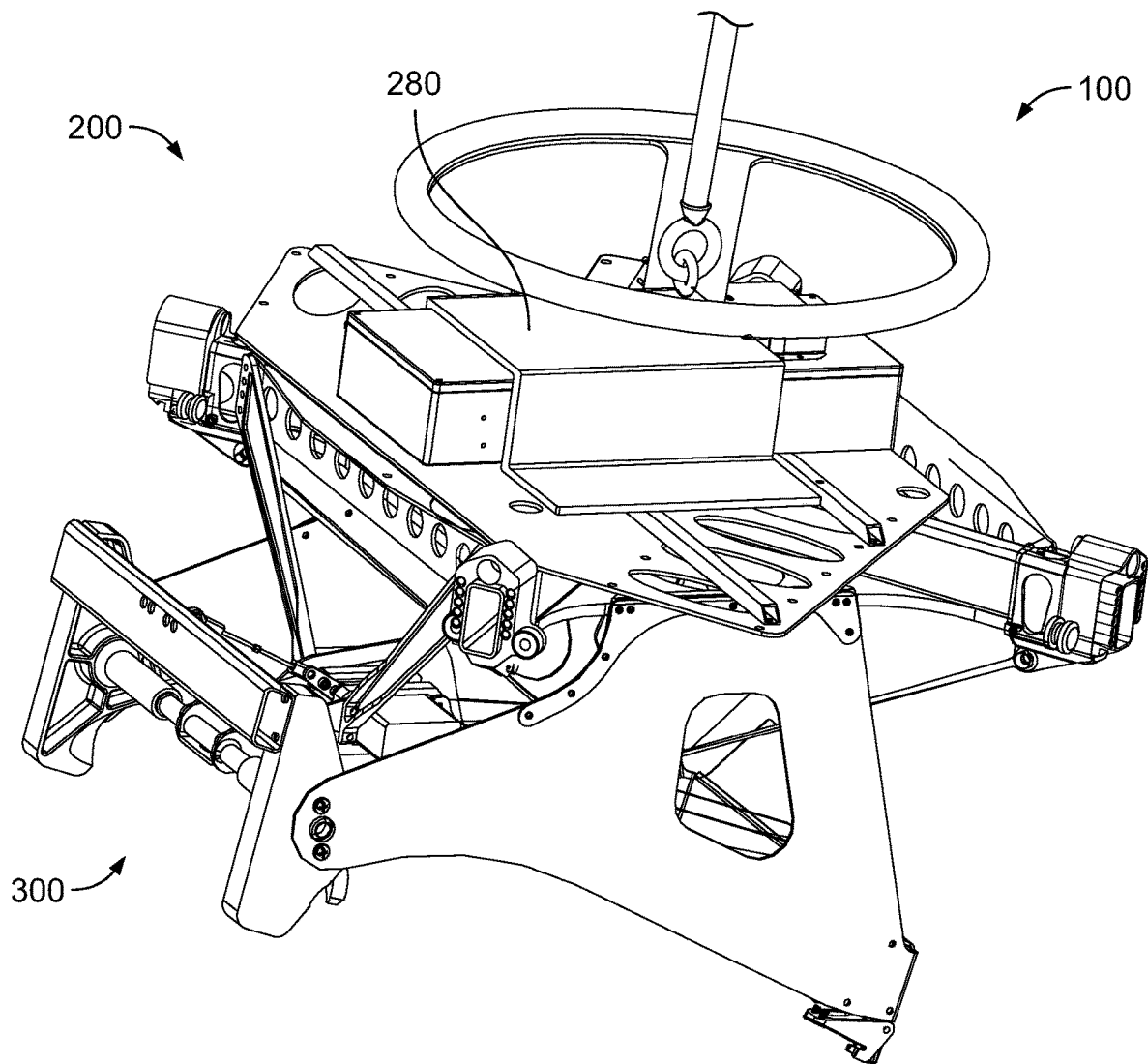


FIG. 2

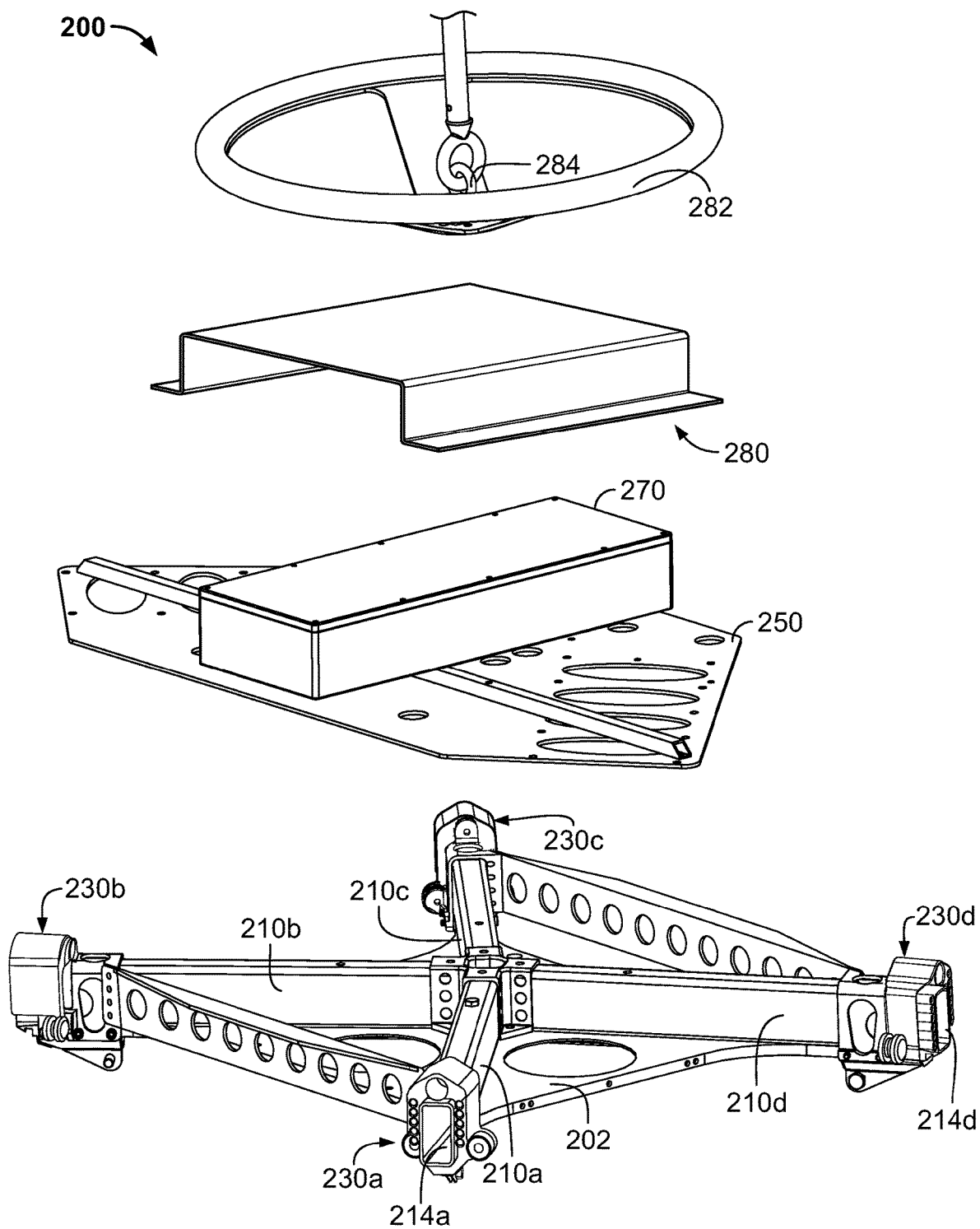


FIG. 3A

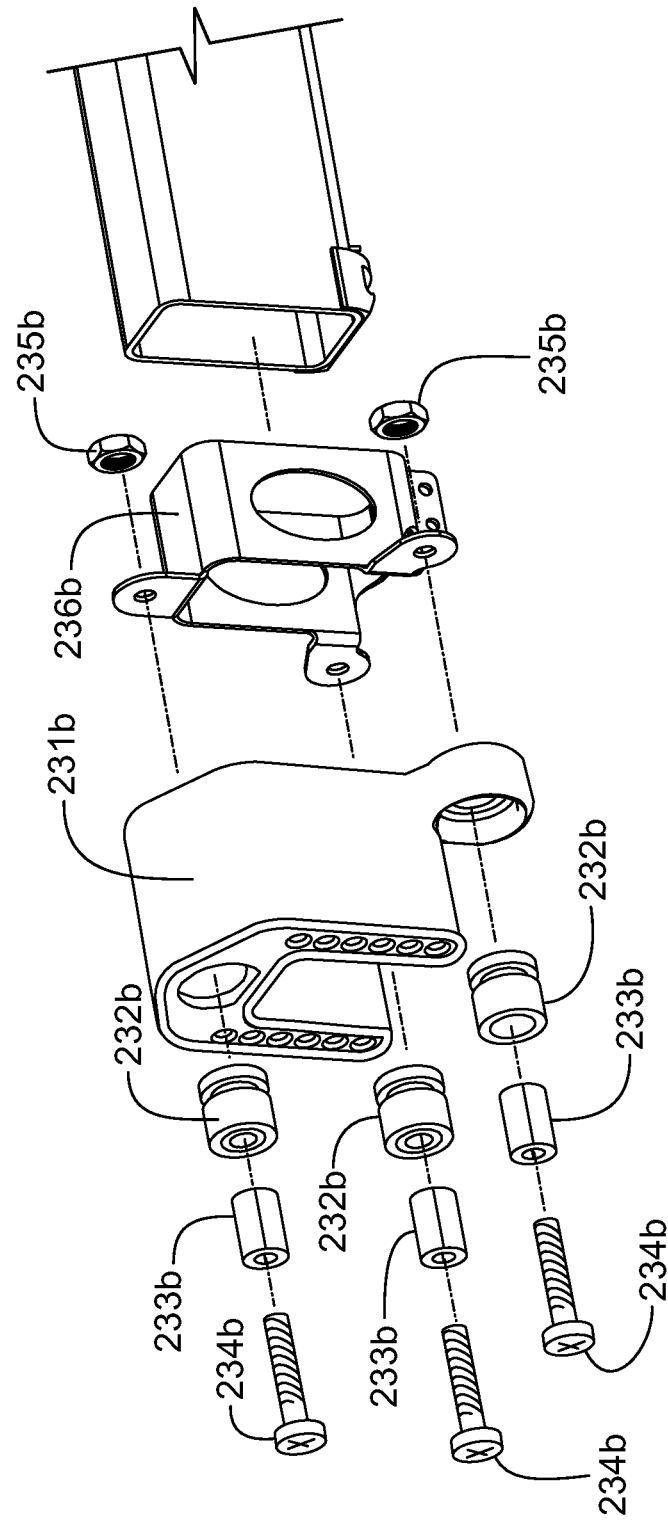


FIG. 3B

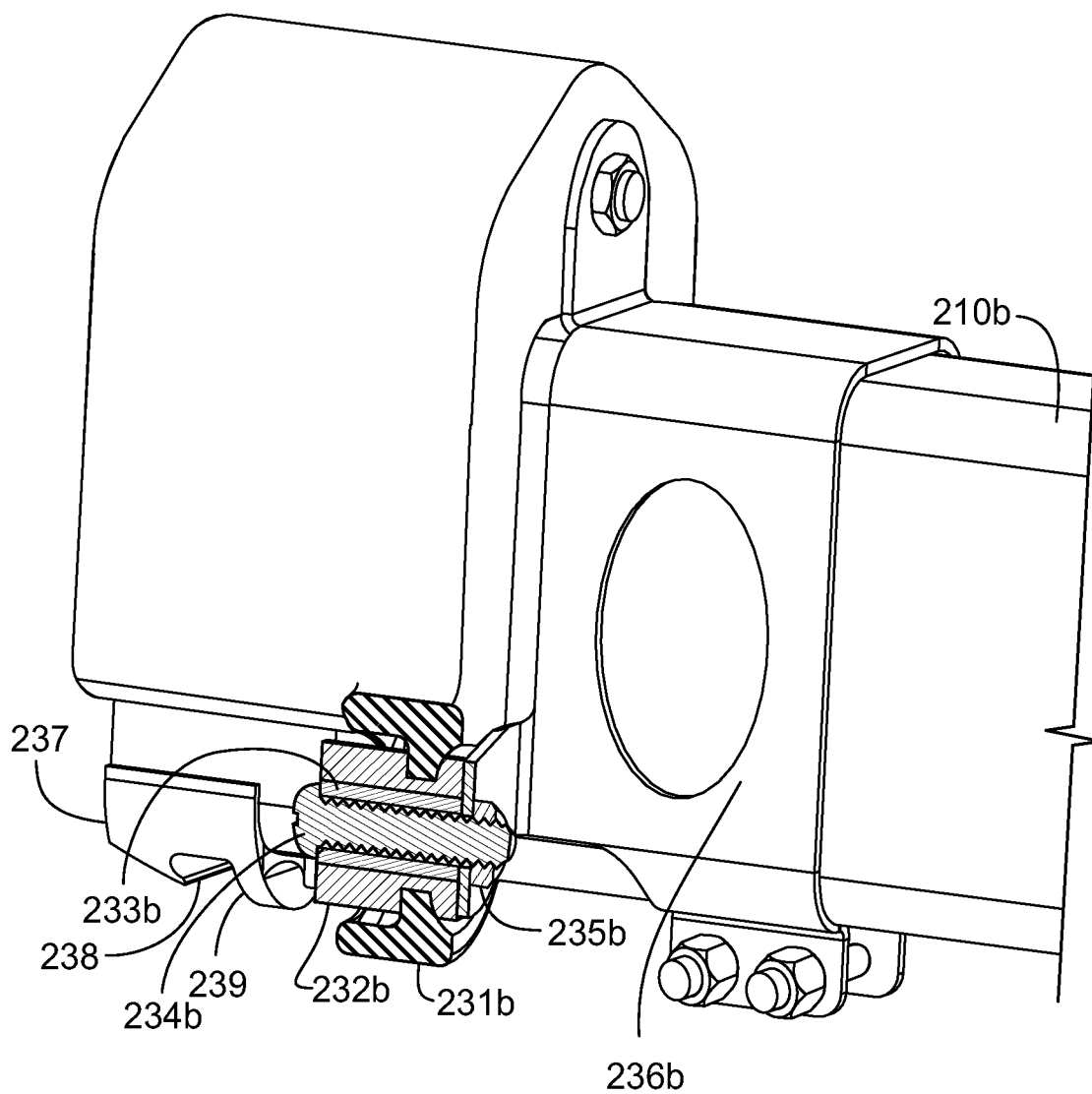


FIG. 3C

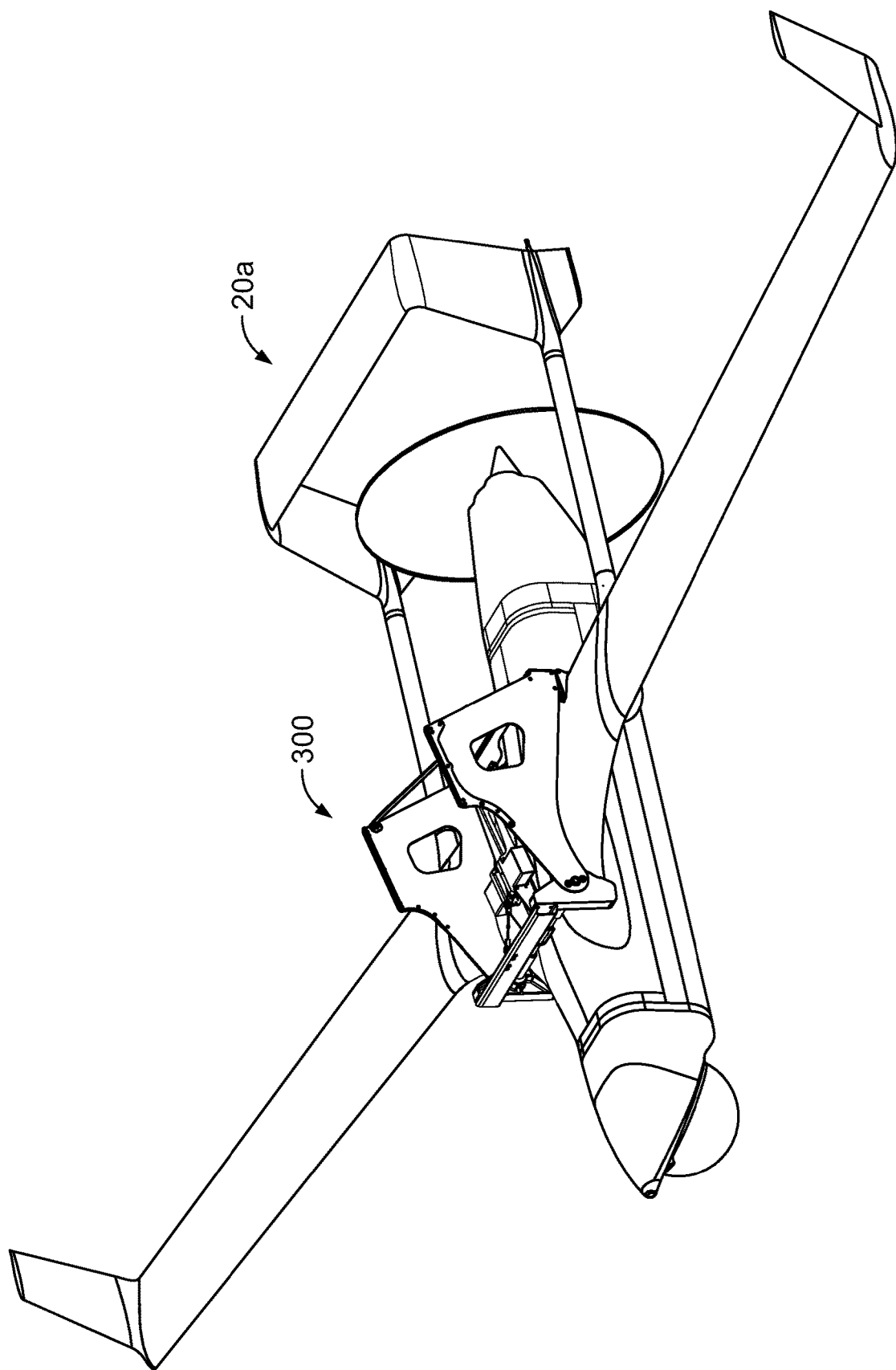
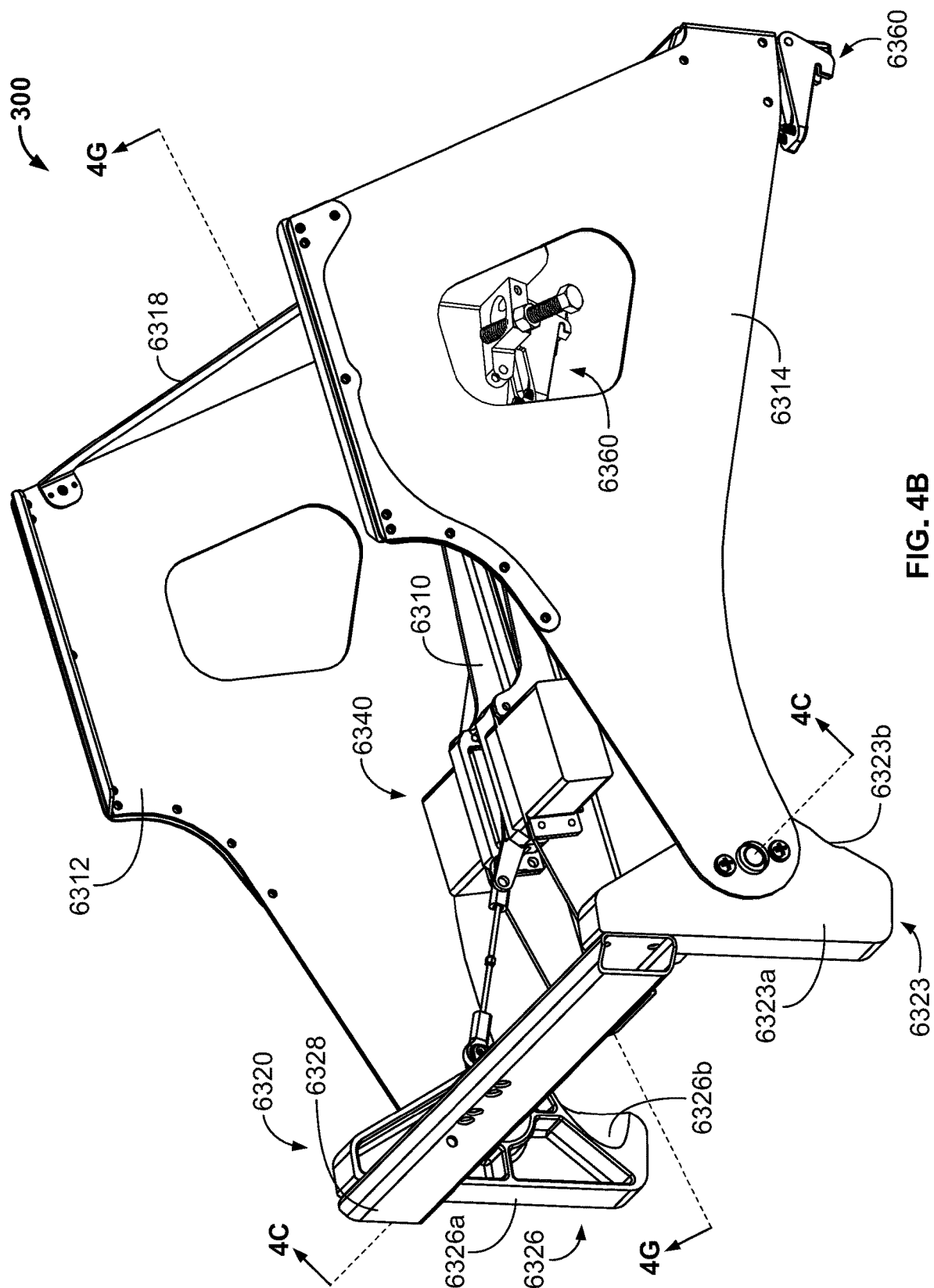


FIG. 4A



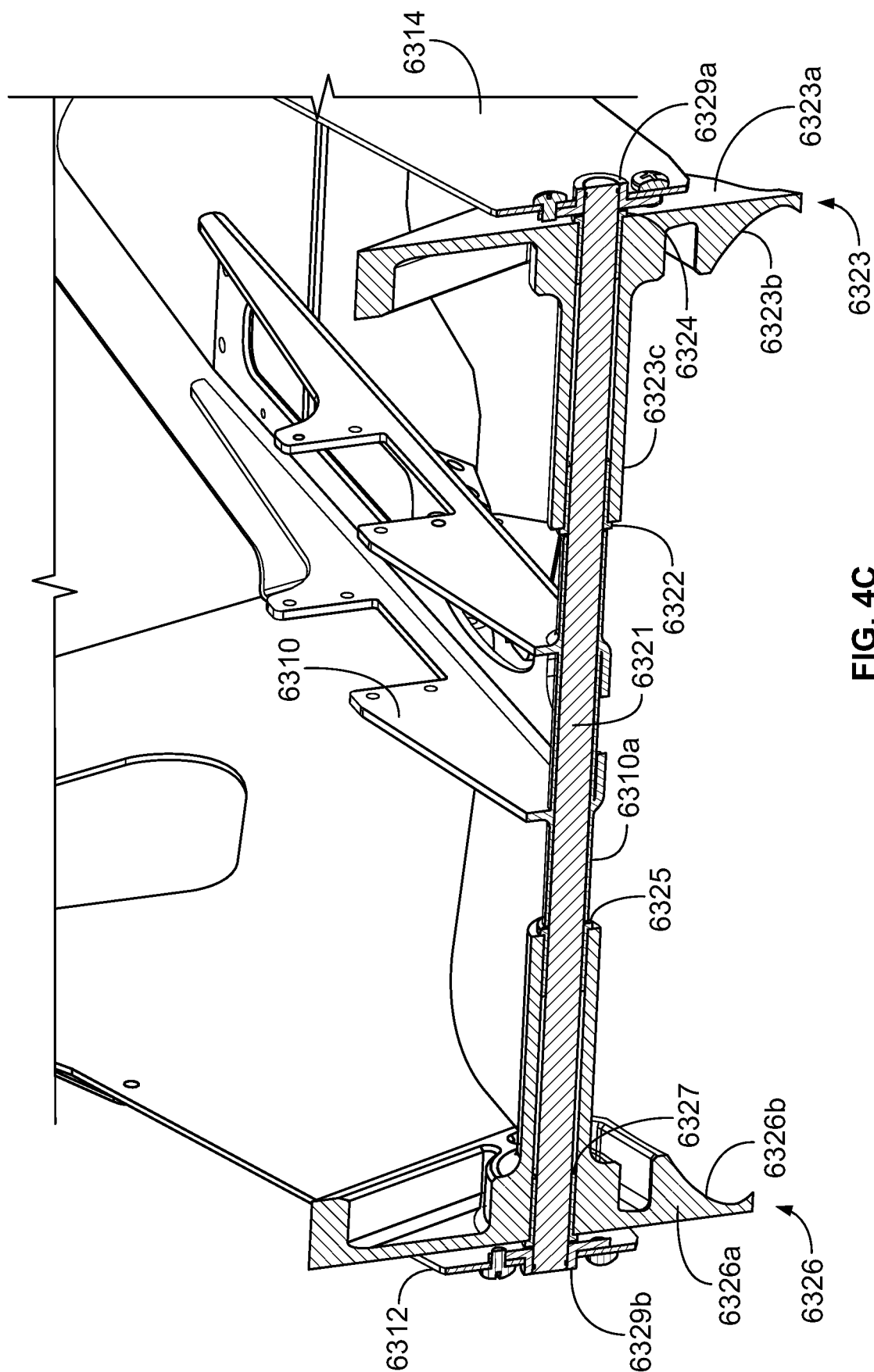


FIG. 4C

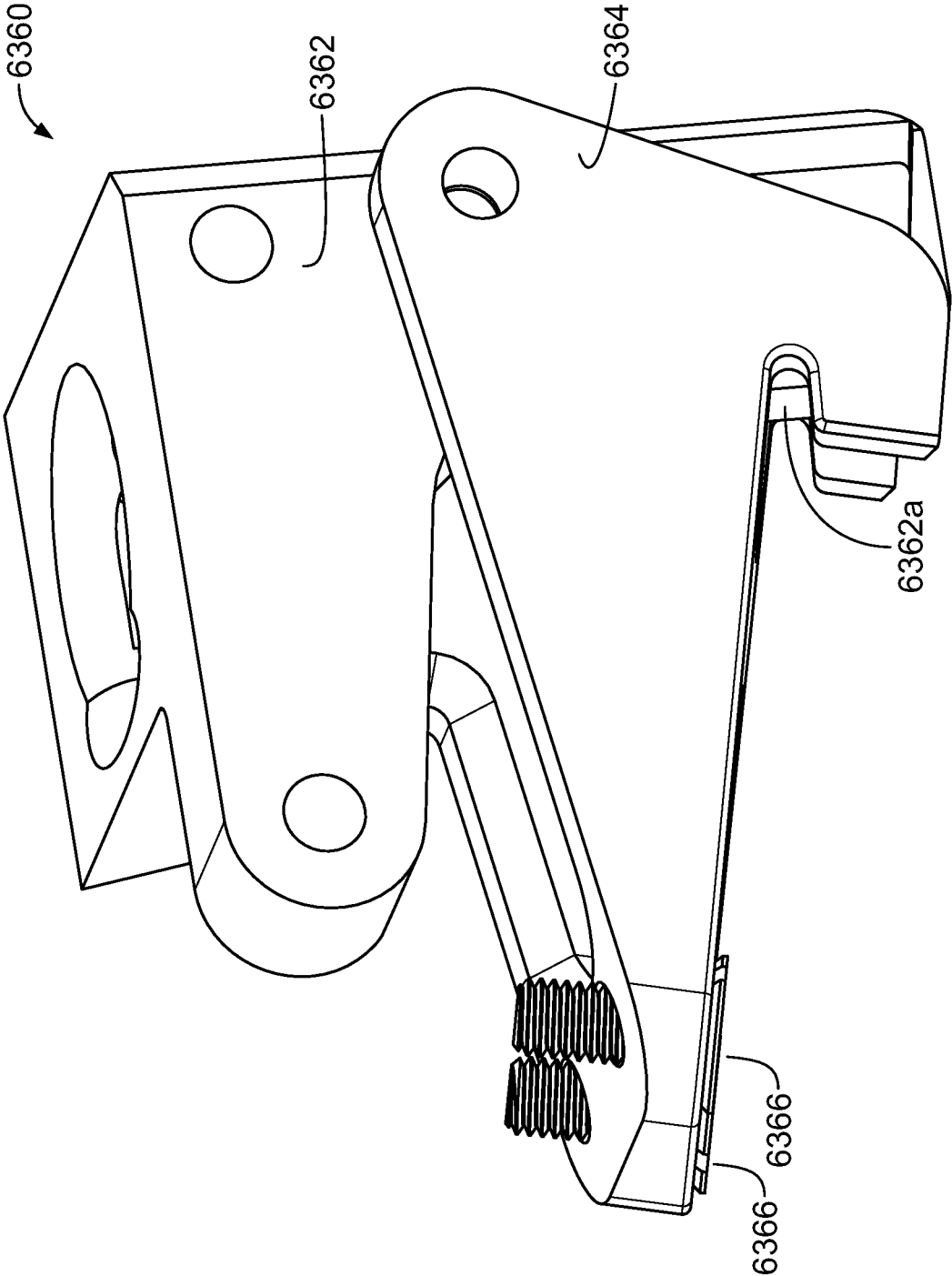


FIG. 4D

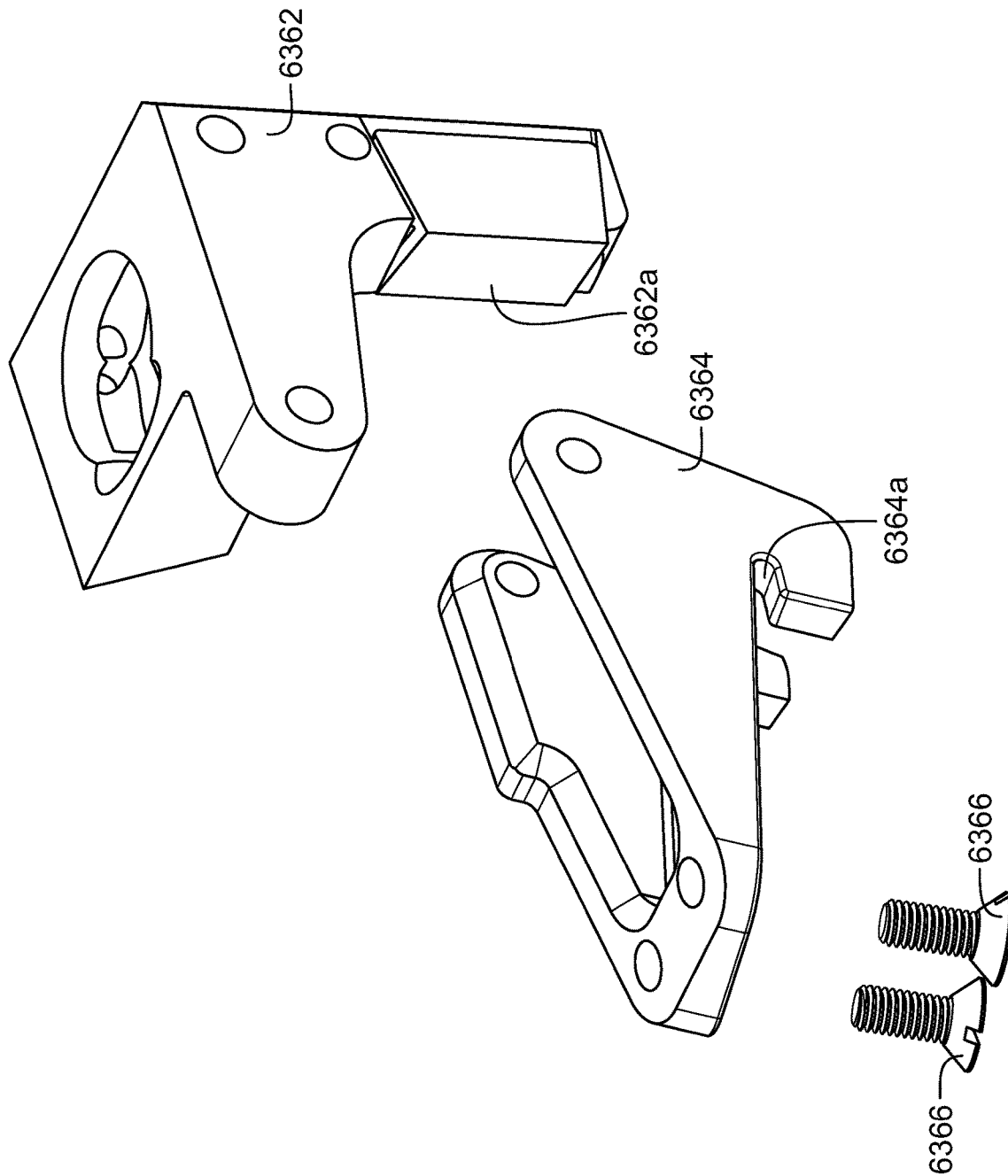


FIG. 4E

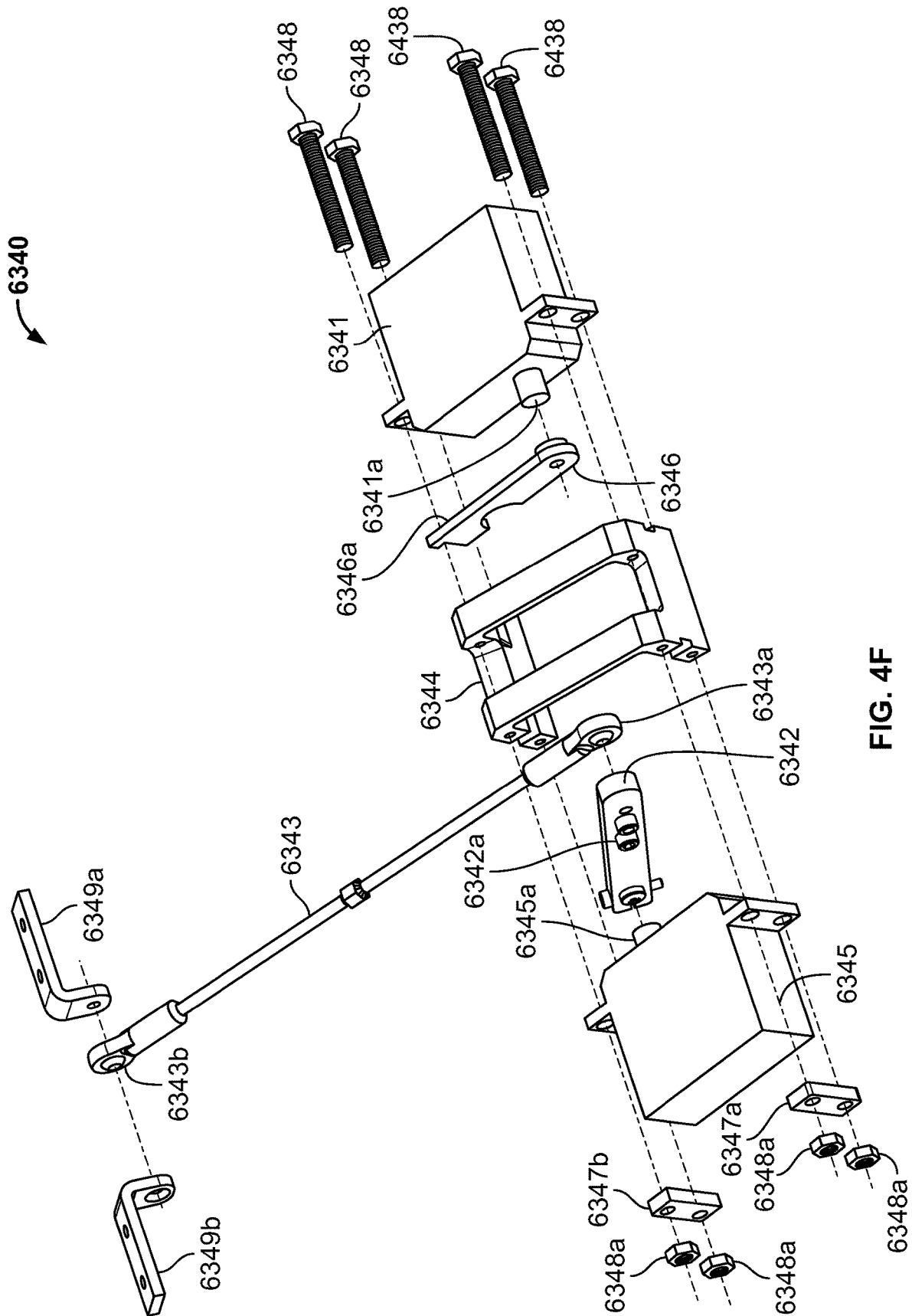


FIG. 4F

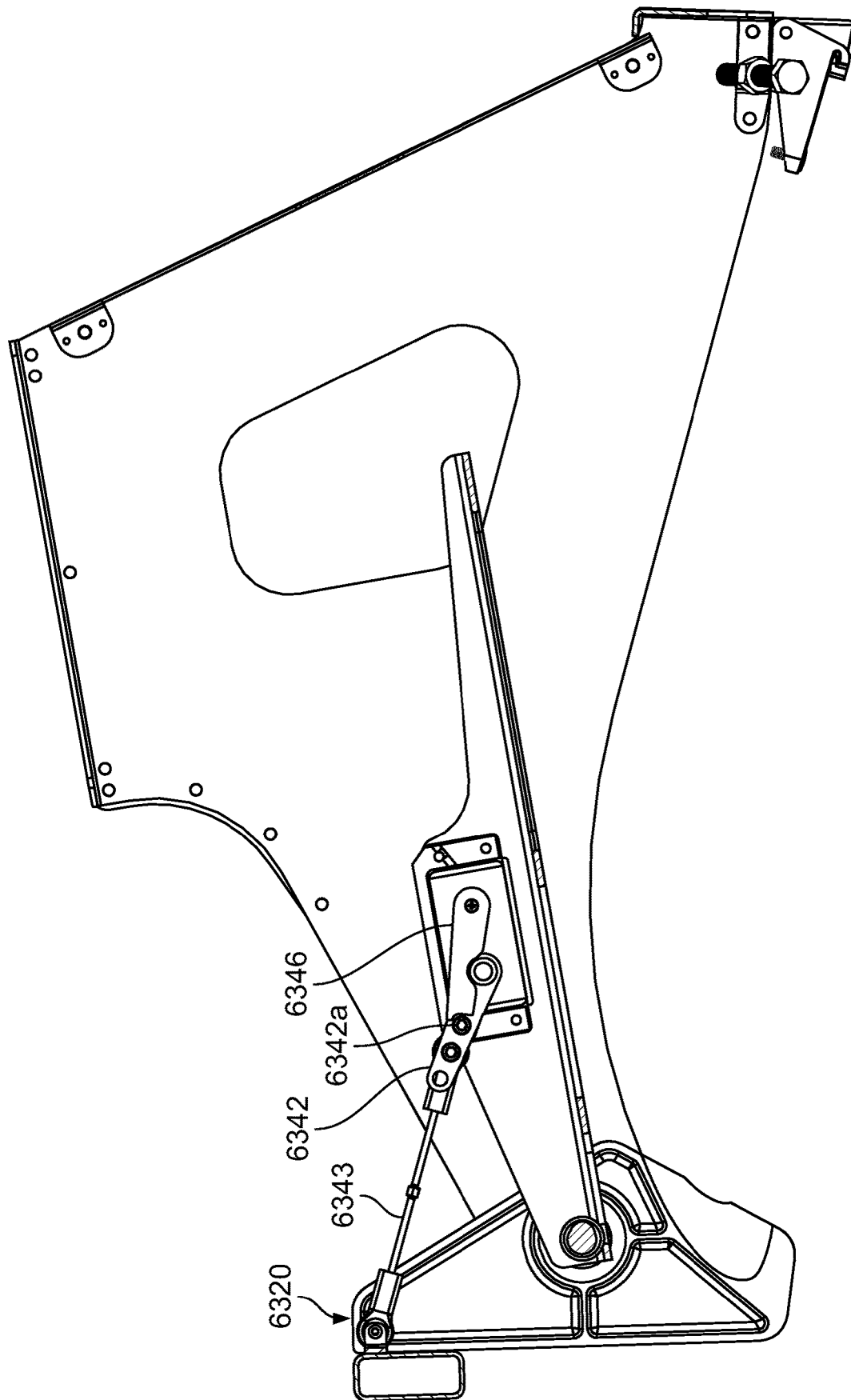


FIG. 4G

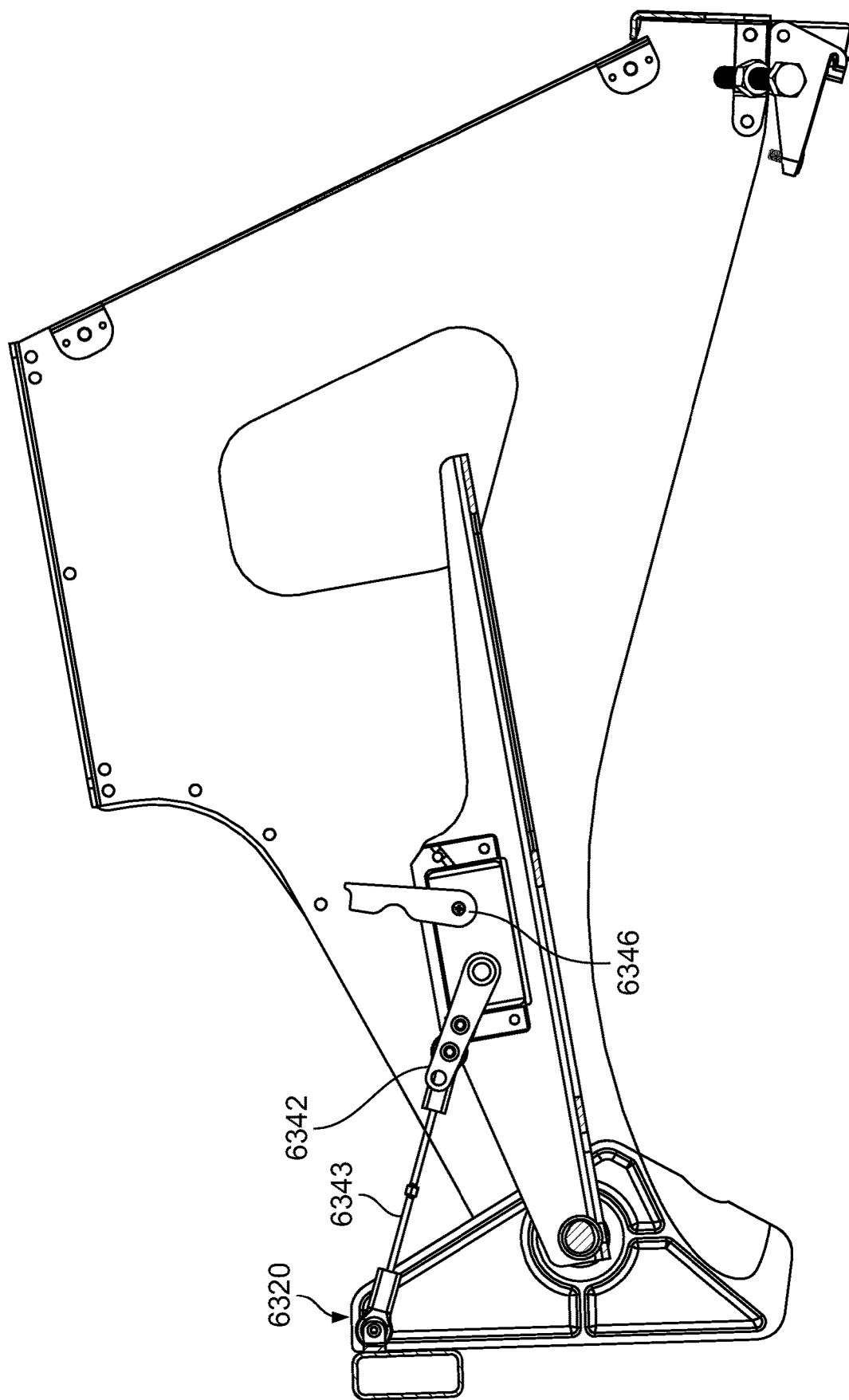


FIG. 4H

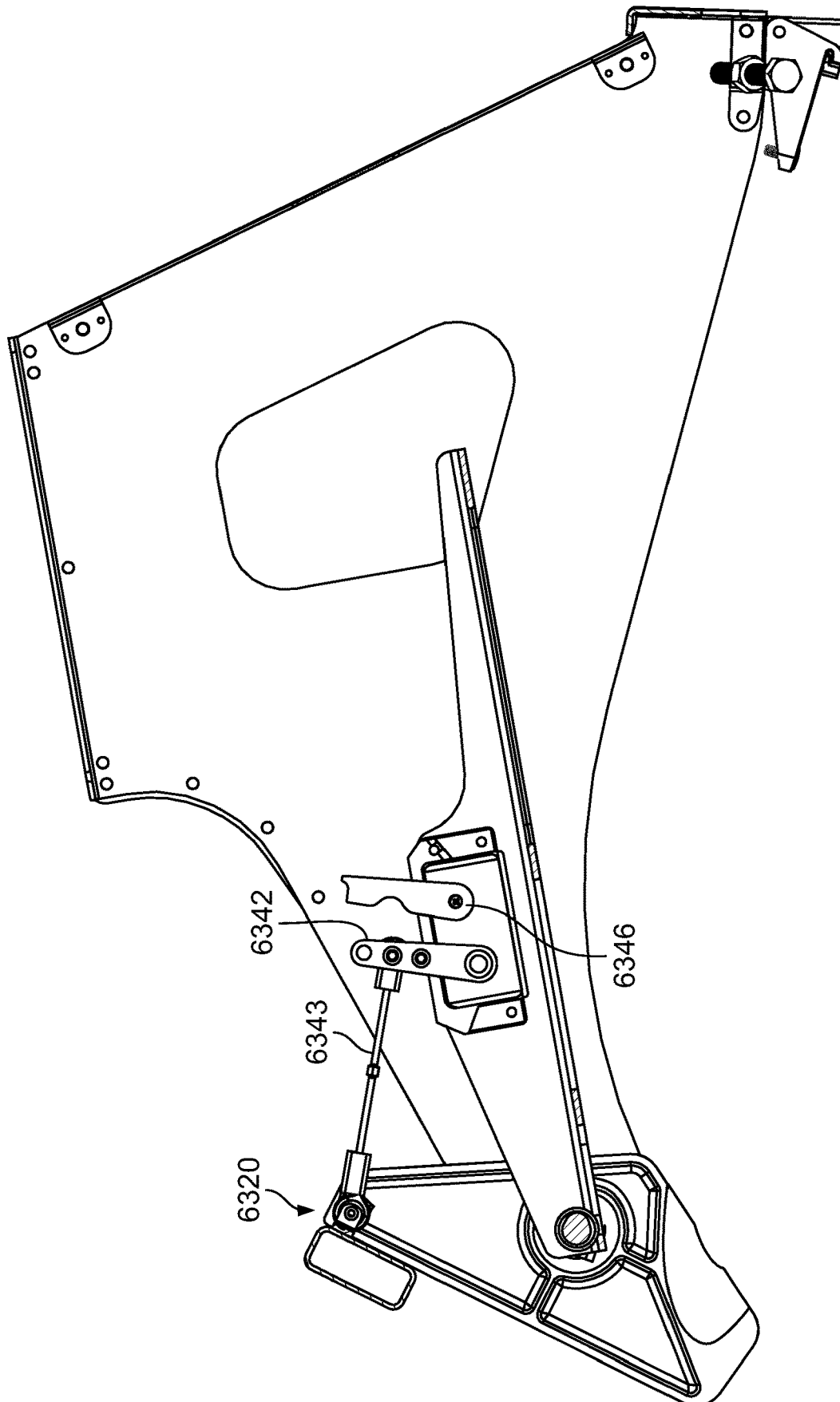
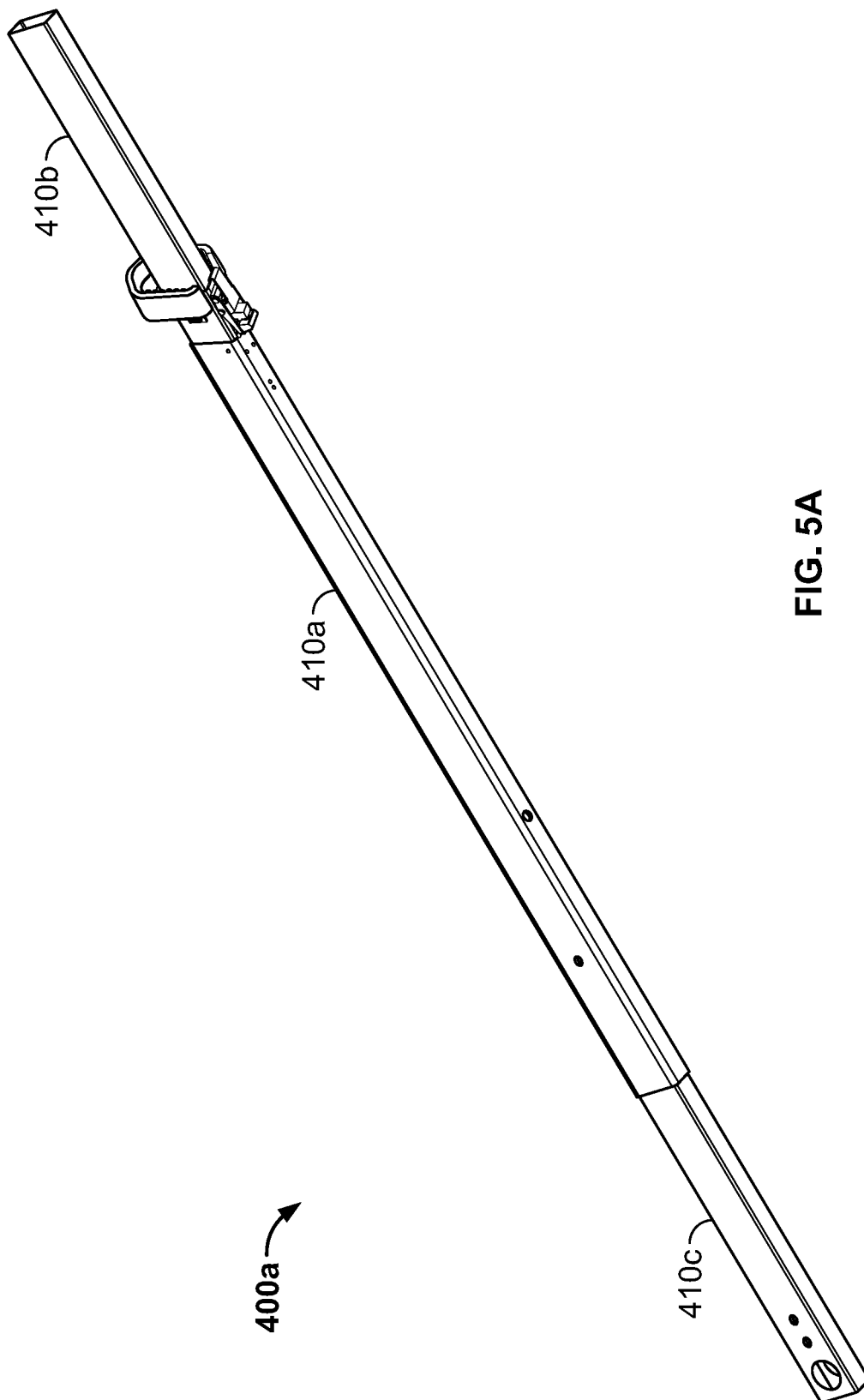


FIG. 4I



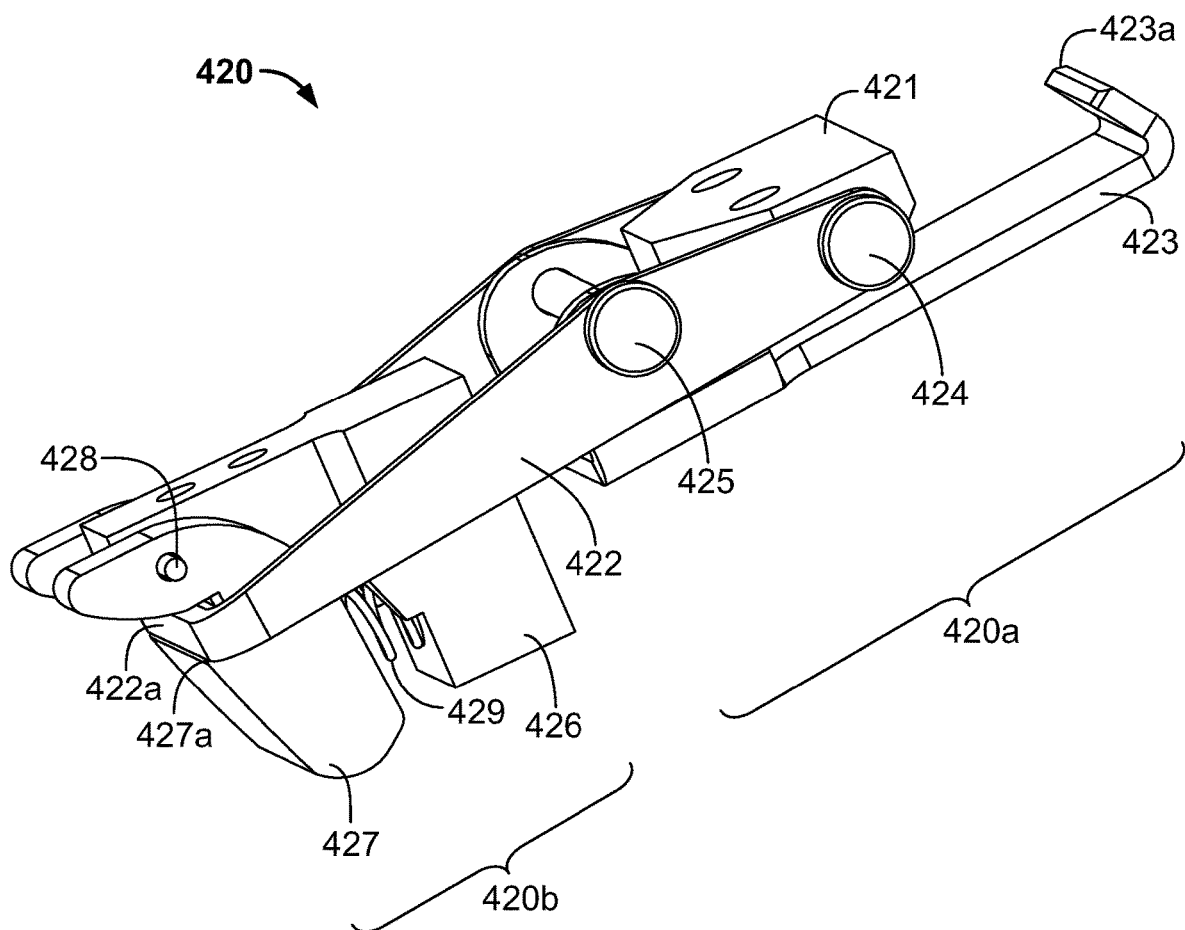


FIG. 5B

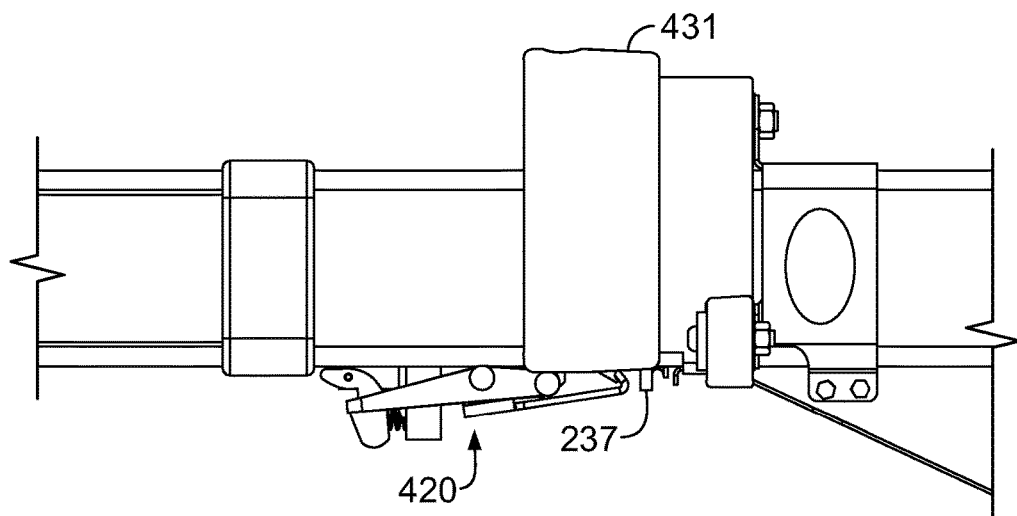


FIG. 5C

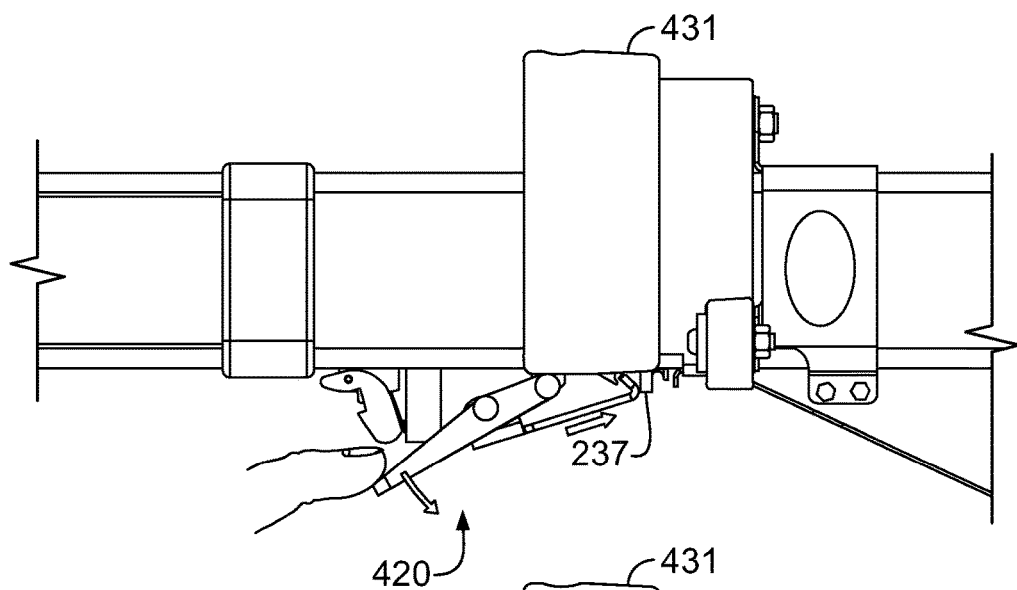


FIG. 5D

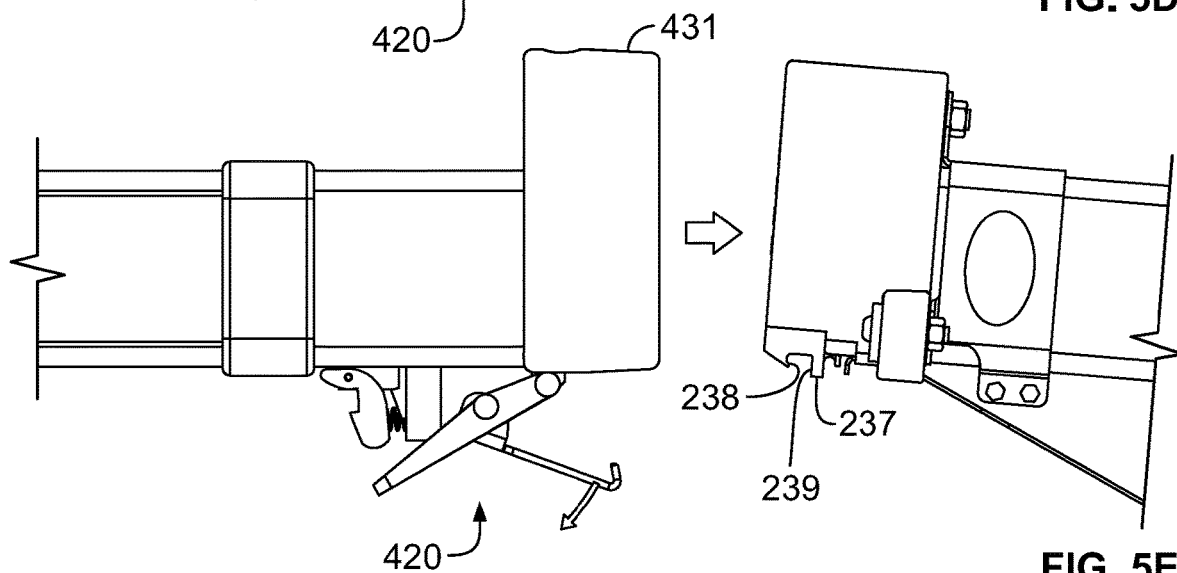


FIG. 5E

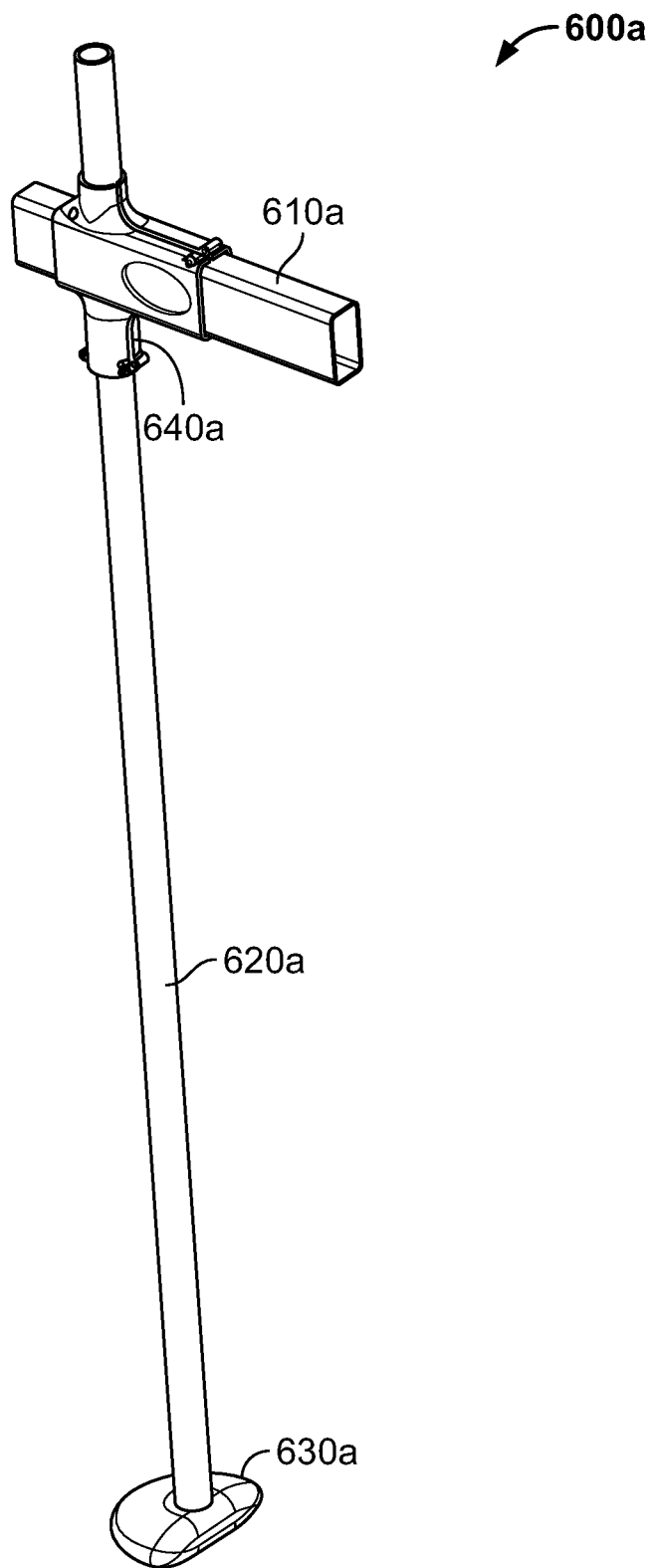


Fig. 6

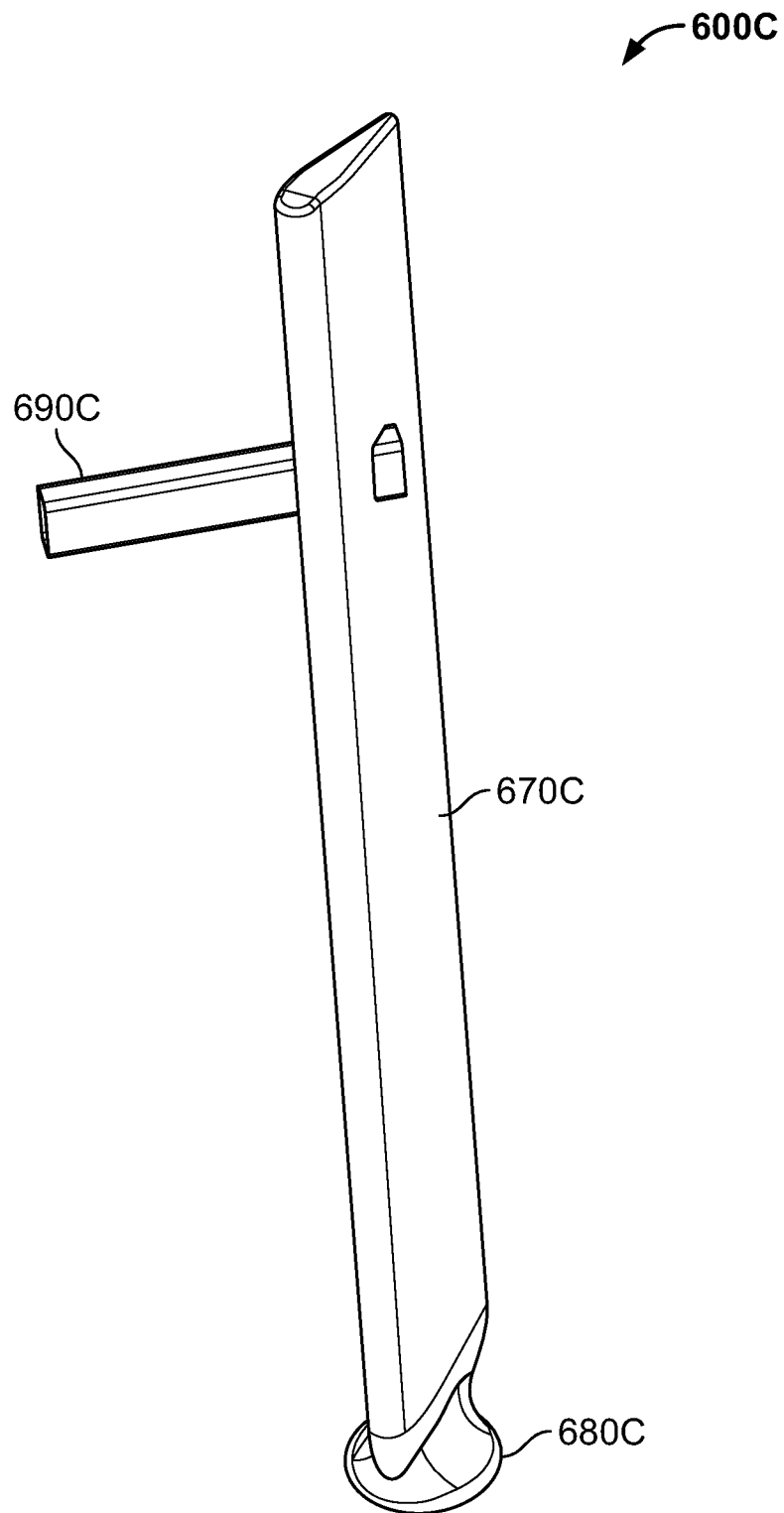
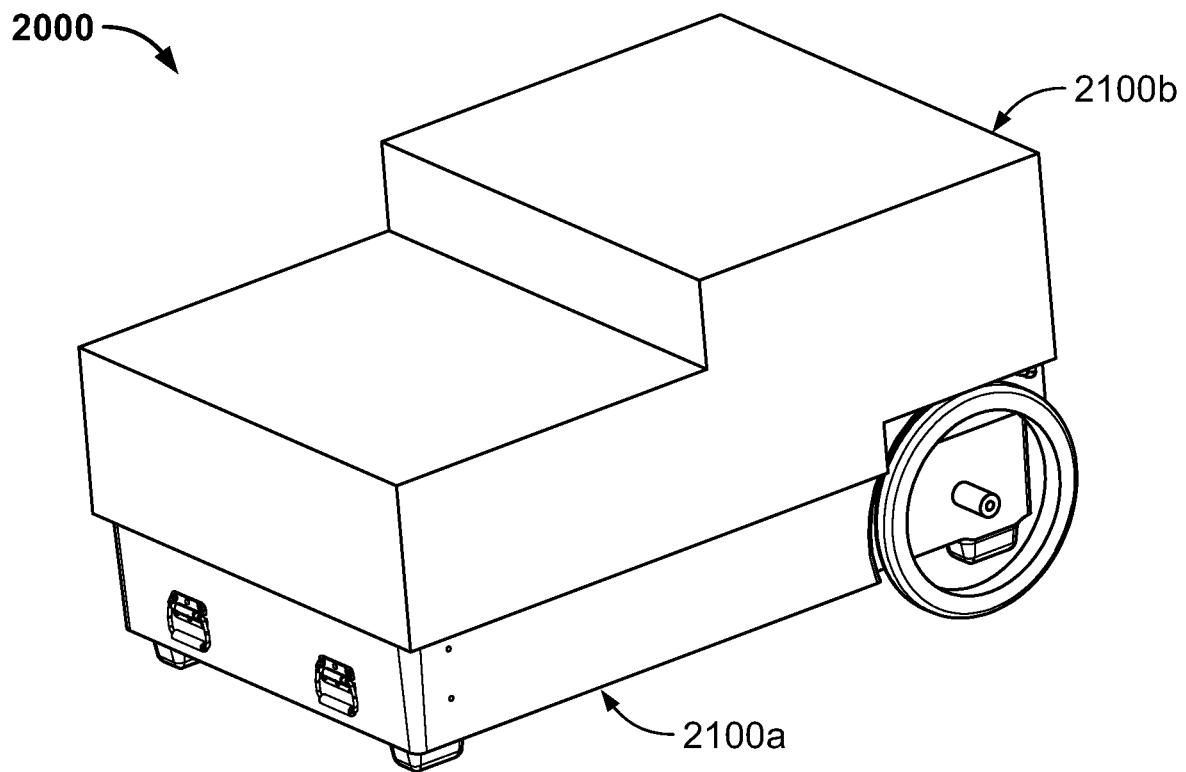


Fig. 7

**FIG. 8A**

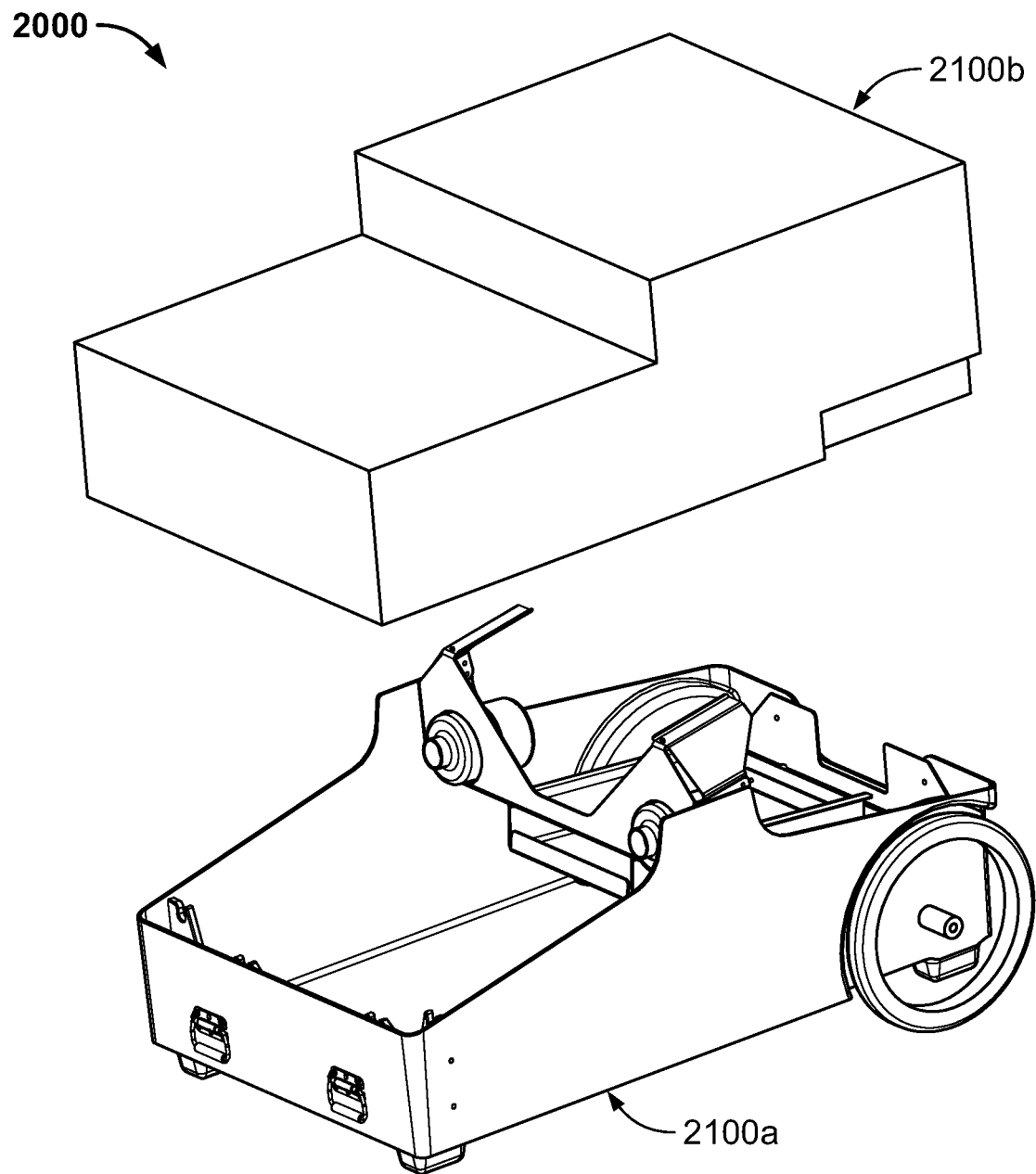


FIG. 8B

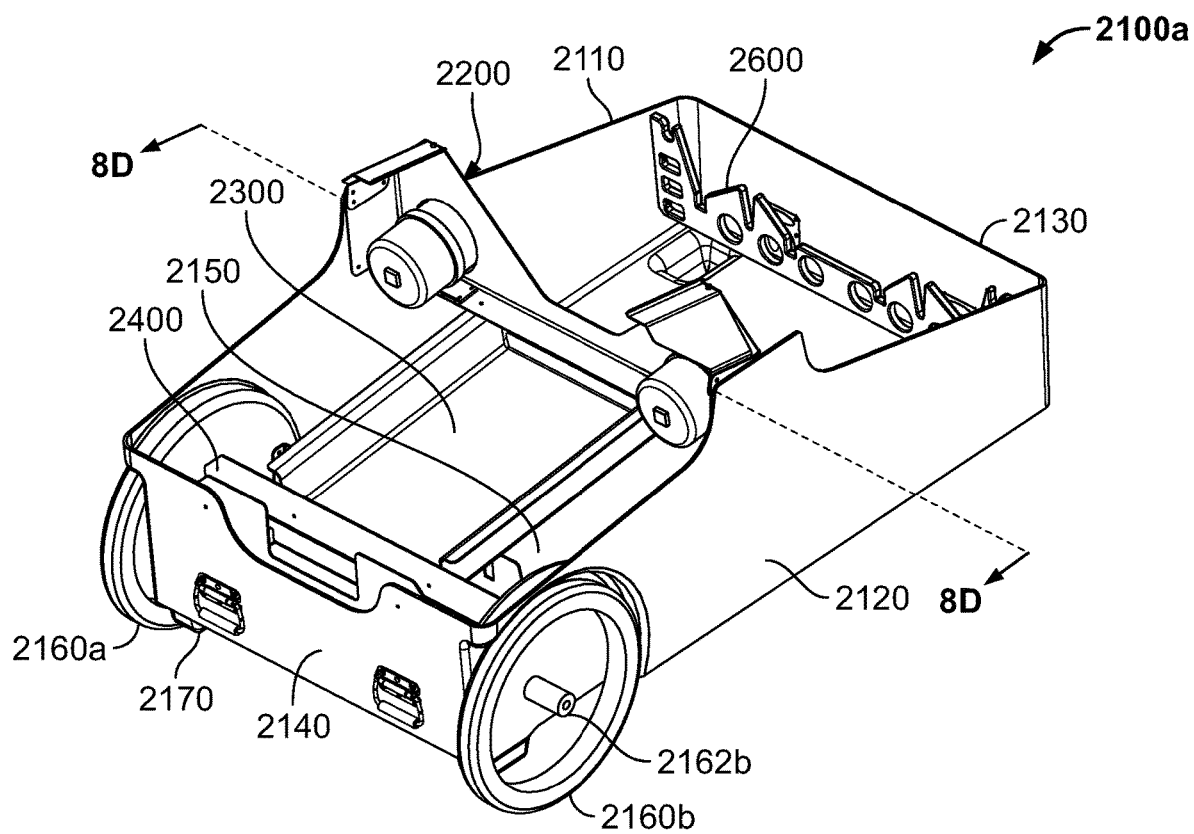


FIG. 8C

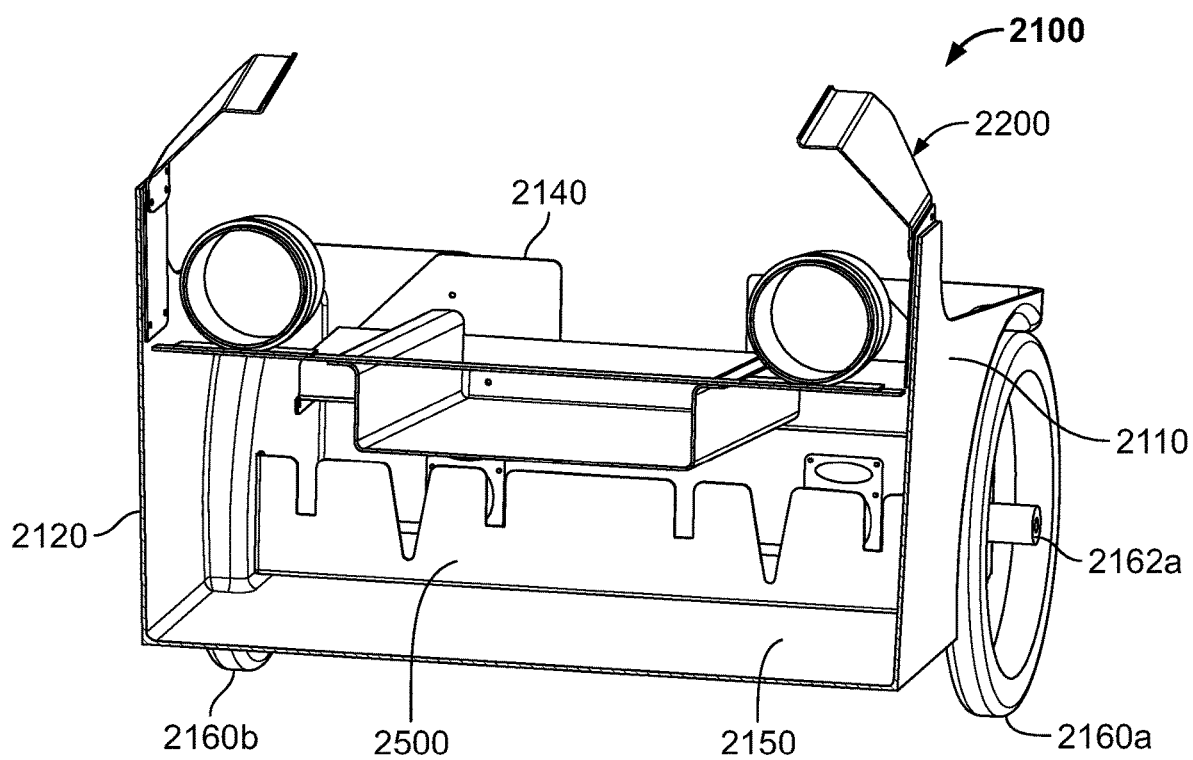


FIG. 8D

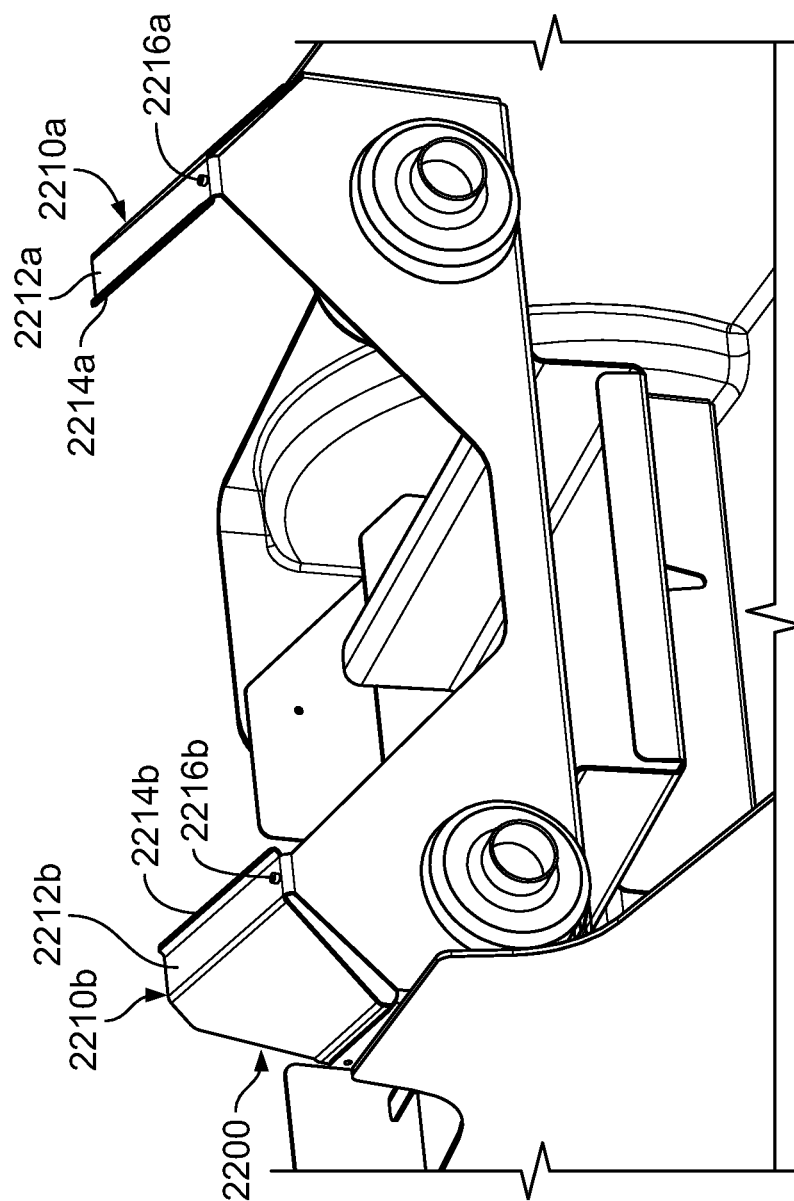


FIG. 8E

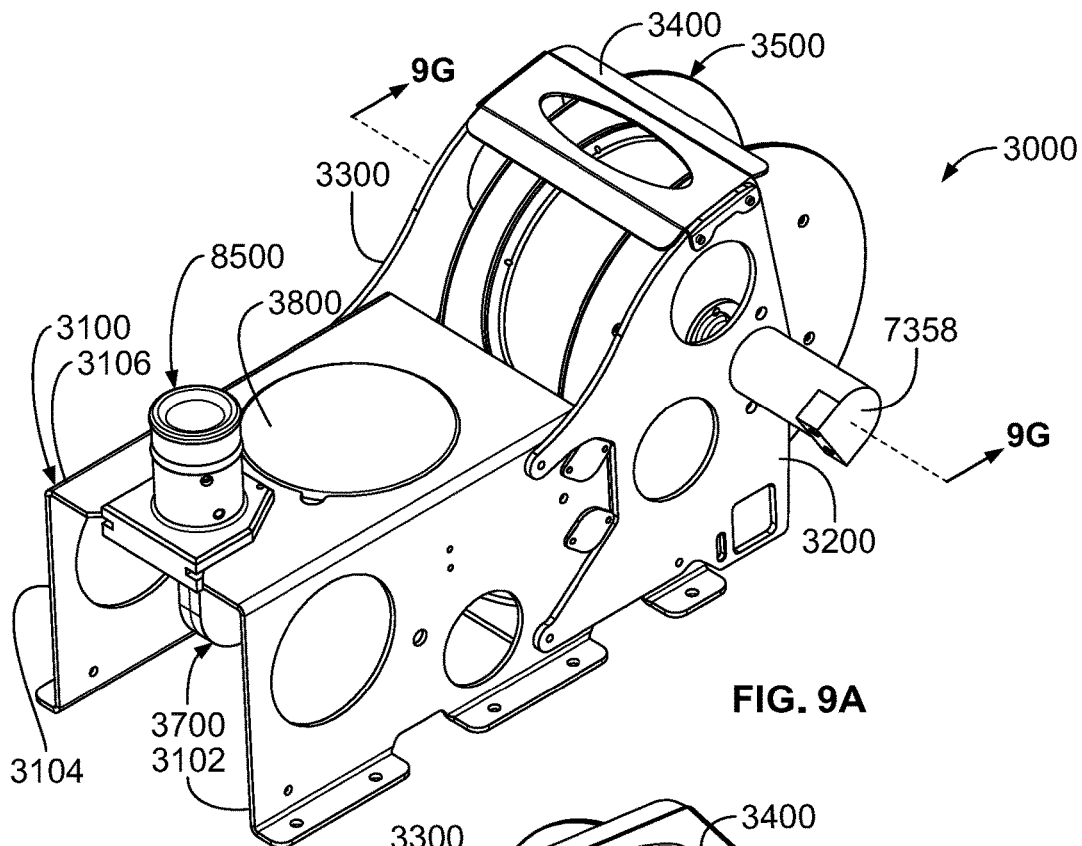


FIG. 9A

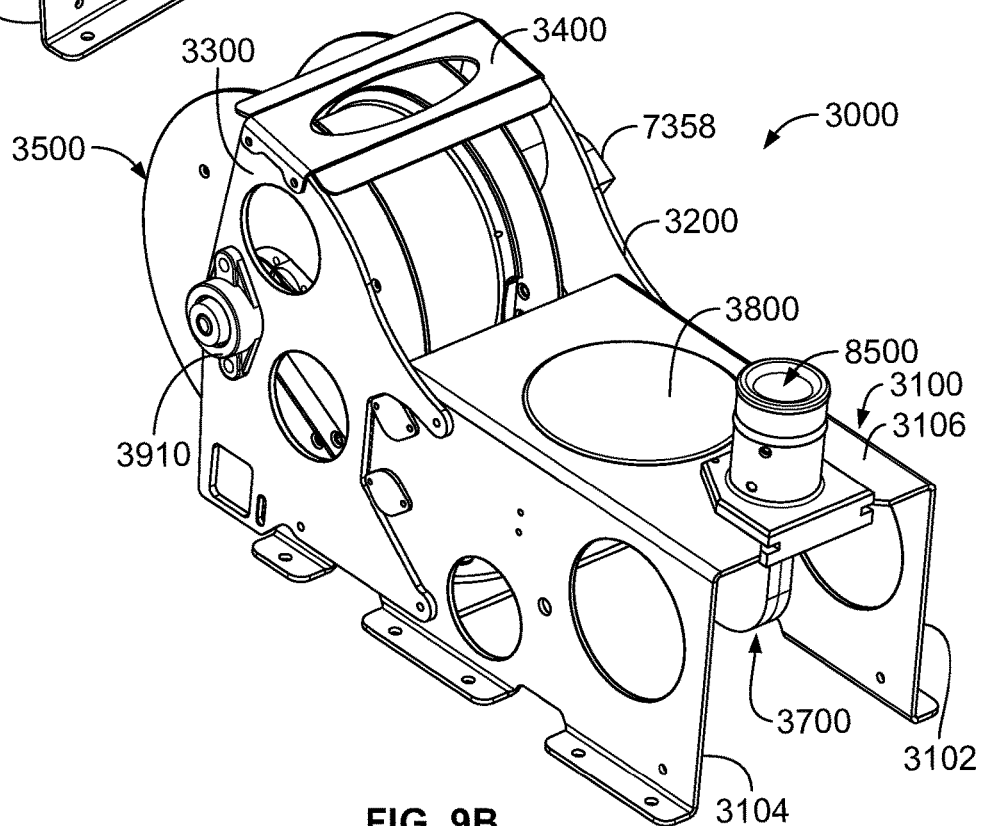


FIG. 9B

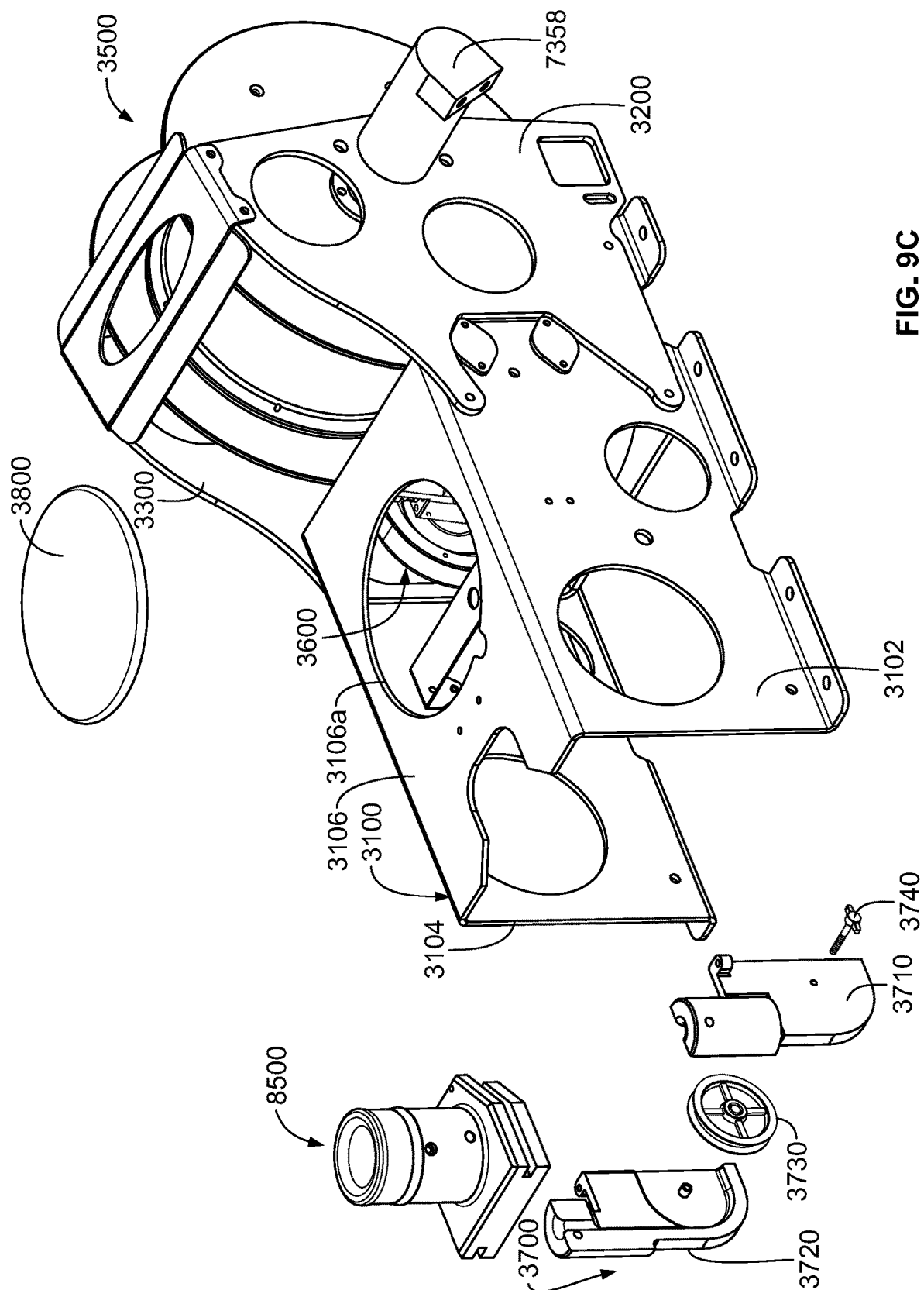
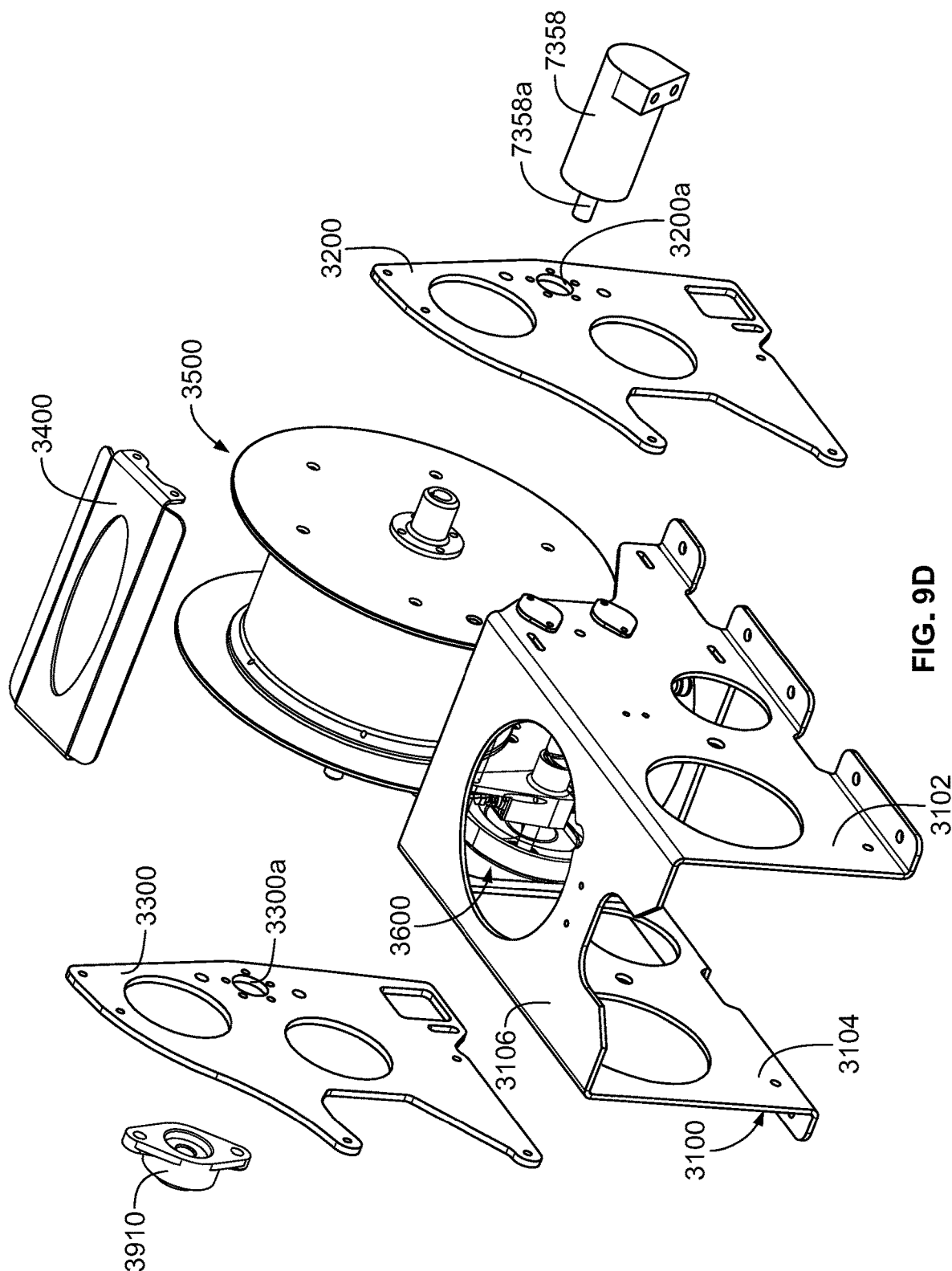


FIG. 9C



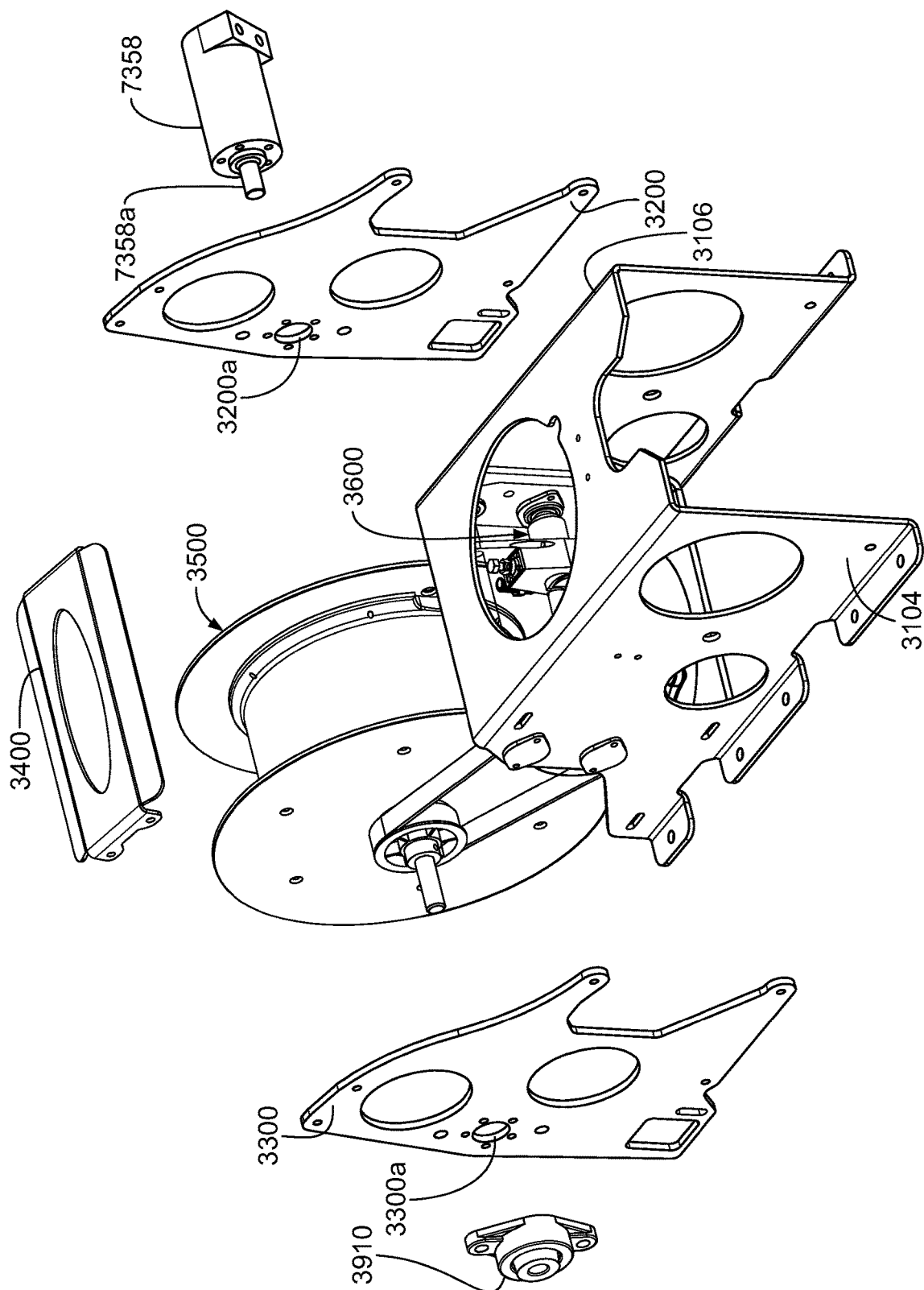


FIG. 9E

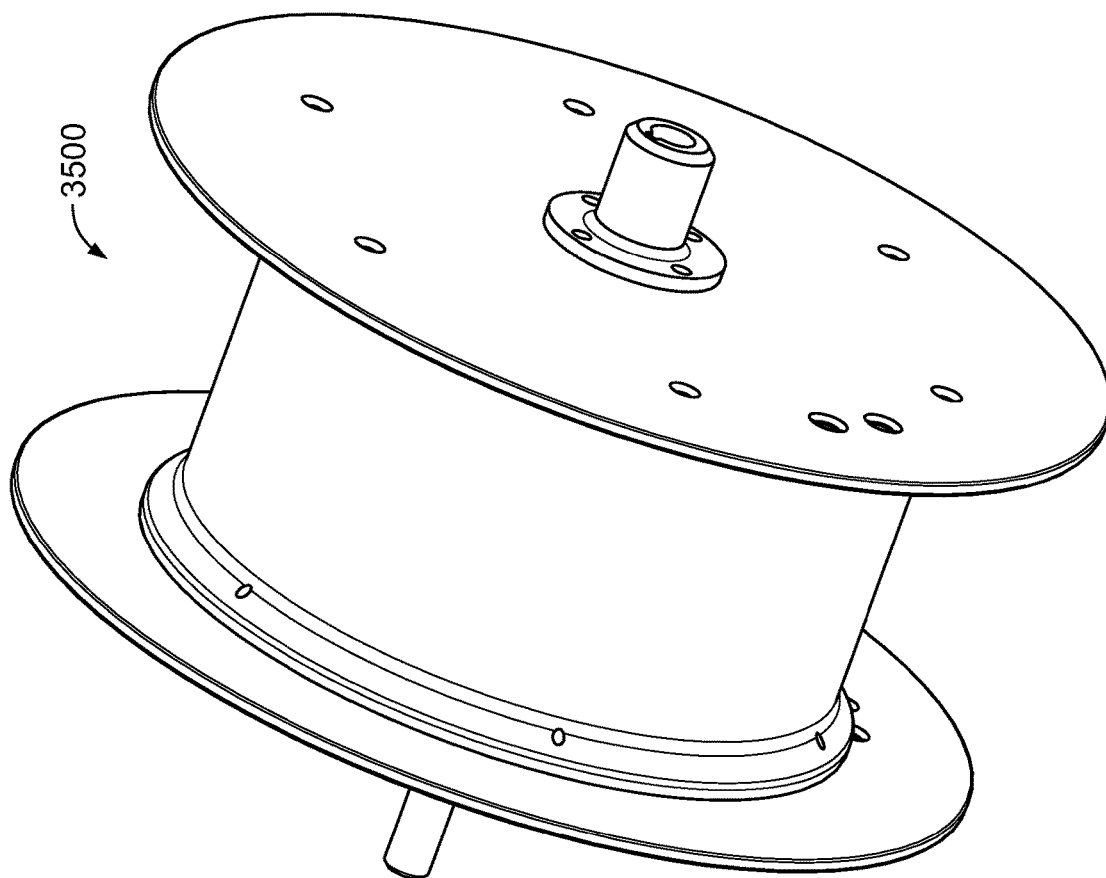
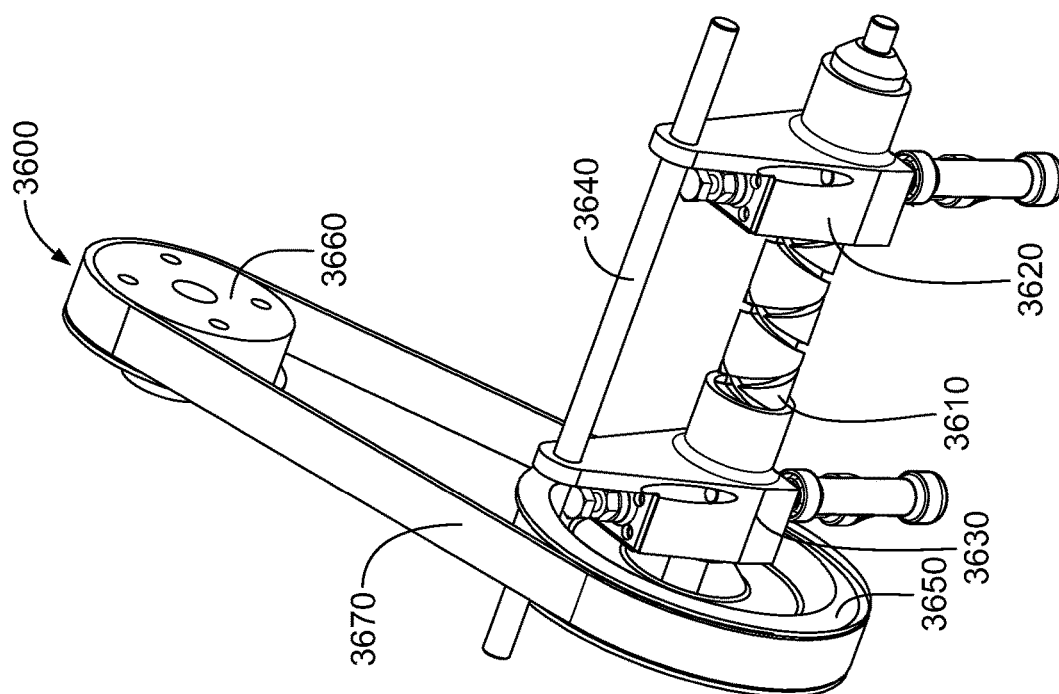


FIG. 9F



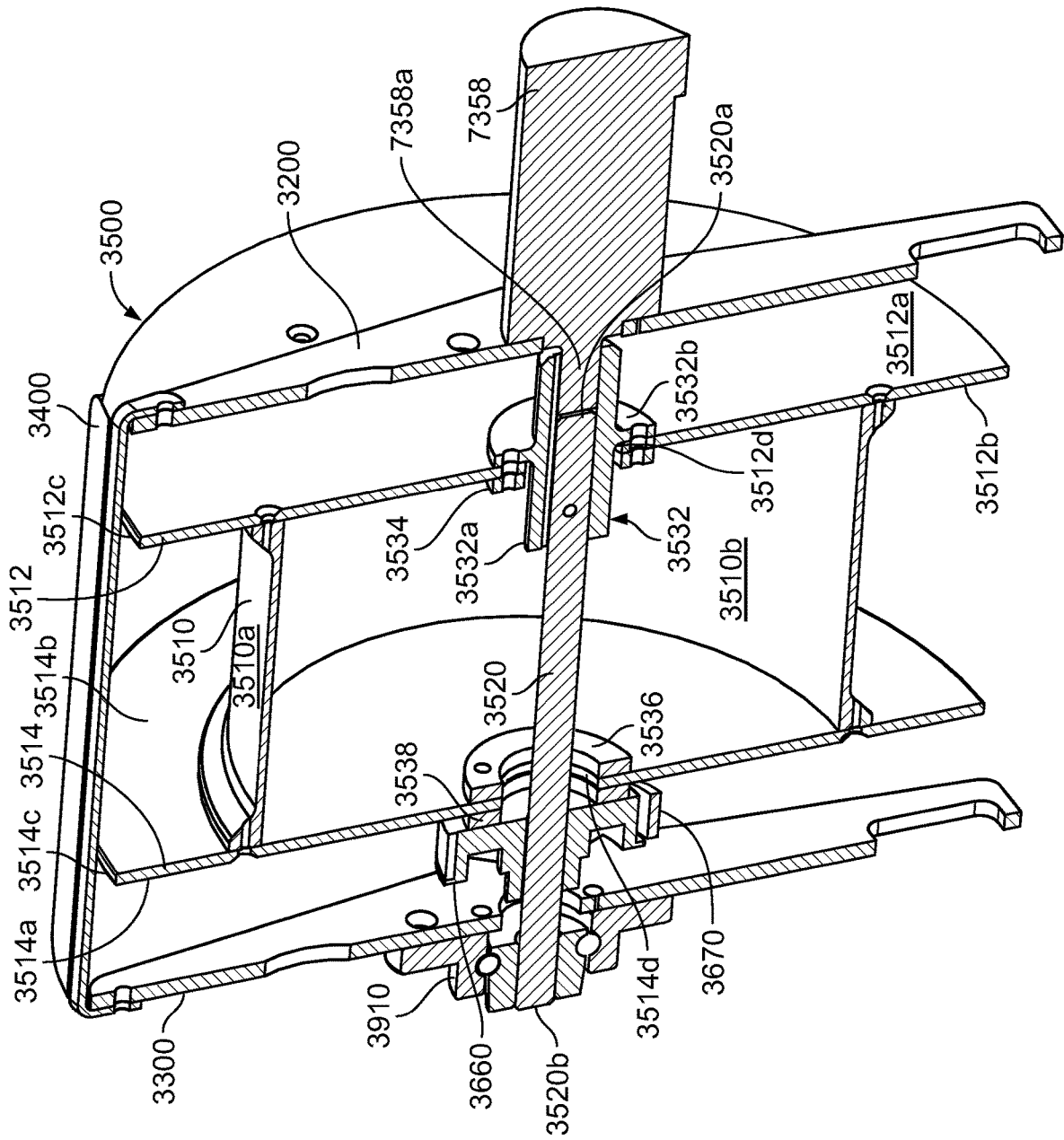


FIG. 9G

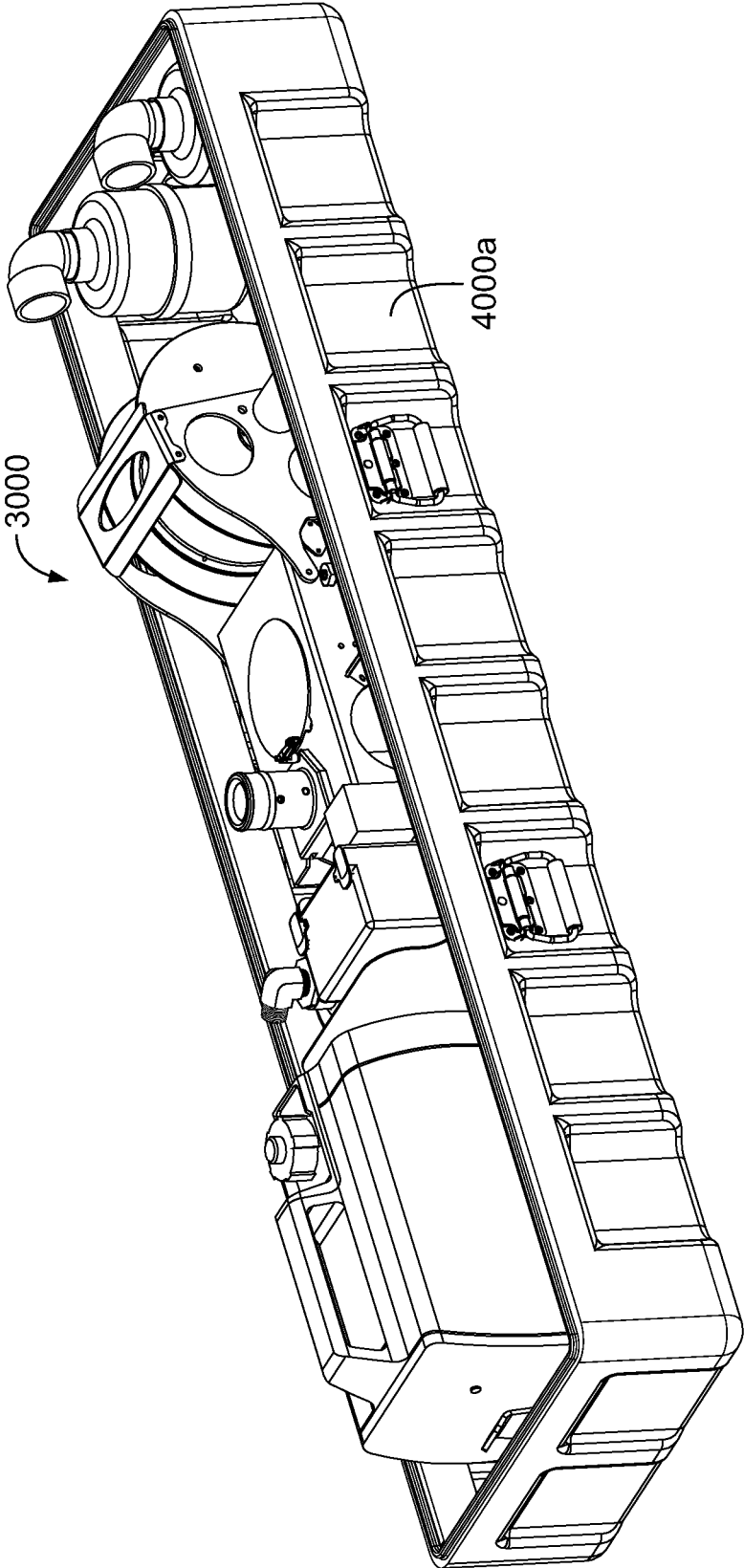


FIG. 9H

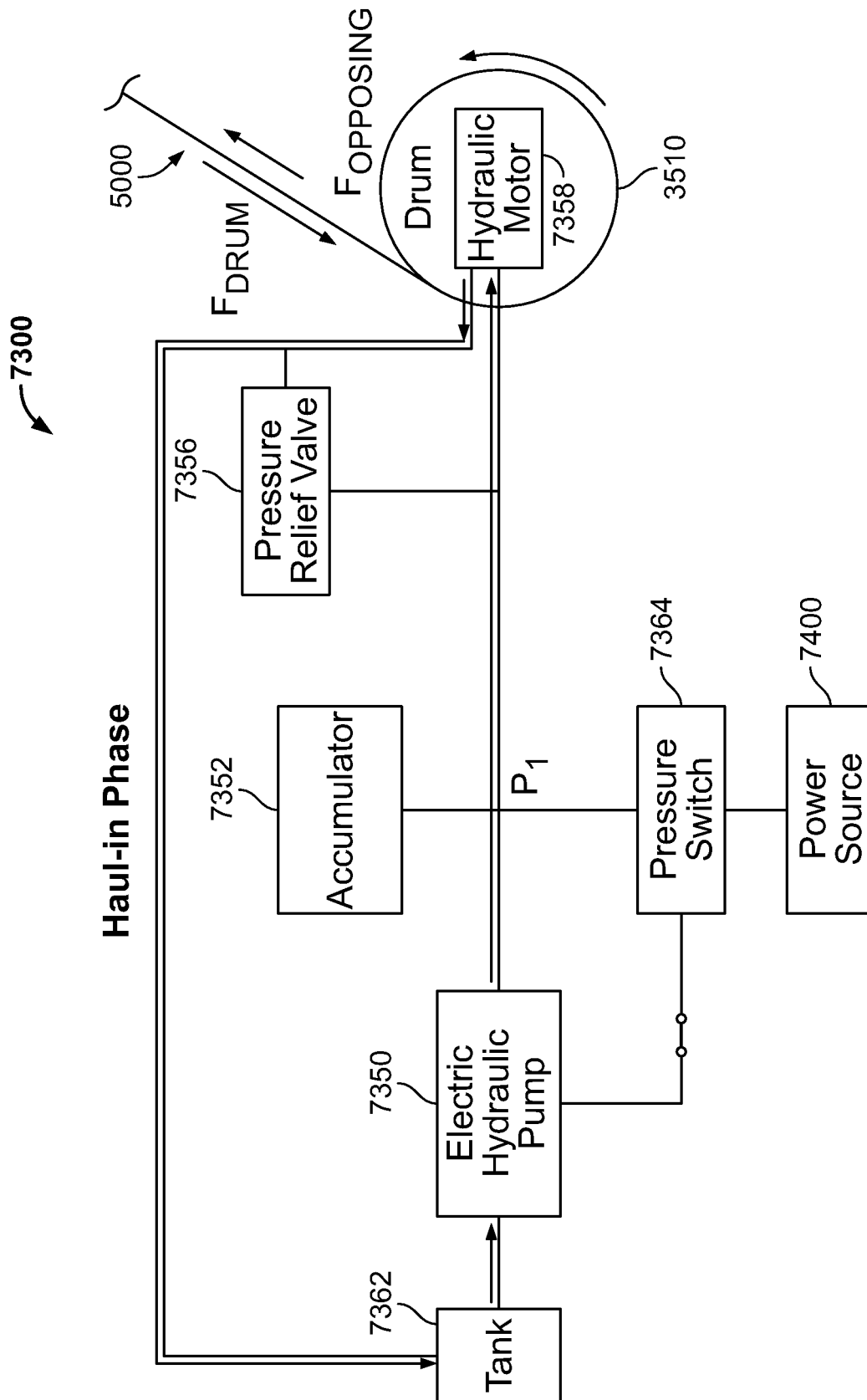


FIG. 10A

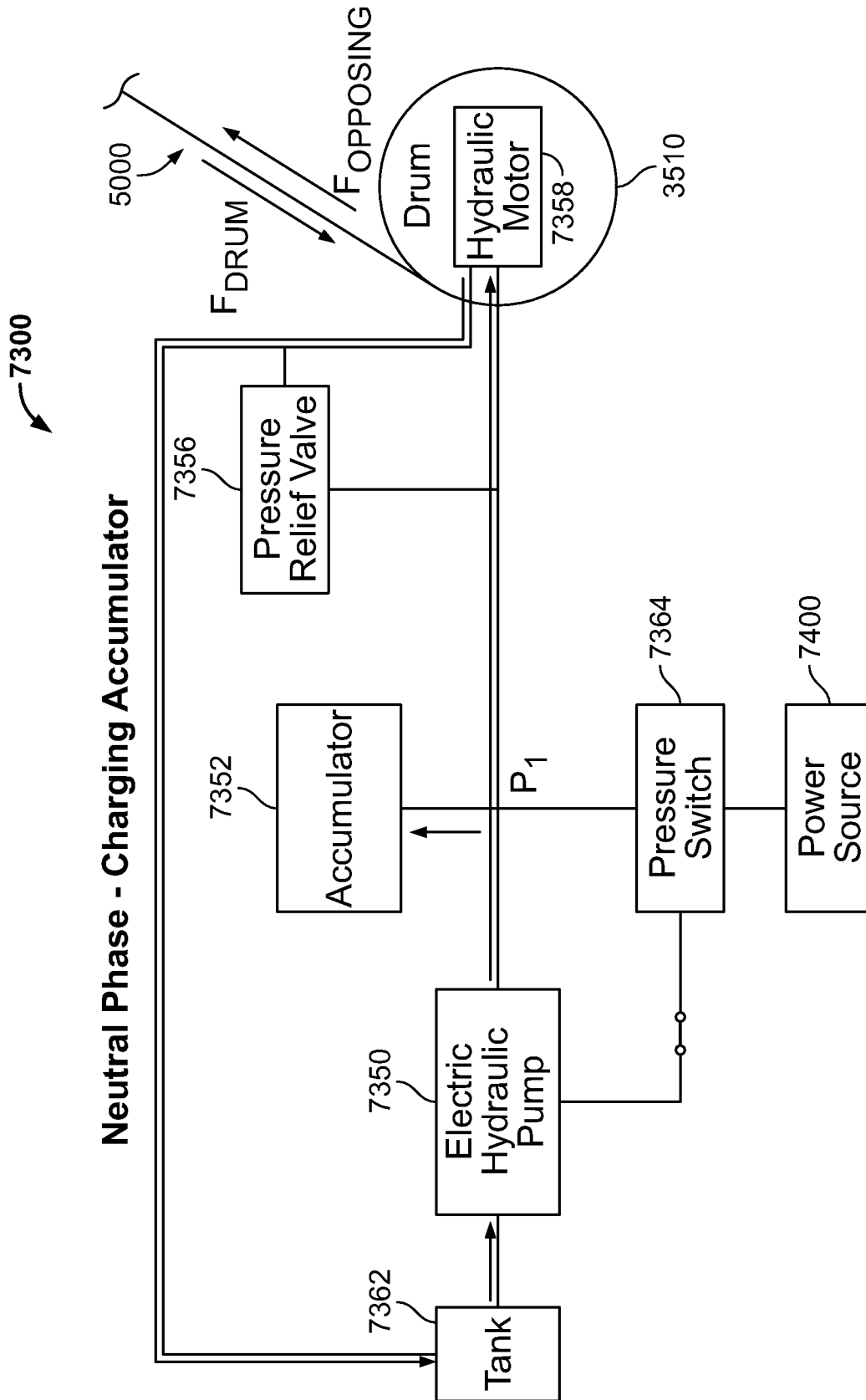


FIG. 10B

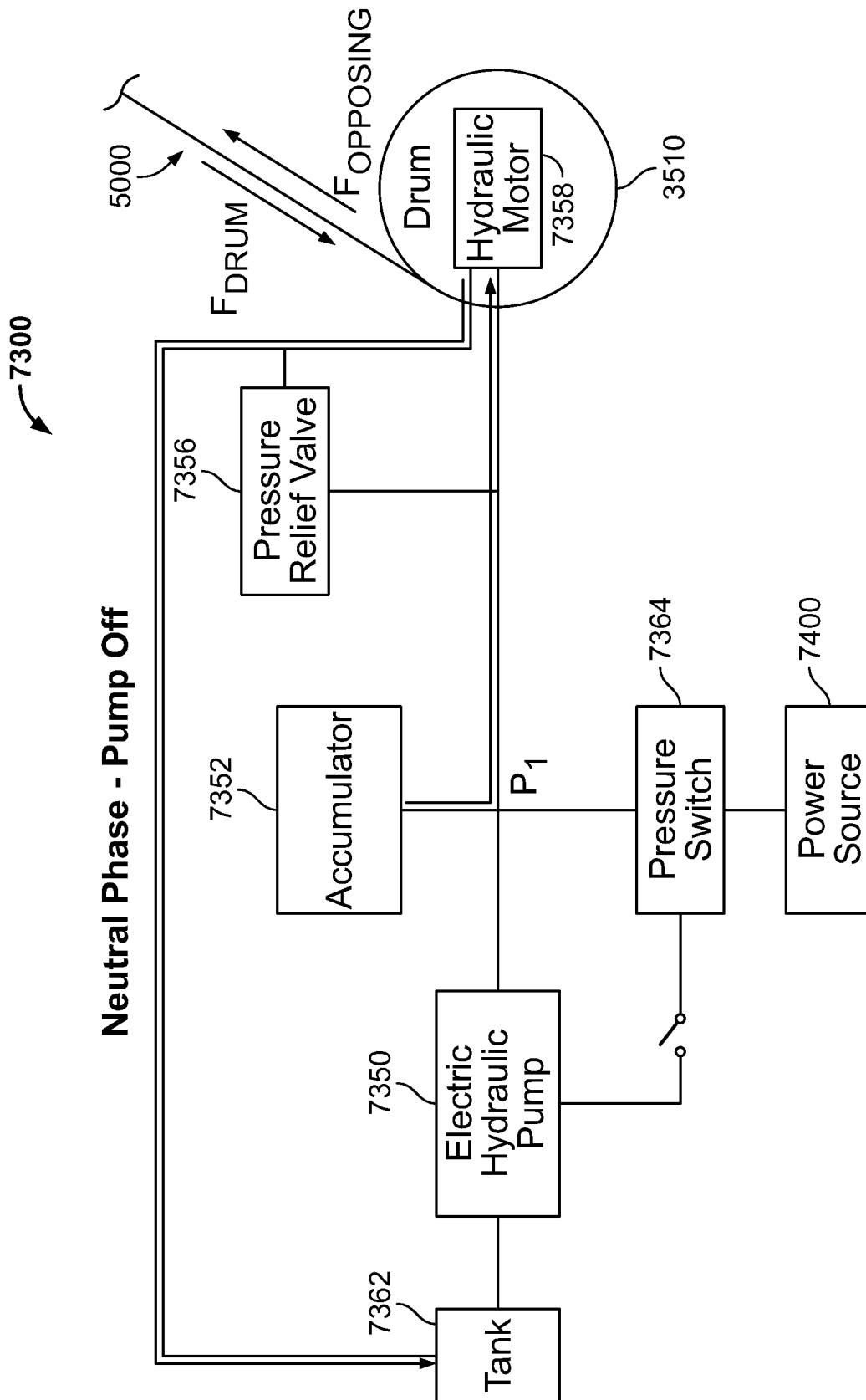


FIG. 10C

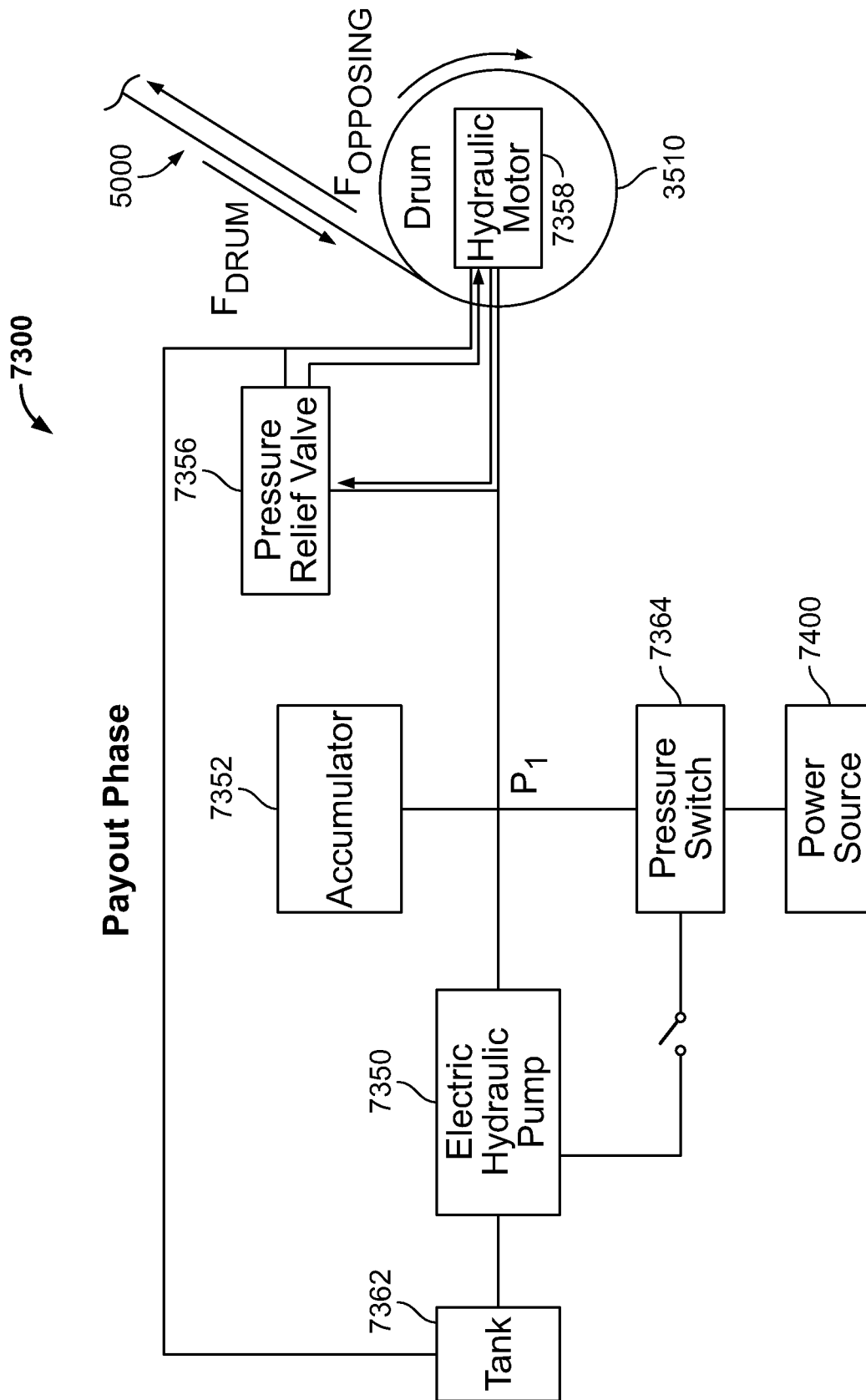


FIG. 10D

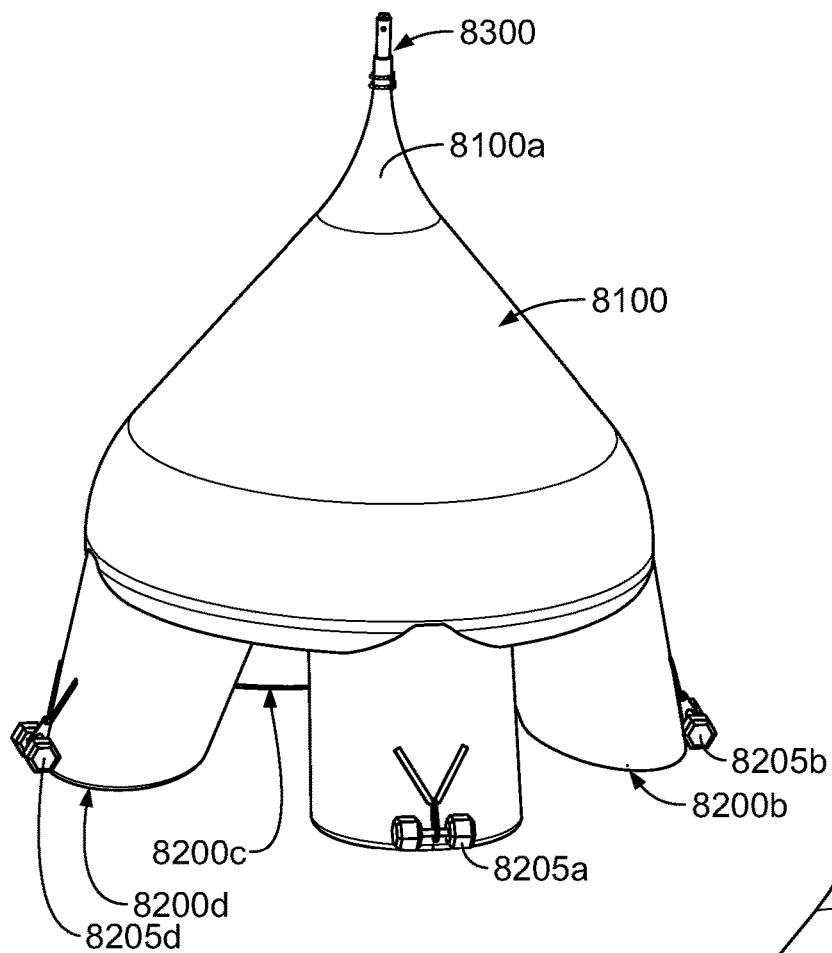


FIG. 11A

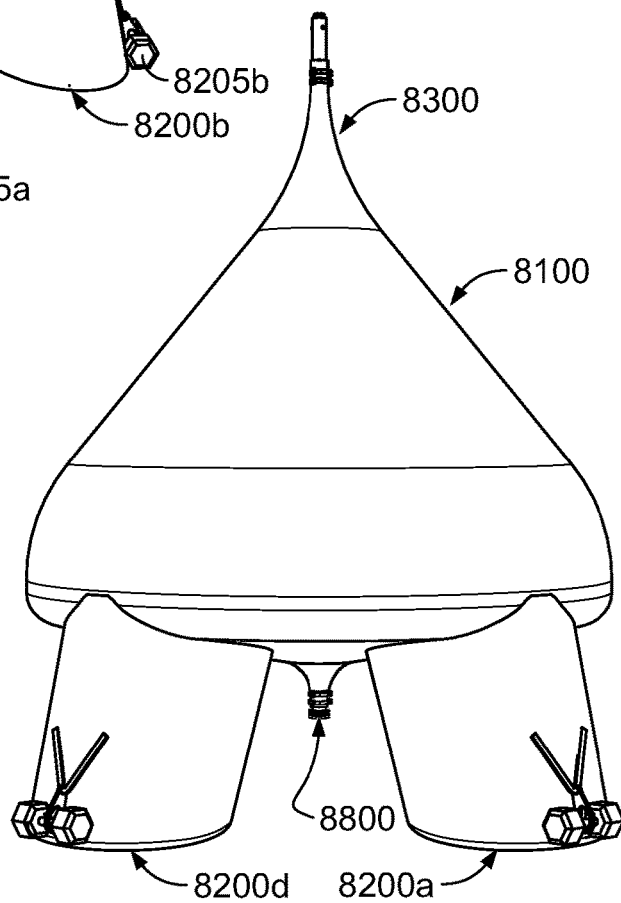


FIG. 11B

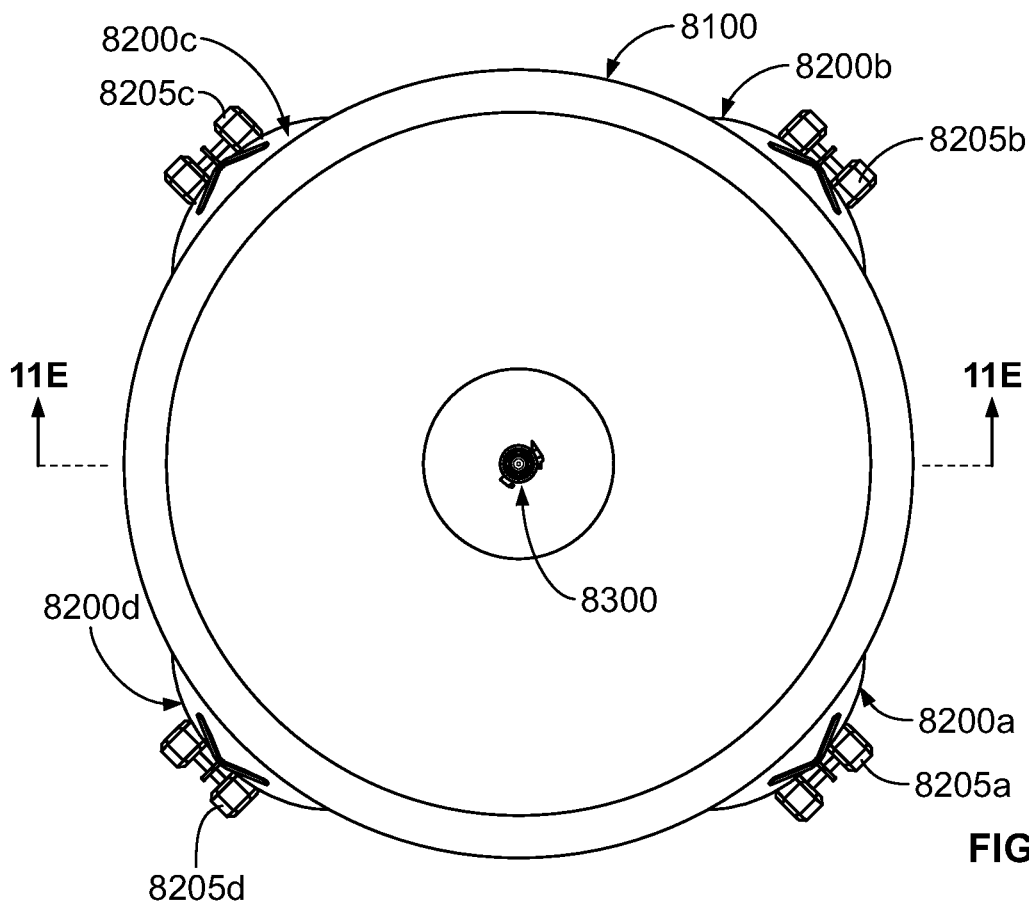


FIG. 11C

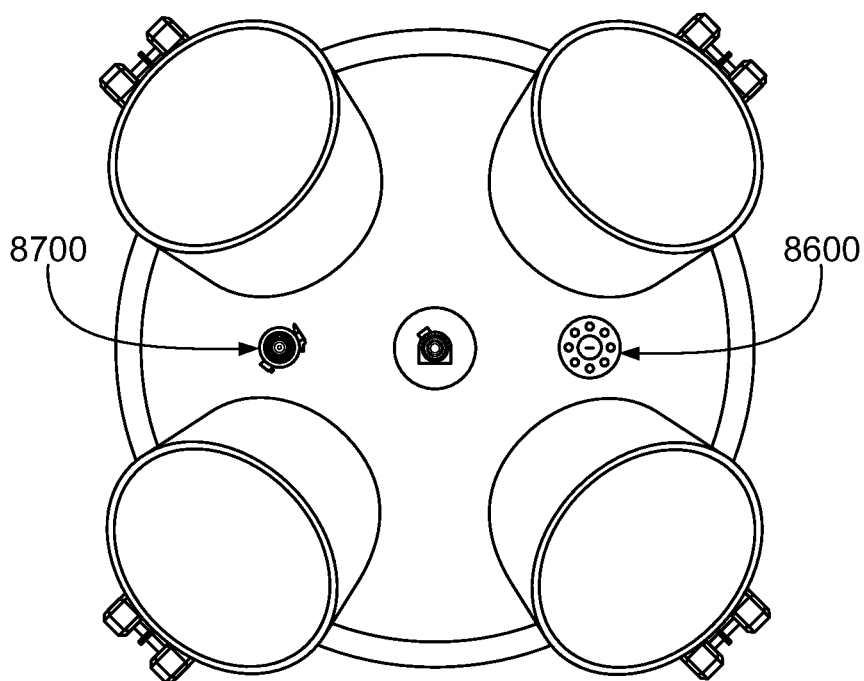


FIG. 11D

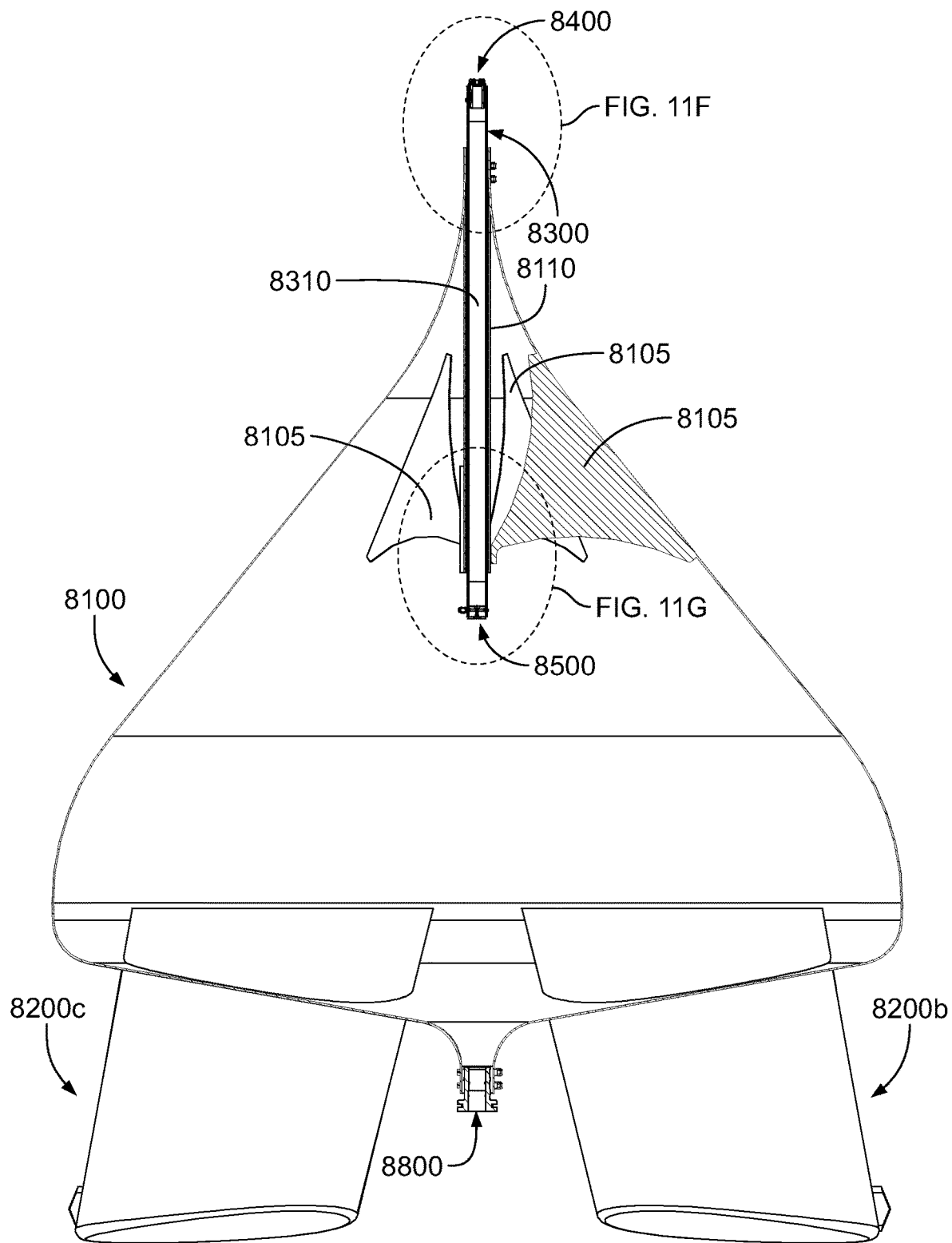


FIG. 11E

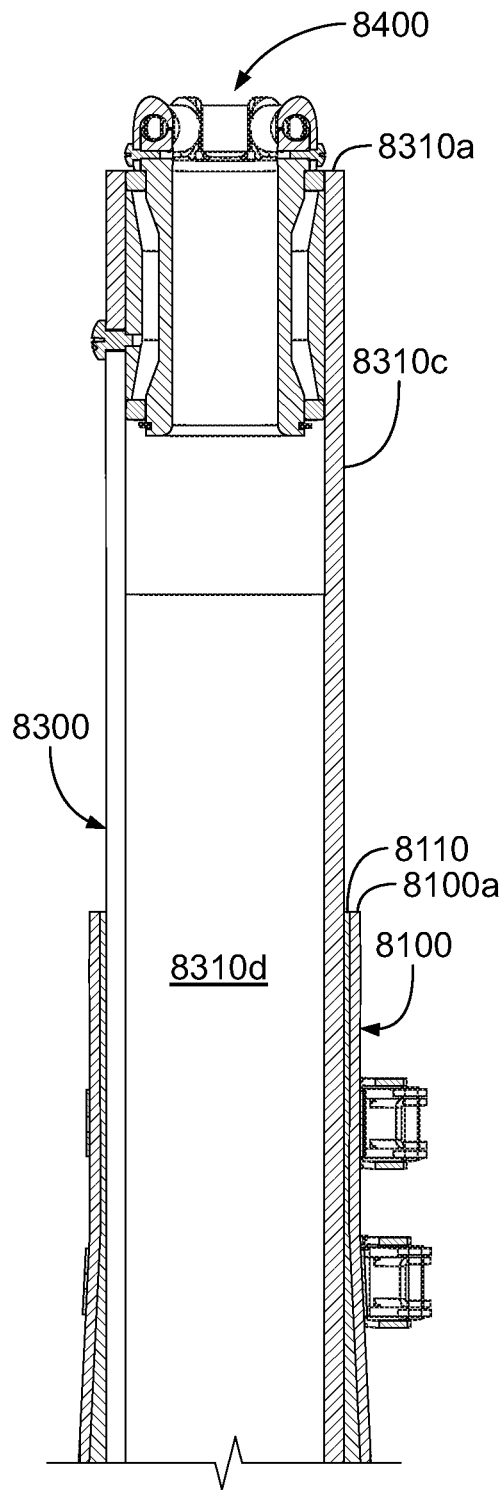


FIG. 11F

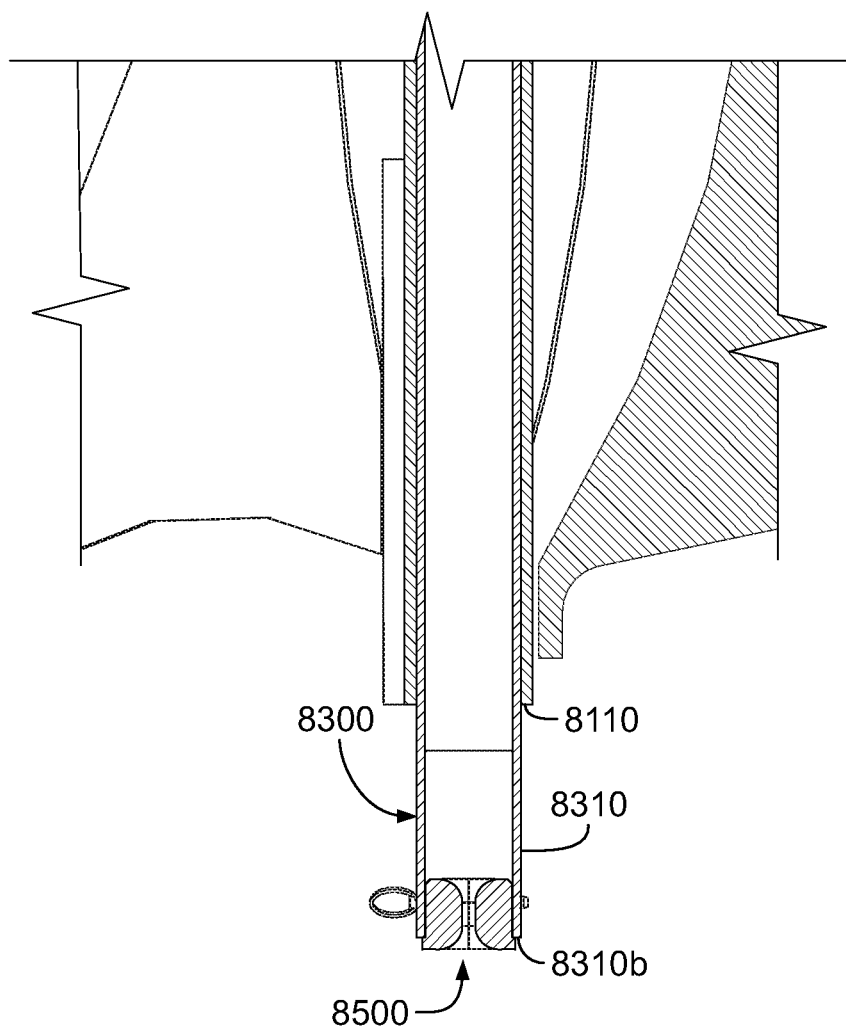


FIG. 11G

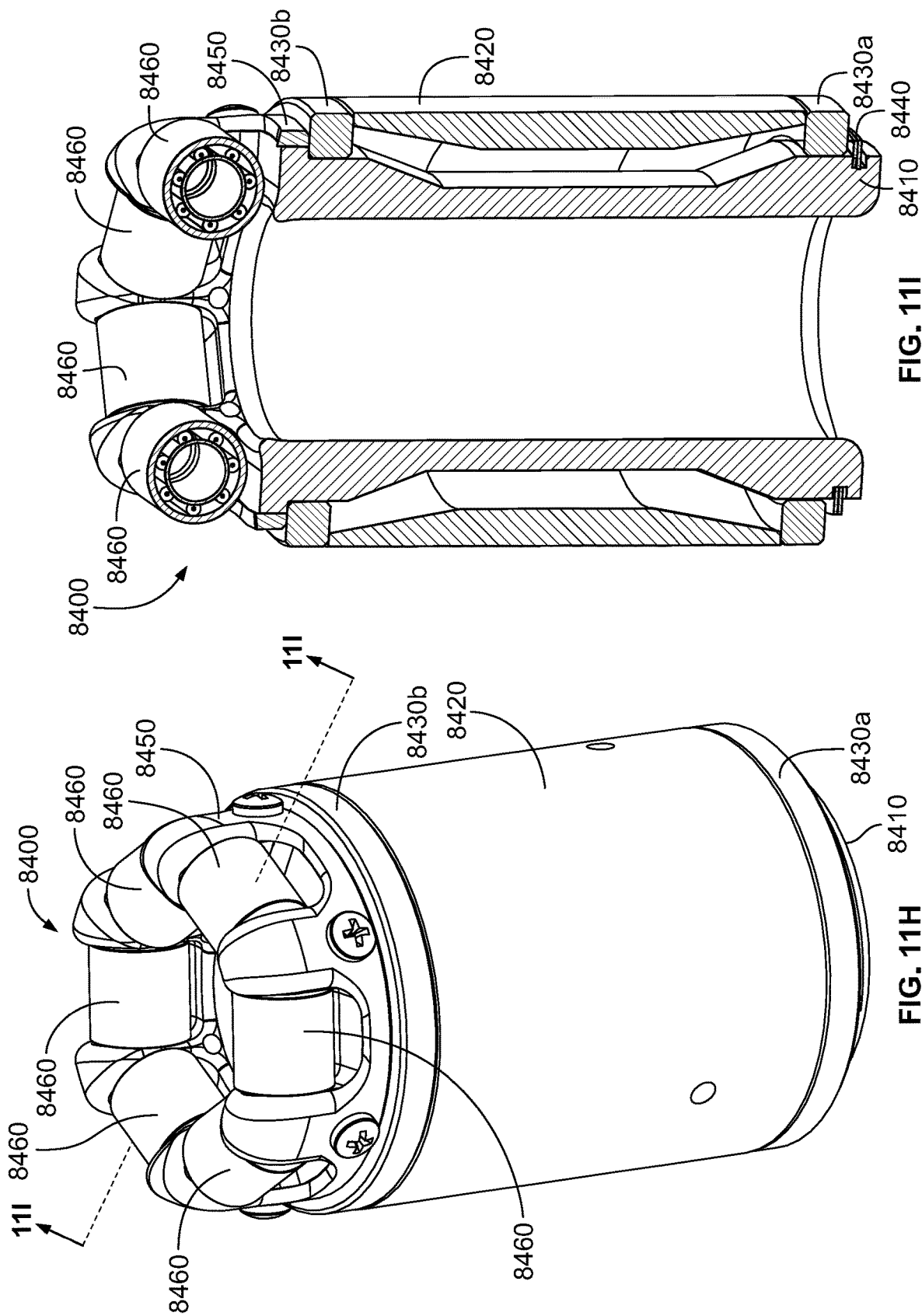


FIG. 11I

FIG. 11H

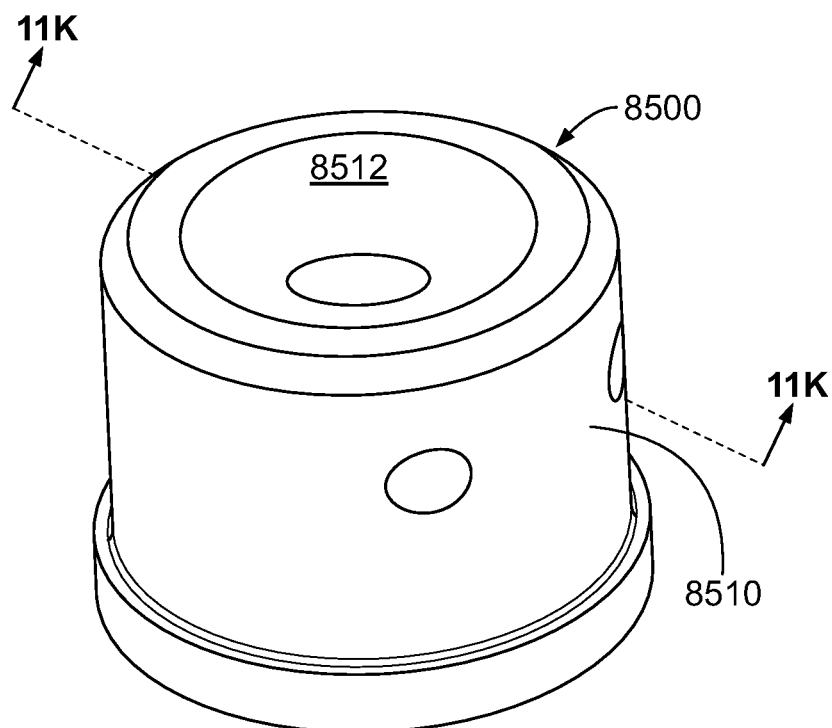


FIG. 11J

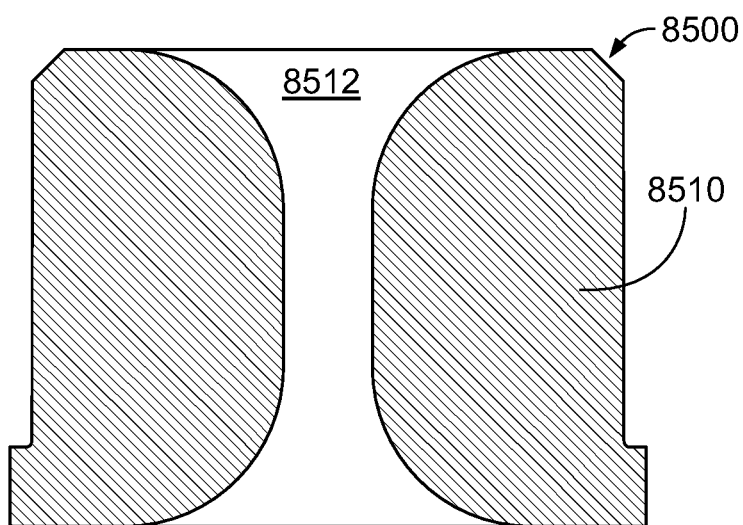
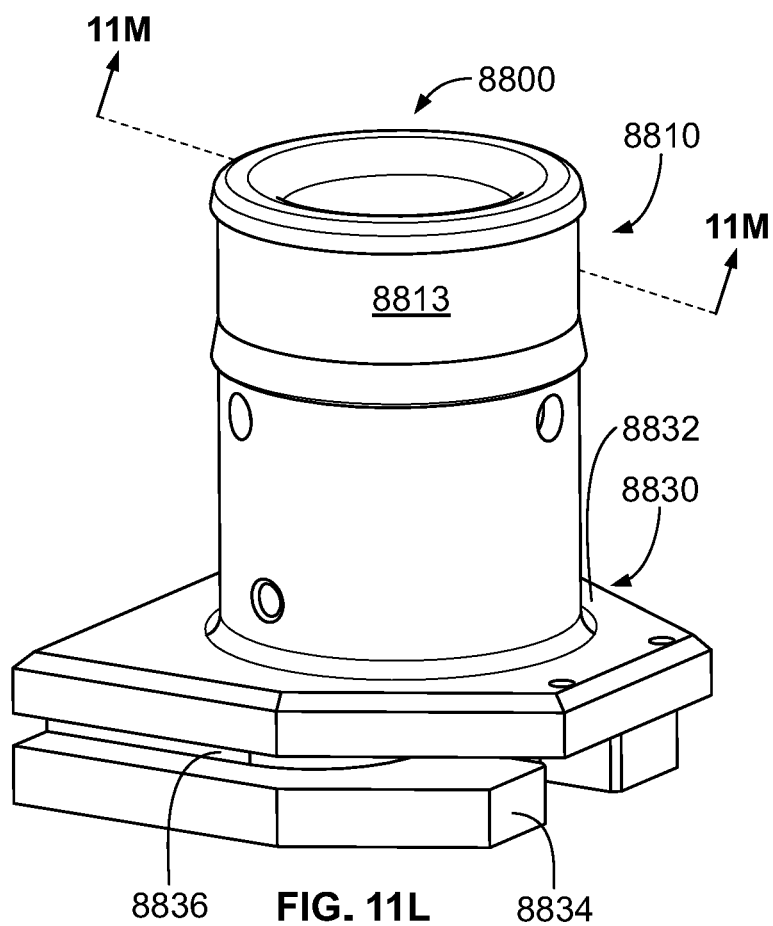


FIG. 11K



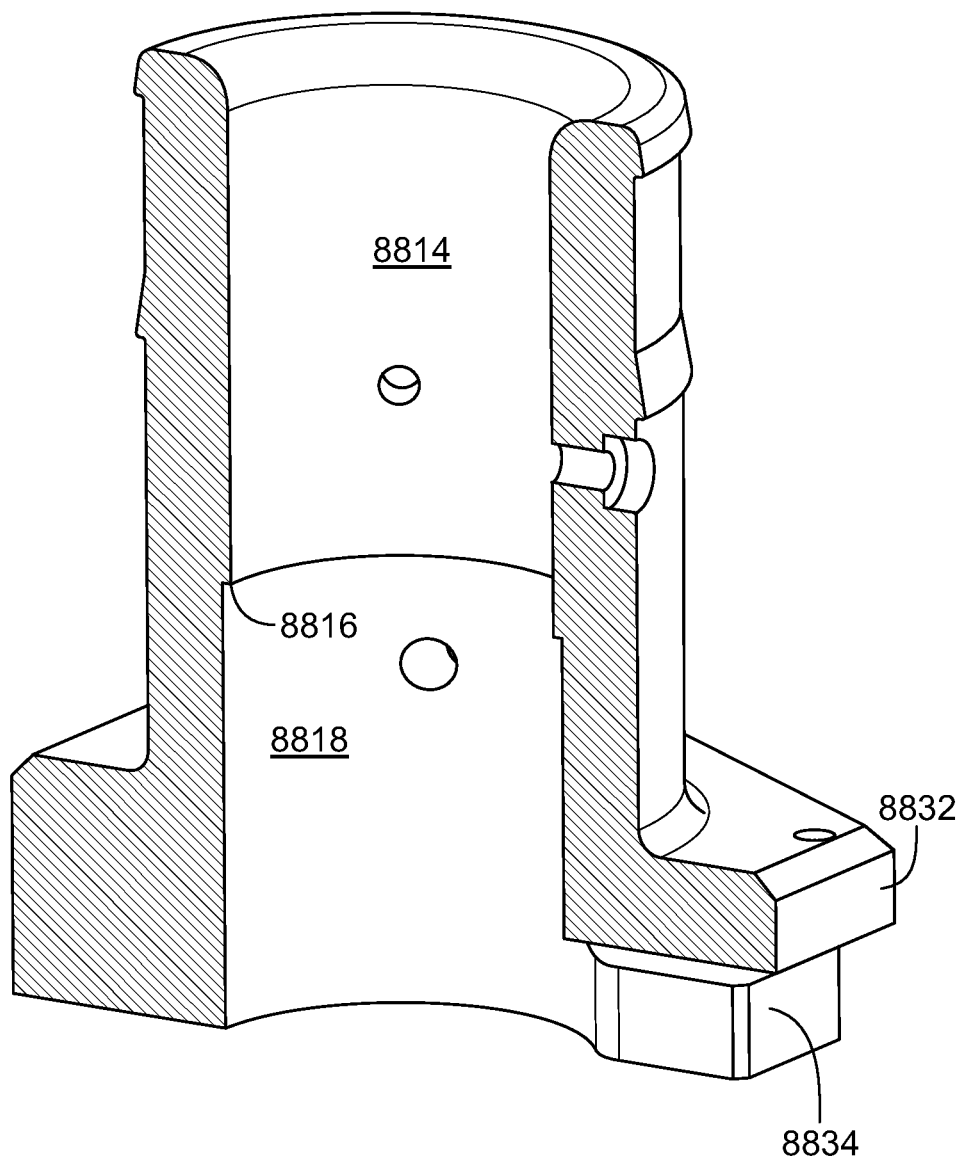


FIG. 11M

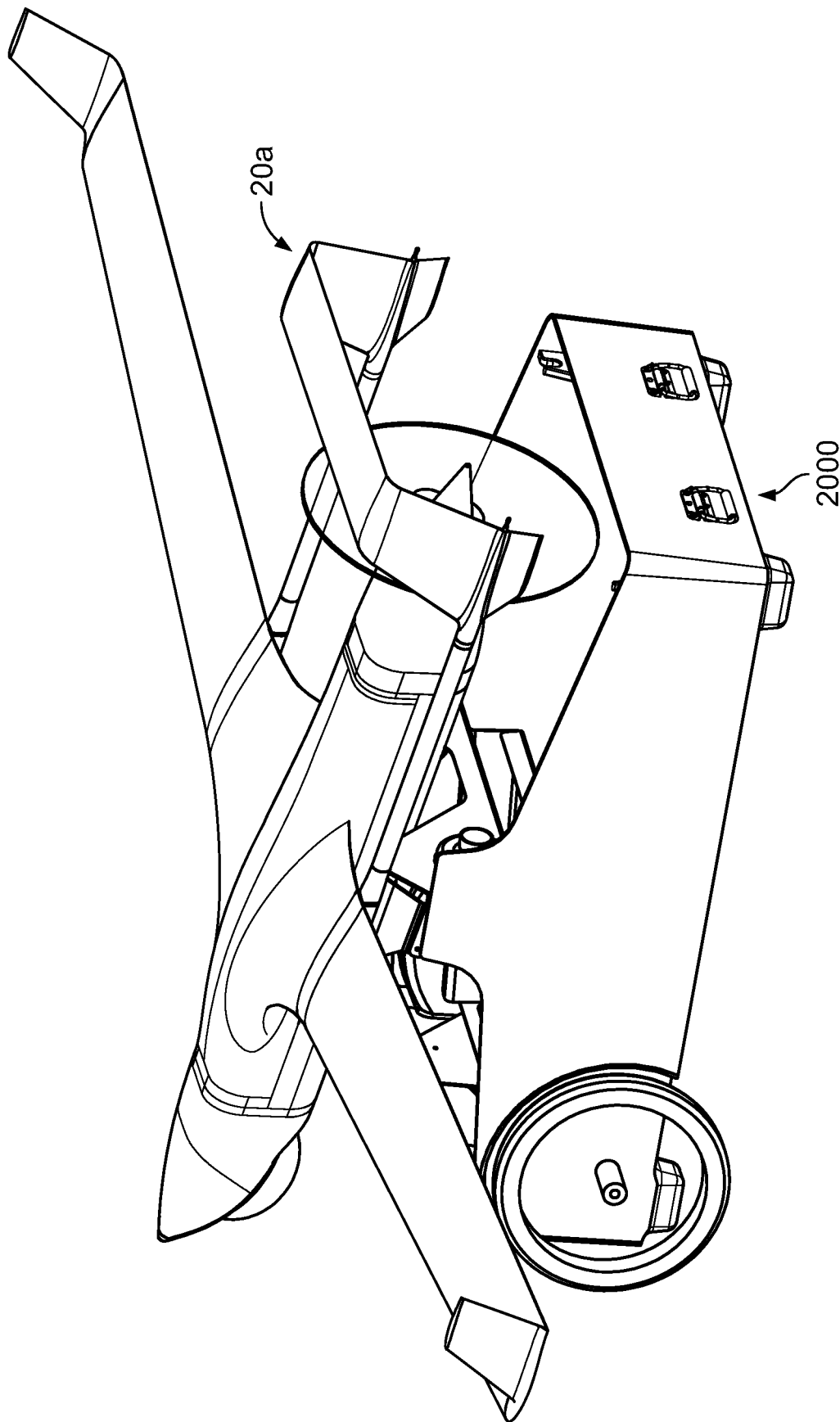


FIG. 12A

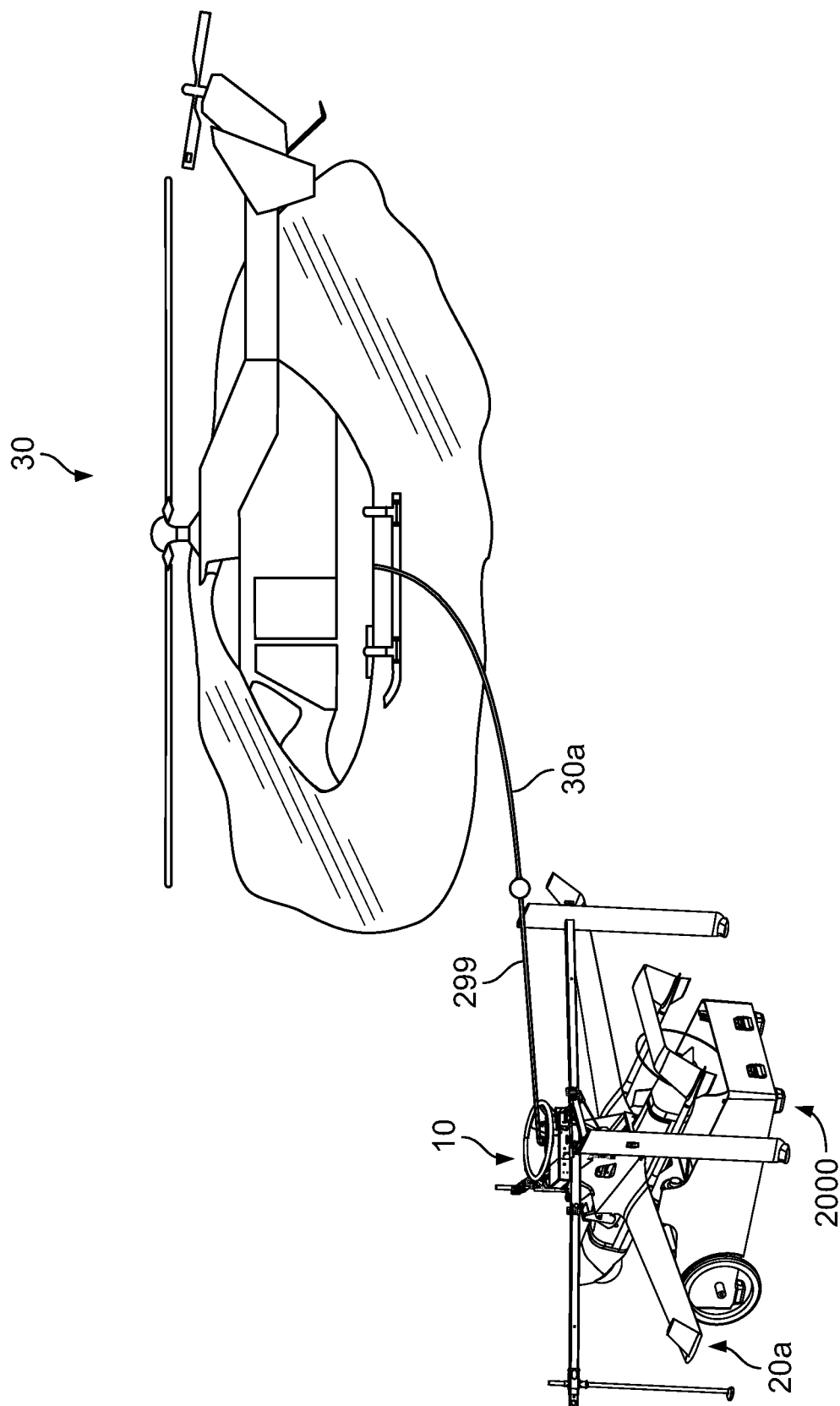
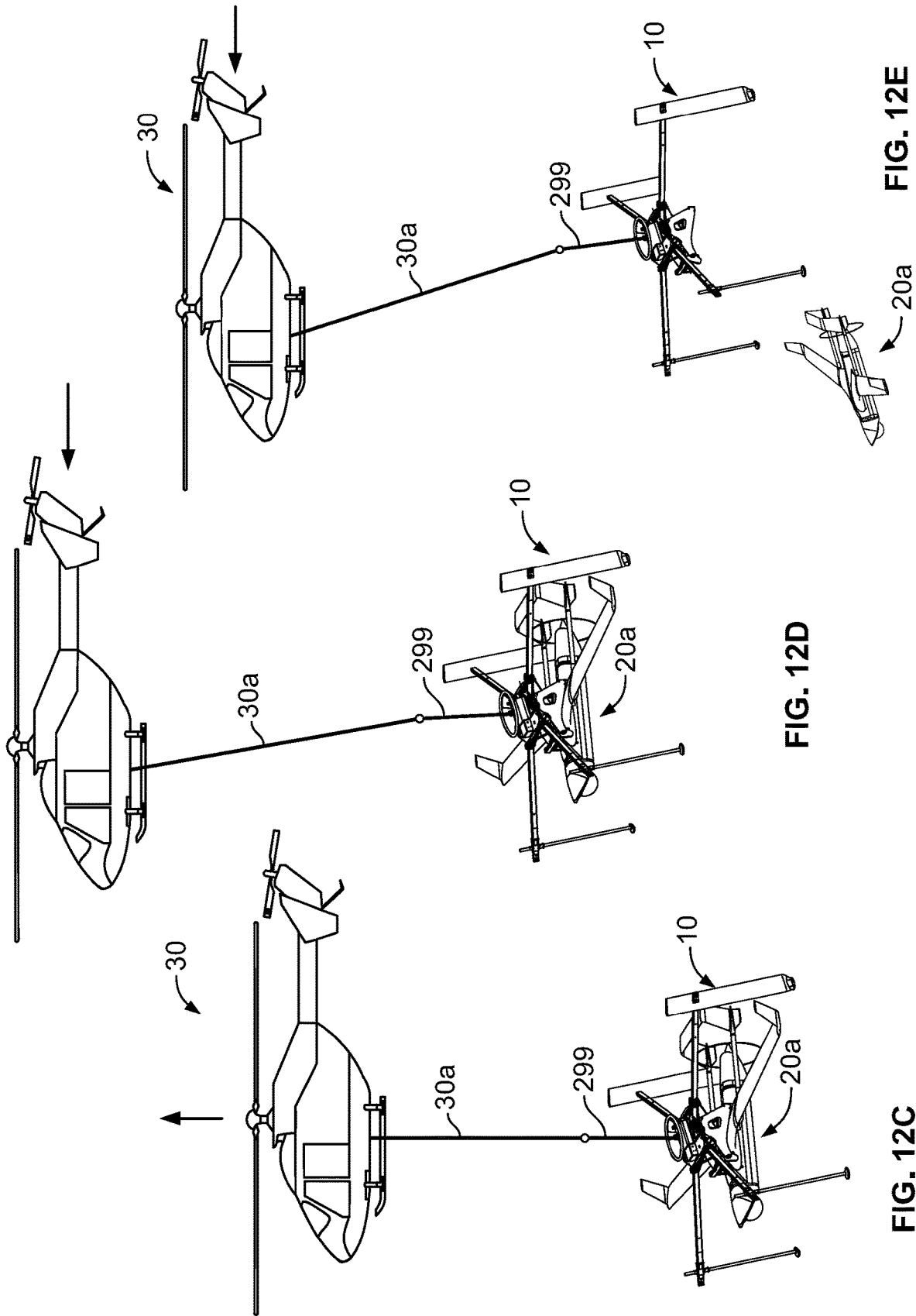


FIG. 12B



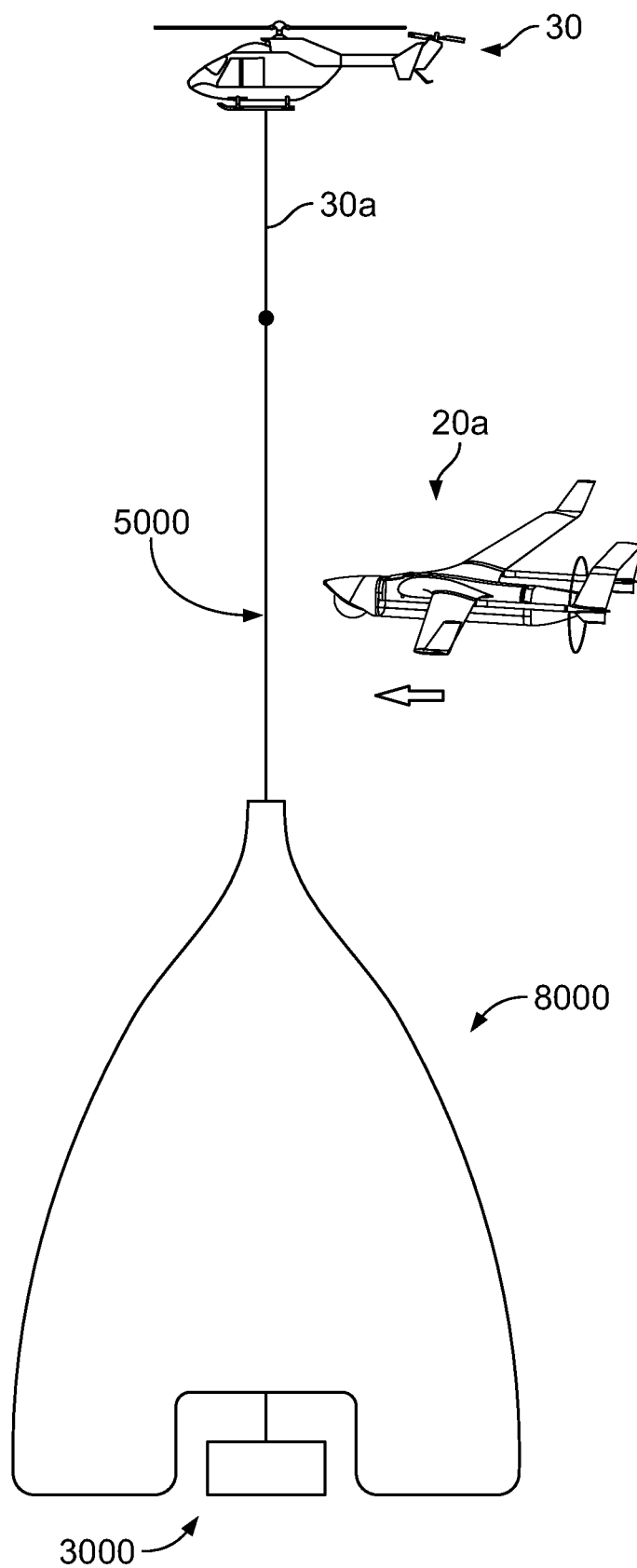
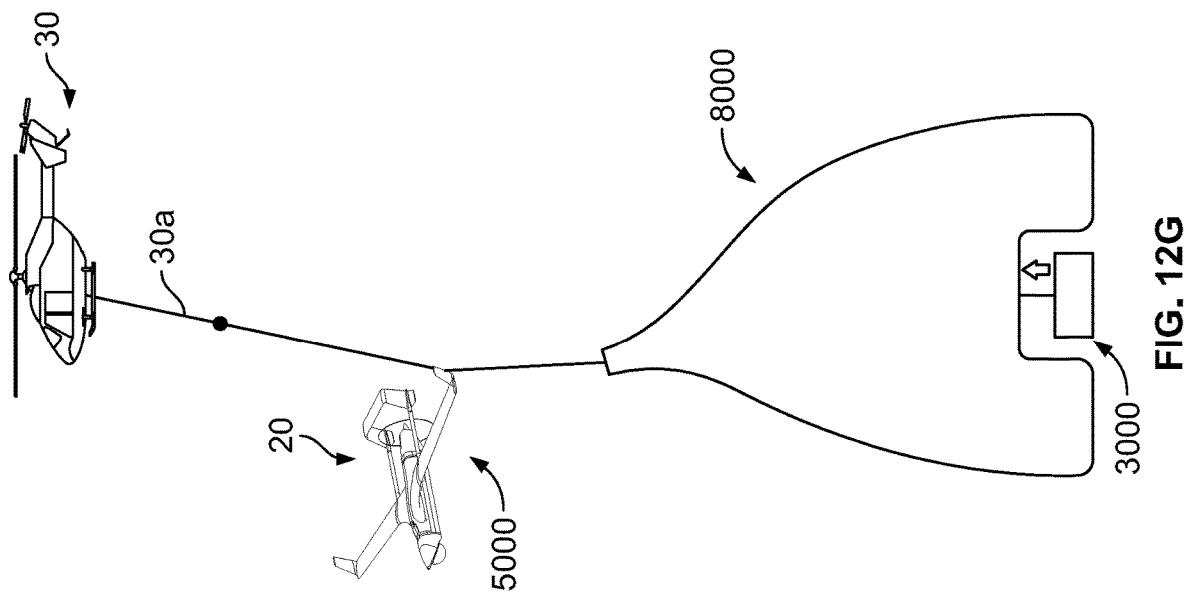
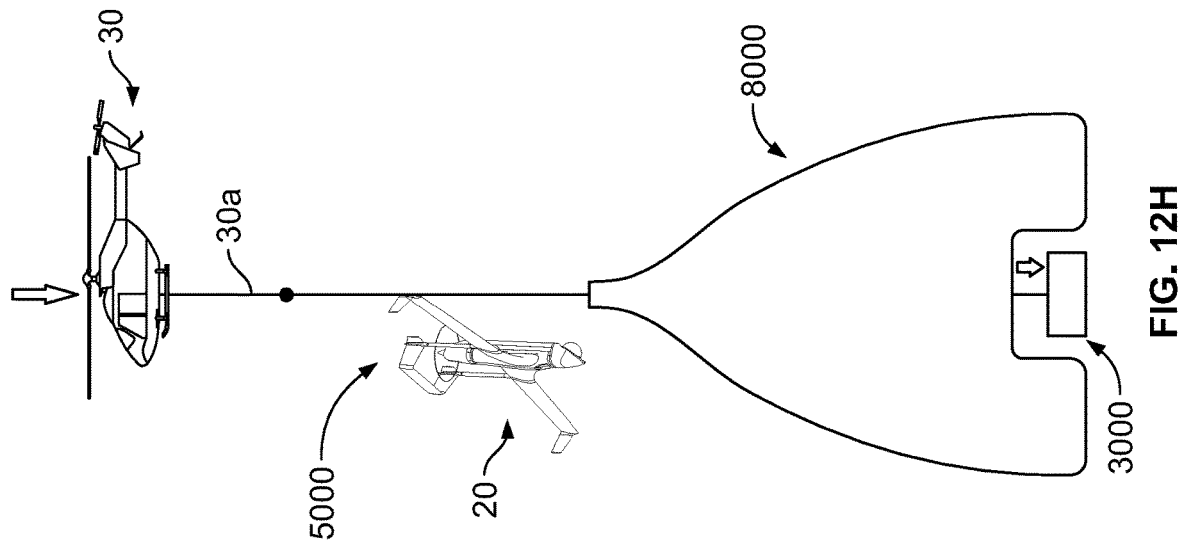


FIG. 12F



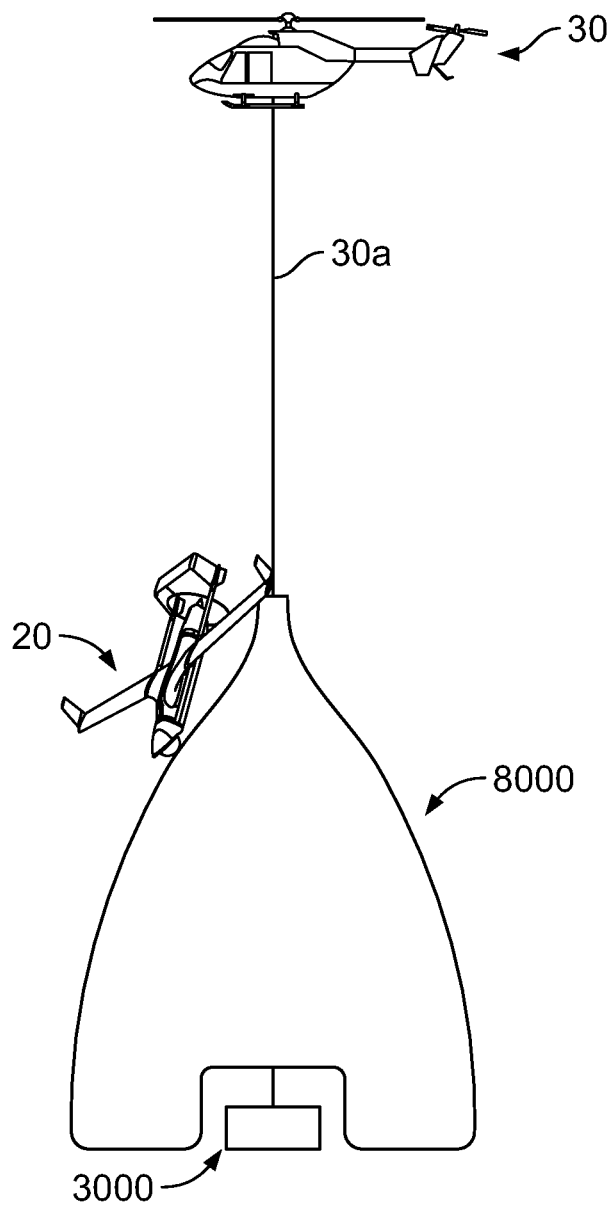


FIG. 12I

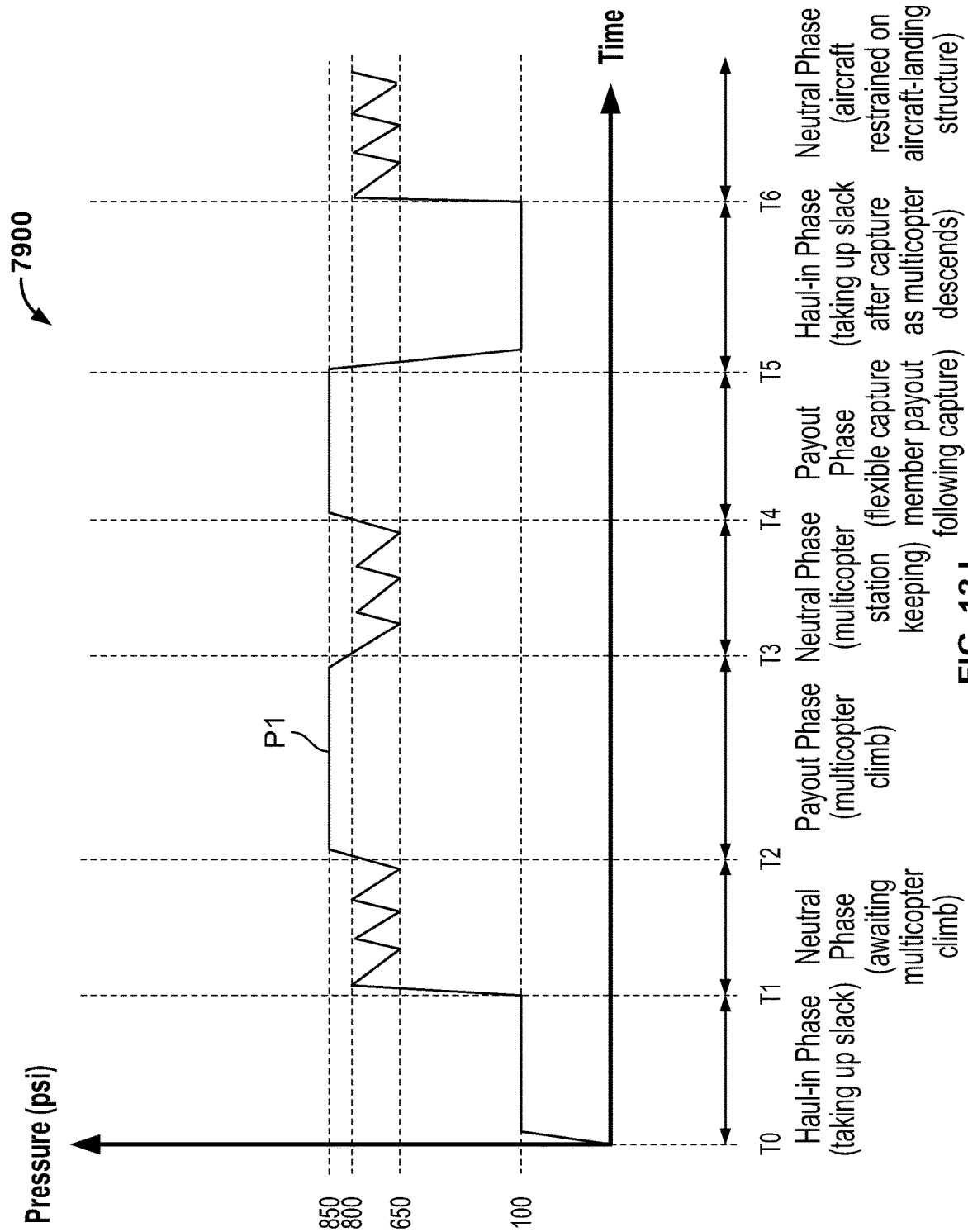


FIG. 12J

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ROTORCRAFT-ASSISTED SYSTEM FOR LAUNCHING AND RETRIEVING A FIXED-WING AIRCRAFT INTO AND FROM FREE FLIGHT

PRIORITY CLAIM

This application claims priority to and the benefit of U.S. Provisional Patent Application No. 62/554,730, which was filed on Sep. 6, 2017, the entire contents of which is incorporated herein by reference.

FIELD

The present disclosure generally relates to systems and methods for launching fixed-wing aircraft into free, wing-borne flight and for retrieving fixed-wing aircraft from free, wing-borne flight. More specifically, the present disclosure relates to systems and methods for launching fixed-wing aircraft into free, wing-borne flight using a rotorcraft and for retrieving fixed-wing aircraft from free, wing-borne flight using a rotorcraft.

BACKGROUND

Aircraft capable of long-distance, efficient cruising flight typically require long runways for take-off and landing. This limits the locations from which the aircraft can take-off and at which the aircraft can land, since many locations do not have sufficient space for a runway. There is a need for new systems and methods that eliminate the need for these aircraft to use long runways to take-off and land.

SUMMARY

Various embodiments of the present disclosure provide a rotorcraft-assisted system for launching and retrieving a fixed-wing aircraft into and from free flight (sometimes called the “launch and retrieval system” for brevity). The launch and retrieval system is usable with a rotorcraft to launch a fixed-wing aircraft into free, wing-borne flight and to retrieve the fixed-wing aircraft from free, wing-borne flight.

The launch and retrieval system includes a modular, fixed-wing aircraft launch apparatus (sometimes called the “aircraft launch apparatus” for brevity), a storage and launch system, an anchor system, a flexible capture member, and an aircraft-landing device.

The aircraft launch apparatus is attachable to the fixed-wing aircraft and is independently attachable to the rotorcraft to facilitate launching the fixed-wing aircraft into free, wing-borne flight. The storage and launch system is usable to store the aircraft launch apparatus (when disassembled) and to act as a launch mount for the fixed-wing aircraft by retaining the fixed-wing aircraft in a desired launch orientation. The anchor system is usable with the rotorcraft, the flexible capture member, and the aircraft-landing device to retrieve the fixed-wing aircraft from free, wing-borne flight.

Generally, to launch the fixed-wing aircraft into free, wing-borne flight, an operator (or operators): (1) removes the disassembled aircraft launch apparatus from a container of the storage and launch system; (2) assembles the aircraft launch apparatus; (3) mounts the fixed-wing aircraft to the storage and launch system, which retains the fixed-wing aircraft in a desired launch orientation; (4) attaches the aircraft launch apparatus to the fixed-wing aircraft; (5) independently attaches the aircraft launch apparatus to the

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rotorcraft; (6) controls the rotorcraft to lift the aircraft launch apparatus (and the attached the fixed-wing aircraft) to a desired altitude and to accelerate to a desired speed; (7) controls the aircraft launch apparatus to release the fixed-wing aircraft into free, wing-borne flight; and (8) controls the rotorcraft to land.

Generally, to retrieve the fixed-wing aircraft from free, wing-borne flight, an operator (or operators): (1) attaches a free end of the flexible capture member to the rotorcraft such that the flexible capture member extends from a drum of the anchor system through the aircraft-landing device to the rotorcraft; (2) inflates the aircraft-landing device such that it is positioned above the anchor system; (3) controls the rotorcraft to fly to a designated altitude above the anchor system and to station-keep relative to the anchor system such that the flexible capture member extends therebetween and the anchor system regulates the tension in the flexible capture member; (4) controls the fixed-wing aircraft to contact and capture the flexible capture member; (5) controls the rotorcraft to descend such that the fixed-wing aircraft contacts the aircraft-landing device without destructive impact and without the need for a ground crew to secure the fixed-wing aircraft; and (6) controls the rotorcraft to land.

Additional features and advantages of the present disclosure are described in, and will be apparent from, the following Detailed Description and the Figures.

BRIEF DESCRIPTION OF THE FIGURES

FIG. 1A is a perspective view of one example embodiment of the aircraft launch apparatus of the present disclosure attached to a fixed-wing aircraft.

FIG. 1B is a top plan view of the aircraft launch apparatus and the fixed-wing aircraft of FIG. 1A.

FIG. 1C is a partially-exploded perspective view of the aircraft launch apparatus of FIG. 1A.

FIG. 1D is a block diagram showing certain electrically-controlled components of the aircraft launch apparatus of FIG. 1A.

FIG. 2 is a perspective view of the hub module of the aircraft launch apparatus of FIG. 1A.

FIG. 3A is a partially exploded perspective view of the hub base of the hub module of FIG. 2.

FIG. 3B is a partially exploded perspective view of one of the female blind mate assemblies of the hub base of FIG. 3A.

FIG. 3C is a partial cross-sectional view of one of the flexural mounts of the female blind mate assembly of FIG. 3B.

FIG. 4A is a perspective view of the fixed-wing aircraft of FIG. 1A attached to the saddle of the hub module of FIG. 2.

FIG. 4B is top perspective view of the saddle of FIG. 4A.

FIG. 4C is a cross-sectional view of the saddle of FIG. 4A taken substantially along line 4C-4C of FIG. 4B and with certain elements removed.

FIGS. 4D and 4E are, respectively, assembled and exploded top perspective views of a rear engager of the saddle of FIG. 4A.

FIG. 4F is an exploded top perspective view of the attachment/release device of the part of the saddle of FIG. 4A.

FIGS. 4G-4I are cross-sectional side elevational views of the part of the saddle of FIG. 4A showing different configurations of the lock arm and the front engager arm taken substantially along the line 4G-4G of FIG. 4B.

FIG. 5A is a perspective view of one of the arm modules of the aircraft launch apparatus of FIG. 1A.

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FIG. 5B is perspective view of the locking assembly of the arm module of FIG. 5A.

FIGS. 5C, 5D, and 5E are side elevational views of the arm module of FIG. 5A detaching from the hub module of FIG. 2 via the locking assembly of FIG. 5B.

FIG. 6 is a perspective view of one of the front landing gear modules of the aircraft launch apparatus of FIG. 1A.

FIG. 7 is a perspective view of one of the rear landing gear modules of the aircraft launch apparatus of FIG. 1A.

FIG. 8A is a perspective view of a storage and launch system of the present disclosure in an assembled configuration.

FIG. 8B is a perspective view of the storage and launch system of FIG. 8A in a partially exploded configuration.

FIG. 8C is a perspective view of the storage and launch system of FIG. 8A with certain components removed.

FIG. 8D is a cross-sectional view of the storage and launch system of FIG. 8A with certain components removed and taken substantially along line 8D-8D of FIG. 8C.

FIG. 8E is a perspective view of the storage and launch system of FIG. 8A with certain components removed.

FIGS. 9A and 9B are a top perspective views of one example embodiment of the anchor system of the present disclosure.

FIG. 9C is a partially exploded top perspective view of the anchor system of FIGS. 9A and 9B.

FIGS. 9D and 9E are partially exploded top perspective views of the anchor system of FIGS. 9A and 9B with some components removed.

FIG. 9F is a partially exploded top perspective view of the drum assembly and the level wind system of the anchor system of FIGS. 9A and 9B.

FIG. 9G is a cross-sectional top perspective view of the anchor system of FIGS. 9A and 9B taken substantially along line 9G-9G of FIG. 9A.

FIG. 9H is a top perspective view of the anchor system of FIGS. 9A and 9B stored in a storage container with other accessories.

FIG. 10A is a schematic block diagram of a hydraulic system of the anchor system of FIGS. 9A and 9B during a flexible capture member haul-in phase of the fixed-wing aircraft retrieval process.

FIG. 10B is a schematic block diagram of the hydraulic system of FIG. 10A during a neutral phase of the fixed-wing aircraft retrieval process while the accumulator is charging.

FIG. 10C is a schematic block diagram of the hydraulic system of FIG. 10A during a neutral phase of the fixed-wing aircraft retrieval process after the accumulator has been charged and the pump is powered off.

FIG. 10D is a schematic block diagram of the hydraulic system of FIG. 10A during a flexible capture member payout phase of the fixed-wing aircraft retrieval process.

FIG. 11A is a top perspective view of an aircraft-landing device of the present disclosure.

FIG. 11B is a front elevational view of the aircraft-landing device of FIG. 11A.

FIG. 11C is a top plan view of the aircraft-landing device of FIG. 11A.

FIG. 11D is a bottom plan view of the aircraft-landing device of FIG. 11A.

FIG. 11E is a cross-sectional side elevational view of the aircraft-landing device of FIG. 11A taken substantially along line 11E-11E of FIG. 11C.

FIG. 11F is a cross-sectional side elevational view of an upper portion of the aircraft-landing device of FIG. 11A taken substantially along line 11E-11E of FIG. 11C.

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FIG. 11G is a cross-sectional side elevational view of an intermediate portion of the aircraft-landing device of FIG. 11A taken substantially along line 11E-11E of FIG. 11C.

FIG. 11H is a top perspective view of an upper guiding sealing component of the aircraft-landing device of FIG. 11A.

FIG. 11I is a cross-sectional side elevational view of the upper guiding component of FIG. 11H taken substantially along line 11I-11I of FIG. 11H.

FIG. 11J is a top perspective view of the intermediate guiding component of the aircraft-landing device of FIG. 11A.

FIG. 11K is a cross-sectional side elevational view of the intermediate guiding component of FIG. 11J taken substantially along line 11K-11K of FIG. 11J.

FIG. 11L is a top perspective view of the lower guiding and mounting component of the aircraft-landing device of FIG. 11A.

FIG. 11M is a cross-sectional side elevational view of the lower guiding and mounting component of FIG. 11L taken substantially along line 11M-11M of FIG. 11L.

FIG. 12A is a diagrammatic view of the fixed-wing aircraft mounted to the storage and launch assembly.

FIG. 12B is a diagrammatic view of the aircraft launch apparatus attached to the fixed-wing aircraft and the rotorcraft.

FIG. 12C is a diagrammatic view of the rotorcraft lifting the aircraft launch apparatus and attached fixed-wing aircraft to a desired altitude.

FIG. 12D is a diagrammatic view of the rotorcraft dashing with the aircraft launch apparatus and attached fixed-wing aircraft attached thereto.

FIG. 12E is a diagrammatic view of the rotorcraft and the attached aircraft launch apparatus just after release of the fixed-wing aircraft into free, wing-borne flight.

FIG. 12F is a diagrammatic view of the fixed-wing aircraft, the flexible capture member, the aircraft-landing device, and the anchor system just before the fixed-wing aircraft captures the flexible capture member.

FIG. 12G is a diagrammatic view of the fixed-wing aircraft, the flexible capture member, the aircraft-landing device, and the anchor system just after the fixed-wing aircraft captures the flexible capture member and as the anchor system is paying out flexible capture member.

FIG. 12H is a diagrammatic view of the fixed-wing aircraft, the flexible capture member, the aircraft-landing device, and the anchor system after the fixed-wing aircraft has stopped moving and the anchor system has retracted the paid-out portion of the flexible capture member.

FIG. 12I is a diagrammatic view of the rotorcraft, the fixed-wing aircraft, the flexible capture member, the aircraft-landing device, and the anchor system after the rotorcraft has lowered the fixed-wing aircraft onto the aircraft-landing device.

FIG. 12J is a graph of two pressures during the fixed-wing aircraft retrieval process employing the anchor system with the hydraulic system of FIGS. 10A-10D.

DETAILED DESCRIPTION

While the features, methods, devices, and systems described herein may be embodied in various forms, there are shown in the drawings, and will hereinafter be described, some exemplary and non-limiting embodiments. Not all of the depicted components described in this disclosure may be required, however, and some implementations may include additional, different, or fewer components from those

expressly described in this disclosure. Variations in the arrangement and type of the components; the shapes, sizes, and materials of the components; and the manners of attachment and connections of the components may be made without departing from the spirit or scope of the claims as set forth herein. This specification is intended to be taken as a whole and interpreted in accordance with the principles of the disclosure as taught herein and understood by one of ordinary skill in the art. The drawings are not to scale unless noted otherwise.

The rotorcraft-assisted fixed-wing aircraft launch and retrieval system (sometimes called the “launch and retrieval system” for brevity) of various embodiments of the present disclosure is usable with a rotorcraft **30** to launch a fixed-wing aircraft **20** into free, wing-borne flight and to retrieve the fixed-wing aircraft **20** from free, wing-borne flight. While the fixed-wing aircraft **20** may be any suitable fixed-wing aircraft, the fixed-wing aircraft of the example embodiments described below include: (1) the INTEGRATOR unmanned aerial vehicle **20a** (INTEGRATOR is a registered trademark of Insitu, Inc.); and (2) the SCANEAGLE unmanned aerial vehicle **20b** (SCANEAGLE is a registered trademark of the Boeing Company). While the rotorcraft **30** may be any suitable rotorcraft—such as a helicopter, quadcopter, or octocopter—the rotorcraft **30** of the example embodiments described below is a UH1 “HUEY,” H60, H65, Seahawk, Blackhawk, K-max, R44, Bell 205/206 or similar helicopter with a sling attachment capable of hoisting the mass of the aircraft launch apparatus and the fixed-wing aircraft. In other embodiments, the rotorcraft **30** is replaced with another suitable lift-producing device, such as a balloon or a parasail.

The launch and retrieval system includes a modular, fixed-wing aircraft launch apparatus **10** (sometimes called the “aircraft launch apparatus” for brevity), a storage and launch system **2000**, an anchor system **3000**, a flexible capture member **5000**, and an aircraft-landing device **8000**.

The aircraft launch apparatus **10** is attachable to the fixed-wing aircraft **20** and is independently attachable to the rotorcraft **30** to facilitate launching the fixed-wing aircraft **20** into free, wing-borne flight. The storage and launch system **2000** is usable to store the aircraft launch apparatus **10** (when disassembled) and to act as a launch mount for the fixed-wing aircraft **20** by retaining the fixed-wing aircraft **20** in a desired launch orientation. The anchor system **3000** is usable with the rotorcraft **30**, the flexible capture member **5000**, and the aircraft-landing device **8000** to retrieve the fixed-wing aircraft **20** from free, wing-borne flight.

Generally, to launch the fixed-wing aircraft **20** into free, wing-borne flight, an operator (or operators): (1) removes the disassembled aircraft launch apparatus **10** from a container of the storage and launch system **2000**; (2) assembles the aircraft launch apparatus **10**; (3) mounts the fixed-wing aircraft **20** to the storage and launch system **2000**, which retains the fixed-wing aircraft **20** in a desired launch orientation; (4) attaches the aircraft launch apparatus **10** to the fixed-wing aircraft **20**; (5) independently attaches the aircraft launch apparatus **10** to the rotorcraft **30**; (6) controls the rotorcraft **30** to lift the aircraft launch apparatus **10** (and the attached fixed-wing aircraft **20**) to a desired altitude and to accelerate to a desired speed; (7) controls the aircraft launch apparatus **10** to release the fixed-wing aircraft **20** into free, wing-borne flight; and (8) controls the rotorcraft **30** to land.

Generally, to retrieve the fixed-wing aircraft **20** from free, wing-borne flight, an operator (or operators): (1) attaches a free end of the flexible capture member **5000** to the rotor-

craft **30** such that the flexible capture member **5000** extends from a drum of the anchor system **3000** through the aircraft-landing device **8000** to the rotorcraft **30**; (2) inflates the aircraft-landing device **8000** such that it is positioned above the anchor system **3000**; (3) controls the rotorcraft **30** to fly to a designated altitude above the anchor system **3000** and to station-keep relative to the anchor system **3000** such that the flexible capture member **5000** extends therebetween and the anchor system **3000** regulates the tension in the flexible capture member **5000**; (4) controls the fixed-wing aircraft **20** to contact and capture the flexible capture member **5000**; (5) controls the rotorcraft **30** to descend such that the fixed-wing aircraft **20** contacts the aircraft-landing device **8000** without destructive impact and without the need for a ground crew to secure the fixed-wing aircraft **20**; and (6) controls the rotorcraft **30** to land. Afterwards, a ground crew can retrieve the fixed-wing aircraft **20** from the aircraft-landing device **8000**.

1. Aircraft Launch Apparatus Components

FIGS. 1A, 1B, and 1C show the aircraft launch apparatus **10**. The aircraft launch apparatus **10** is modular in that it is assembled from (and can be disassembled into) a plurality of different modules or subassemblies. The aircraft launch apparatus **10** is removably attachable to the fixed-wing aircraft **20** and is independently removably attachable to the rotorcraft **30** to facilitate launching the fixed-wing aircraft **20** into free, wing-borne flight (as described below).

As best shown in FIG. 1C, the aircraft launch apparatus **10** includes the following nine modules or subassemblies: a hub module **100**; first, second, third, and fourth arm modules **400a**, **400b**, **400c**, and **400d**; first and second front landing gear modules **600a** and **600b**; and first and second rear landing gear modules **600c** and **600d**.

As described in detail below, to assemble the aircraft launch apparatus **10** from these nine modules or subassemblies after removing the modules from the storage and launch system **2000** (described below), an operator: (1) attaches the first, second, third, and fourth arm modules **400a**, **400b**, **400c**, and **400d** to the hub module **100**; (2) attaches the first and second front landing gear module **600a** and **600b** to the first and second arm modules **400a** and **400b**, respectively; and (3) attaches the first and second rear landing gear modules **600c** and **600d** to the third and fourth arm modules **400c** and **400d**, respectively.

The modularity of this aircraft launch apparatus **10** is beneficial compared to non-modular or unitary construction. First, the modularity of this aircraft launch apparatus **10** enables an operator to quickly and easily disassemble this relatively large apparatus into nine smaller modules or subassemblies. The operator can compactly store these modules or subassemblies into a single container, which makes the disassembled aircraft launch apparatus **10** easy to store and transport compared to when it is assembled. Second, if a part of this aircraft launch apparatus **10** breaks, its modularity enables the operator to quickly and easily replace the module(s) or subassembly(ies) including the broken part with a properly-functioning replacement module(s) or subassembly(ies) rather than waste time repairing the broken component(s).

Other embodiments of the aircraft launch apparatus may include more or fewer modules.

FIG. 1D is a block diagram of certain electrically-controlled components of the aircraft launch apparatus **10**. In this embodiment, although not shown in FIG. 1D, a lithium-ion battery (or any other suitable power source(s)) powers these components. For a given component, the power source may be directly electrically connected to that component to

power that component or indirectly electrically connected to that component (e.g., via another component) to power that component.

The hub module **100** includes a hub base **200** and a saddle **300**. The hub base **200** includes a controller **272** and a communications interface **274** electrically and communicatively connected to the controller **272**. The saddle **300** includes a front engager servo motor **6341** and a lock servo motor **6345** both electrically and communicatively connected to the controller **272**. This is merely one example configuration, and these components may be located on any suitable part of the aircraft launch apparatus in other embodiments.

The controller **272** includes a processor **272a** and a memory **272b**. The processor **272a** is configured to execute program code or instructions stored in the memory **272b** to control operation of the aircraft launch apparatus **10**, as described herein. The processor **272a** may be one or more of: a general-purpose processor; a content-addressable memory; a digital-signal processor; an application-specific integrated circuit; a field-programmable gate array; any suitable programmable logic device, discrete gate, or transistor logic; discrete hardware components; and any other suitable processing device.

The memory **272b** is configured to store, maintain, and provide data as needed to support the functionality of the aircraft launch apparatus **10**. For instance, in various embodiments, the memory **272b** stores program code or instructions executable by the processor **272a** to control the aircraft launch apparatus **10**. The memory **272b** may be any suitable data storage device, such as one or more of: volatile memory (e.g., RAM, which can include non-volatile RAM, magnetic RAM, ferroelectric RAM, and any other suitable forms); non-volatile memory (e.g., disk memory, FLASH memory, EPROMs, EEPROMs, memristor-based non-volatile solid-state memory, etc.); unalterable memory (e.g., EPROMs); and read-only memory.

The communications interface **274** is a suitable wireless communication interface, such as a transceiver like an MM2 900 MHz Embedded Radio by Freewave Technologies, configured to establish and facilitate communication between the controller **272** and: (1) a computing device (such as a laptop computer, a tablet computer, or a mobile phone, not shown); and (2) an R/C controller (not shown) that the operator of the aircraft launch apparatus **10** controls. In certain embodiments, the rotorcraft **30** is communicatively connected to the processor **272** via the communications interface **274**. In operation, once the communications interface **274** establishes communication with the computing device, the controller **272** can send data (via the communications interface **274**) associated with the operation of the aircraft launch apparatus **10** to the computing device. Once the communications interface **274** establishes communication with the R/C controller, the controller **272** can receive signals (via the communications interface **274**) from the R/C controller. More specifically, upon receipt of these signals from the R/C controller, the communications interface **274** converts these signals into a format readable by the controller **272** and sends the converted signals to the controller **272** for processing.

The above-described communication may be bidirectional or unidirectional. In some embodiments, the communications interface **274** enables the controller **272** to send data to the computing device but not receive data from the computing device. In other embodiments, the communications interface **274** enables the controller **272** to send data to the computing device and to receive data from the comput-

ing device. In some embodiments, the communications interface **274** enables the controller **272** to receive signals from the R/C controller but not send signals to the R/C controller. In other embodiments, the communications interface **274** enables the controller **272** to receive signals from the R/C controller and send signals to the R/C controller. For example, the communications interface **274** might relay altitude and airspeed data from onboard sensors to a remote control console. If altitude and airspeed are acceptable, the remote operator would then command the launch apparatus to UNLOCK and RELEASE the fixed-wing aircraft into flight, as described below.

In certain embodiments, the communications interface **274** includes separate components for communicating with the computing device (such as a telemetry link) and the R/C controller (such as an R/C receiver).

In certain embodiments, the aircraft launch apparatus **10** includes suitable sensors configured to measure its altitude and its pitch, roll, and yaw rates. In certain embodiments, the processor **272a** is configured to prevent release of the fixed-wing aircraft **30** if the aircraft launch apparatus **10** has an altitude below a certain threshold or a pitch, roll, or yaw rate above a certain threshold.

1.1 Hub Module

FIG. 2 shows the hub module **100**. The hub module **100**: (1) serves as the attachment point for the arm modules **400a** to **400d**; (2) is the portion of the aircraft launch apparatus **10** to which the fixed-wing aircraft **20** and the rotorcraft **30** are attached for launch; (3) includes the power source for the aircraft launch apparatus **10**; and (4) includes certain components used to control operation of the aircraft launch apparatus **10**.

The hub module **100** includes a hub base **200** and a saddle **300**. The saddle **300** is attached to the underside of the hub base **200** via various brackets and fasteners (not labeled). This is merely one example of how the saddle can be attached to the hub base, and in other embodiments the saddle may be attached to the hub base in any suitable manner.

1.1.1 Hub Base

FIGS. 3A, 3B, and 3C show the hub base **200** or components thereof. The hub base **200** is the portion of the hub module **100** that: (1) serves as the attachment point for the arm modules **400a** to **400d**; (2) is the portion of the aircraft launch apparatus **10** to which the rotorcraft **30** is attached for launch; (3) includes the power source for the aircraft launch apparatus **10**; and (4) includes certain components used to control operation of the aircraft launch apparatus **10**.

As best shown in FIG. 3A, the hub base **200** includes four elongated tubular rectangular supports **210a**, **210b**, **210c**, and **210d** attached to a first mounting plate **202** with suitable brackets and fasteners. Stabilizing brackets (not labeled) extend between and connect the free ends of the supports **210a** and **210b** and the supports **210c** and **210d**. A second mounting plate **250b** is attached to the supports **210a**, **210b**, **210c**, and **210d** such that the supports are sandwiched between the first and second mounting plates **202** and **250**. A housing **270** is mounted to the second mounting plate **250**. The housing **270** encloses various electrical components, such as the power source, the controller **272**, and the communications interface **274**.

A guard **282** is attached to a guard mounting bracket **280** (via suitable fasteners) that is attached to the second mounting plate **250** (via suitable fasteners). A snag-prevention member attachment device **284** is attached to the guard **282** near the center of the guard **282** (when viewed from the top). As described in detail below, a snag-prevention member **299**

is attachable to the snag-prevention member attachment device **284** (such as a universal joint) such that the snag-prevention member **299** can rotate 360 degrees (or less in other embodiments) relative to the guard **282** and the aircraft launch apparatus **10** and pivot relative to a vertical axis between an angle defined by the geometry of the guard **282** and the geometry of the snag-prevention member **299**. In this embodiment, the snag-prevention member **299** includes a flexible rod (such as a carbon-fiber rod) that has a normal shape to which it is biased to return once flexed. The snag-prevention member **299** may attach to the snag-prevention member attachment device **284** in any suitable manner, such as via a carabiner or other hook-type manner of attachment.

The open free ends of the tubular supports **210a-210d** form arm module receiving sockets that can receive one of the arm modules **400a** to **400d**. Specifically, the support **210a** forms a first arm module receiving socket **214a** sized to receive the first arm module **400a**, the support **210b** forms a second arm module receiving socket (not shown) sized to receive the second arm module **400b**, the support **210c** forms a third arm module receiving socket (not shown) sized to receive the third arm module **400c**, and the support **210d** forms a fourth arm module receiving socket **214d** sized to receive the fourth arm module **400d**.

As best shown in FIG. 3A, female blind mate assemblies are attached to the free ends of the hollow supports **210a-210d**. Specifically, a first female blind mate assembly **230a** is attached to the free end of the support **210a** near the first arm module receiving socket **214a**, a second female blind mate assembly **230b** is attached to the free end of the support **210b** near the second arm module receiving socket, a third female blind mate assembly **230c** is attached to the free end of the support **210c** near the third arm module receiving socket, and a fourth female blind mate assembly **230d** is attached to the free end of the support **210d** near the fourth arm module receiving socket **214d**.

The female blind mate assemblies **230** (along with the corresponding male blind mate connectors described below with respect to the arm modules) facilitate mechanical attachment of the arm modules **400a**, **400b**, **400c**, and **400d** to the hub module **100**.

FIGS. 3B and 3C show the second female blind mate assembly **230b**. The female blind mate assemblies **230a**, **230c**, and **230d** are similar to the second female blind mate assembly **230b** and are therefore not separately shown or described.

The second female blind mate assembly **230b** includes: (1) a female blind mate connector **231b** including a plurality of pin receptacles (not labeled); (2) three elastomeric grommets **232b**; (3) three rigid, hollow cylindrical spacers **233b**; (4) three fasteners **234b**; (5) three nuts **235b**; (6) a mounting bracket **236b**; and (7) mounting bracket fasteners (not labeled).

The mounting bracket **236b** is positioned at a desired location along the hollow support **210b**, and the mounting bracket fasteners are tightened to clamp the mounting bracket **236b** in place relative to the hollow support **210b**.

The female blind mate connector **231b** is flexurally mounted to the mounting bracket **236b** via the elastomeric grommets **232b**, the spacers **233b**, the fasteners **234b**, and the nuts **235b**. Specifically, the elastomeric grommets **232b** are fitted into corresponding cavities in the female blind mate connector **231b**. As best shown in FIG. 3C, each cavity includes an inwardly-projecting annular rib that fits into a corresponding annular cutout of the corresponding elastomeric grommet **232b**. The spacers **233b** are disposed within

longitudinal bores defined through the elastomeric grommets **232b**. The fasteners **234b** extend through the hollow spacers **233b** and through corresponding fastener receiving openings defined through the mounting bracket **236b** into their corresponding nuts **235b**. This secures the female blind mate connector **231b** to the mounting bracket **236b**.

This flexural mount of the female blind mate connector to the mounting bracket via the elastomeric grommets is beneficial compared to a rigid connection of the female blind mate connector to the mounting bracket. The flexural mount enables the female blind mate connector to move—via deformation of the elastomeric grommet—relative to the mounting bracket (and the rest of the hub module) when loads are applied to the female blind mate connector, such as loads imposed on the female blind mate connector by the attached arm module during flight. Because the female blind mate connector is not rigidly attached to the corresponding mounting bracket, it is less likely that the pins of the male blind mate connector (described below) received by the pin receptacles of the female blind mate connector will break when loads are applied to the female blind mate connector.

As best shown in FIG. 3C, a latch plate **237** is attached to the underside of each hollow support **210a** and **210b** below each female blind mate connector **231** attached thereto. The latch plate **237** includes a claw engager **238** and a backstop **239**. The latch plate **237** is described below with respect to the locking assemblies **420** of the arm modules **400a** to **400d**.

1.1.2 Saddle

FIGS. 4A-4I show the saddle **300** or components thereof. The saddle **300** is the portion of the hub module **100**: (1) to which the fixed-wing aircraft **20a** is attached for launch; (2) from which the fixed-wing aircraft **20a** is released for launch.

This embodiment of the saddle **300** is sized, shaped, arranged, and otherwise configured to attach to and release the fixed-wing aircraft **20a** without requiring any modification to the fixed-wing aircraft **20a**. The size, shape, arrangement, and configuration of the components of the saddle **300** may be modified such that the saddle **300** can attach to and release other fixed-wing aircraft (such as the fixed-wing aircraft **20a**).

The saddle **300** includes a saddle base bracket **6310** and first and second saddle side brackets **6312** and **6314** straddling the saddle base bracket **6310**. A cross-brace **6318** is connected to and extends between the first and second saddle side brackets **6312** and **6314** near their back ends. As described in more detail below, the front ends of the first saddle side bracket **6312**, the second saddle side bracket **6314**, and the saddle base bracket **6310** are connected or otherwise mounted to a front engager **6320** such that the front engager **6320** can rotate relative to the first saddle side bracket **6312**, the second saddle side bracket **6314**, and the saddle base bracket **6310**. Although not shown for clarity, the saddle base bracket **6310** is fixedly connected to the hub base via suitable mounting brackets, and the first and second saddle side brackets **6312** and **6314** are fixedly connected to the hub base via suitable fasteners.

As best shown in FIGS. 4B and 4C, the front engager **6320** includes: a shaft **6321**; first and second leading-edge engagers **6323** and **6326**; sleeve bearings **6322**, **6324**, **6325**, and **6327**; and a stabilizer **6328**.

The first leading-edge engager **6323** includes a generally triangular base **6323a** having a tube **6323c** extending therefrom. A shaft-receiving bore (not labeled) extends through the base **6323a** and the tube **6323c**. The base **6323a** defines a contoured leading edge engaging surface **6323b** that is shaped to receive and engage the portion of the leading edge

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of the wing of the fixed-wing aircraft **20a** to which the saddle **300** will attach, as described below. The base **6323a** includes a plurality of strengthening ribs extending outward from the tube **6323c**. Similarly, the second leading-edge engager **6326** includes a generally triangular base **6326a** having a tube **6326c** extending therefrom. A shaft-receiving bore (not labeled) extends through the base **6326a** and the tube **6326c**. The base **6326a** defines a contoured leading edge engaging surface **6326b** that is shaped to receive and engage the portion of the leading edge of the wing of the fixed-wing aircraft **20a** to which the saddle **300** will attach, as described below. The base **6326a** includes a plurality of strengthening ribs extending outward from the tube **6326c**.

As noted above, the front engager **6230** is connected or otherwise mounted to the saddle base bracket **6310** and the first and second saddle side brackets **6312** and **6314** such that the front engager **6230** is rotatable relative to those components. The saddle base bracket **6310** includes a tubular mounting portion **6310a** that defines a shaft-receiving bore therethrough. Part of the shaft **6321** is received in the shaft-receiving bore of the tubular mounting portion **6310a** such that first and second free ends of the shaft are positioned on opposing sides of the tubular mounting portion **6310a**. The shaft **6321** is rotatably fixed relative to the saddle base bracket **6310**, though in other embodiments the shaft **6321** may rotate relative to the saddle base bracket **6310**. Suitable bearings may be incorporated at the interfaces between the saddle base bracket and the shaft to facilitate rotation of the shaft relative to the saddle base bracket.

The first and second leading-edge engagers **6323** and **6326** are rotatably mounted to the shaft **6321** on opposite sides of the tubular mounting portion **6310a** of the saddle base bracket **6310** via the sleeve bearings **6322**, **6324**, **6325**, and **6327**. Specifically, the sleeve bearings **6322** and **6324** are press fit into the opposing ends of the shaft-receiving bore through the first leading-edge engager **6323** such that the sleeve bearings **6322** and **6324** cannot rotate relative to the first leading-edge engager **6323**. Part of the shaft **6321** is received in the sleeve bearings **6322** and **6324** and the shaft-receiving bore of the first leading-edge engager **6323** such that the first end of the shaft **6321** protrudes from the sleeve bearing **6324**. The first end of the shaft **6321** is received in a first retaining element **6329a** fixedly attached to the second saddle side bracket **6314**. The first retaining element **6329a** prevents substantial axial movement of the shaft **6321** relative to the first retaining nub **6329a**, and retains the first leading-edge engager **6323** on the shaft **6321**. At this point, the first leading-edge engager **6323** is mounted to the shaft **6321** via the sleeve bearings **6322** and **6324** such that the first leading-edge engager **6323** is rotatable about the longitudinal axis of the shaft **6321** relative to the saddle base bracket **6310**. The longitudinal axis of the shaft **6321** is above the leading edges of the wings of the fixed-wing aircraft **20a**.

Similarly, the sleeve bearings **6325** and **6327** are press fit into the opposing ends of the shaft-receiving bore through the second leading-edge engager **6326** such that the sleeve bearings **6325** and **6327** cannot rotate relative to the second leading-edge engager **6326**. Part of the shaft **6321** is received in the sleeve bearings **6325** and **6327** and the shaft-receiving bore of the second leading-edge engager **6326** such that the second end of the shaft **6321** protrudes from the sleeve bearing **6325**. The second end of the shaft **6321** is received in a second retaining element **6329b** fixedly attached to the first saddle side bracket **6312**. The second retaining element **6329b** prevents substantial axial movement of the shaft **6321** relative to the second retaining

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element **6329a**, and retains the second leading-edge engager **6326** on the shaft **6321**. At this point, the second leading-edge engager **6326** is mounted to the shaft **6321** via the sleeve bearings **6325** and **6327** such that the second leading-edge engager **6326** is rotatable about the longitudinal axis of the shaft **6321** relative to the saddle base bracket **6310**.

The stabilizer **6328** is attached to the base **6323a** of the first leading-edge engager **6323** and to the base **6326a** of the second leading-edge engager **6326** such that the stabilizer **6328** extends between and connects the first and second leading-edge engagers **6323** and **6326**. The stabilizer **6328** ensures the first and second leading-edge engagers **6323** and **6326** rotate relative to the saddle base bracket **6310** and the first and second saddle side brackets **6312** and **6314** substantially simultaneously rather than independently of one another.

As best shown in FIGS. 4B and 4F, an aircraft attaching/releasing assembly **6340** is attached to the saddle base bracket **6310** and to the front engager **6320** and controls rotation of the first engager **6320** about the longitudinal axis of the shaft **6321** relative to the saddle base bracket **6310**. As best shown in FIG. 4F, the aircraft attaching/releasing assembly **6340** includes: a front engager servo motor **6345** having a front engager servo motor shaft **6345a**, a front engager arm **6342**, a front engager arm lock device **6342a**, a servo spacer **6344**, first and second nut plates **6347a** and **6347b**, fasteners **6348** and corresponding nuts **6348a**, a front engager rotation control link **6343** having connectors **6343a** and **6343b** at opposite ends, a lock servo motor **6341** having a lock servo motor shaft **6341a**, a lock arm **6346** terminating at one end in a locking extension **6346a**, and first and second front engager attachment brackets **6349a** and **6349b**.

The front engager servo motor **6345** and the lock servo motor **6341** are attached to one another and to the saddle base bracket **6310** via the fasteners **6348**, the servo spacer **6344**, the first and second nut plates **6347a** and **6347b**, and the nuts **6348a**.

The front engager arm **6342** is attached near one end to the front engager servo motor shaft **6345a** and near the other end to the connector **6343a**. The connector **6343b** is attached to the stabilizer **6328** of the front engager **6320** via the first and second front engager attachment brackets **6349a** and **6349b** (such as via suitable fasteners, not shown). This operatively links the front engager servo motor shaft **6345a** to the front engager **6320**. The front engager arm lock device **6342a** is attached to the front engager arm **6342** between the connector **6343a** and the front engager servo motor shaft **6345a**.

The lock arm **6346** is attached to the lock servo motor shaft **6341a** near one end. The free end of the lock arm **6346** terminates in the locking extension **6346a**, which is engageable to the front engager arm lock device **6342a** in certain instances to prevent clockwise (from the viewpoint shown in FIGS. 4G-4I) rotation of the front engager arm **6342**.

The front engager servo motor **6345** controls rotation of the front engager **6320** (and, specifically, the first and second leading-edge engagers **6323** and **6326**) about the longitudinal axis of the shaft **6321** relative to the saddle base bracket **6310**. To rotate the front engager **6320**, the front engager servo motor **6345** rotates the front engager servo motor shaft **6345a**, which rotates the attached front engager arm **6342**, which in turn rotates the front engager **6320** via the front engager rotation control link **6343**. The front engager servo motor **6345** can rotate the front engager **6320** between an attached rotational position-shown in FIGS. 4G and 4H—and a release rotational position-shown in FIG. 4I.

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The lock servo motor **6341** controls rotation of the lock arm **6346** between a front engager rotation-preventing rotational position—shown in FIG. 4G—and a front engager rotation-enabling rotational position—shown in FIGS. 4H and 4I. When the front engager **6320** is in the attached rotational position and the lock arm **6346** is in the front engager rotation-preventing rotational position, the locking extension **6346a** engages the front engager arm lock device **6342a** of the front engager arm **6342**. This prevents the front engager servo motor **6345** from rotating the front engager **6320** clockwise (from the viewpoint shown in FIGS. 4G-4I) from the attached rotational position to the release rotational position. As best shown in FIG. 4G, the servo spacer **6344** prevents counter-clockwise rotation (from the viewpoint shown in FIGS. 4G-4I) of the front engager arm **6342**.

FIGS. 4G-4I show how the front engager servo motor **6345** and the lock servo motor **6341** cooperate to rotate the front engager **6320** from the attached rotational position to the release rotational position. Initially, the front engager arm **6342** is in the attached rotational position and the lock arm **6346** is in the front engager rotation-preventing rotational position. Here, the locking extension **6346a** on the end of the lock arm **6346** engages the front engager arm lock device **6342a** of the front engager arm **6342**.

Since the locking extension **6346a** engages the front engager lock device **6342a** of the front engager arm **6342**, the front engager servo motor **6345** cannot rotate the front engager **6320** from the attached rotational position to the release rotational position (clockwise from this viewpoint). And as indicated above, the servo spacer **6344b** prevents counter-clockwise rotation of the front engager arm **6342** (from this viewpoint).

Rotating the front engager **6320** from the attached rotational position to the release rotational position is a two-step process. As shown in FIG. 4H, the operator first operates the lock servo motor **6341** to rotate the lock arm **6346** into the front engager rotation-enabling rotational position (clockwise from this viewpoint). Second, as shown in FIG. 4I, the operator operates the front engager servo motor **6345** to rotate the front engager **6320** from the attached rotational position to the release rotational position (clockwise from this viewpoint).

As shown in FIG. 4B, separate (but in this embodiment, identical) rear engagers **6360** (here, trailing-edge engagers) are attached to the first and second saddle side brackets **6312** and **6314**. As best shown in FIGS. 4D and 4E, the rear engager **6360** includes a body **6362** and a pivotable portion **6364** pivotably connected to the body **6362** via a suitable pivot shaft (not shown). The body **6362** includes a trailing edge engaging surface **6362a**. The pivotable portion **6364** includes multiple surfaces that define a trailing edge receiving channel **6364a** sized and shaped to receive the trailing edge of a wing of the fixed-wing aircraft **20a**. Fasteners **6366** are threadably received in the pivotable portion **6364**. The fasteners **6366** engage the top surface of the wing of the fixed-wing aircraft **20a**, and can be threaded further into or further out of the pivotable portion **6364** as desired to adjust clearance between the pivotable portion **6364** and the exterior upper surface of the wing. In one embodiment, the fasteners are formed from a relatively soft material, such as Teflon, and the pivotable portion is formed from a relatively harder material, such as aluminum.

The body **6362** is fixedly attached to the appropriate saddle side bracket via suitable fasteners (not shown for clarity) such that the trailing edge engaging surface **6362a** and the pivotable portion **6364** extend below the body **6362**.

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In operation, to launch the fixed-wing aircraft **20a** an operator first attaches the hub module **100** to the fixed-wing aircraft **20a**, assembles the aircraft-launch apparatus **10**, hoists the fixed-wing aircraft **20a** using the rotorcraft **30** and the aircraft-launch apparatus **10** and brings it to a desired airspeed, and releases the fixed-wing aircraft **20a** from the aircraft-launch apparatus **10**, as described below.

More specifically, the operator attaches the hub module **100** to the fixed-wing aircraft **20a** by: (1) operating the front engager servo motor **6345** (either manually or remotely via the R/C controller) to rotate the front engager **6320** to the release rotational position; (2) inserting the trailing edges of the wings of the fixed-wing aircraft **20a** into the trailing edge receiving channels **6364a** of the pivotable portions **6364** of the rear engagers **6360**; (3) positioning the saddle **300** relative to the fixed-wing aircraft **20a** such that the leading edge engaging surfaces **6323b** and **6326b** of the front engager **6320** are adjacent the leading edges of the wings of the fixed-wing aircraft **20a**; (4) operating the front engager servo motor **6345** (either manually or remotely via the R/C controller) to rotate the front engager **6320** to the attached rotational position such that the leading edge engaging surfaces **6323b** and **6326b** of the front engager **6320** contact the leading edges of the wings of the fixed-wing aircraft **20a**; and (5) operating the lock servo motor **6341** (either manually or remotely via the R/C controller) to rotate the lock arm **6346** into the front engager rotation-preventing rotational position so the locking extension **6346a** on the end of the lock arm **6346** engages the front engager arm lock device **6342a** of the front engager arm **6342**.

At this point the fixed-wing aircraft **20a** is attached to the saddle **300** (and the aircraft-launch apparatus **10**) because the front engager **6320** and the rear engagers **6360** engage the wings of the fixed-wing aircraft **20a** therebetween. The pivotable portions **6364** of the rear engagers **6360** are rotationally positioned relative to the bodies **6362** of the rear engagers **6360** such that the trailing-edge engaging surfaces **6362a** are not within the trailing-edge receiving channels of the pivotable portions **6364**. The positioning of the servo spacer **6344b** and the fact that the locking extension **6346a** is engaged to the front engager arm lock device **6342a** of the front engager arm **6342** ensure the front engager servo motor **6345** cannot rotate the front engager **6320** from the attached rotational position to the release rotational position. This prevents undesired release of the fixed-wing aircraft **20a** from the saddle **300** (and the aircraft-launch apparatus **10**).

Releasing the fixed-wing aircraft **20a** from the saddle **300** while the aircraft-launch apparatus **10** is airborne is a two-step process shown in FIGS. 4H and 4I. To release the fixed-wing aircraft **20a** from the saddle **300** (and the aircraft-launch apparatus **10**), the operator first remotely controls the lock servo motor **6341** (via the R/C controller) to rotate the lock arm **6346** into the front engager rotation-enabling rotational position, as shown in FIG. 4H. Second, the operator remotely controls the front engager servo motor **6345** (via the R/C controller) to rotate the front engager **6320** from the attached rotational position to the release rotational position, as shown in FIG. 4I. As the front engager servo motor **6345** rotates the front engager **6320** from the attached rotational position to the release rotational position, the first and second leading edge engaging surfaces **6323b** and **6326b** of the front engager **6320** rotate away from and begin to lose contact with the leading edge of the wing of the fixed-wing aircraft **20a**. As the front engager **6320** continues to rotate clear of the wings of the fixed-wing aircraft **20a**, the pivotable portions **6364** of the rear engagers **6360** enable the fixed-wing aircraft **20a** to freely pivot relative to the saddle

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base bracket **6310**, the first and second saddle side brackets **6312** and **6314**, and the bodies **6362** of the rear engagers **6360** as gravity pulls the fixed-wing aircraft **20a** downward. The center of gravity of the fixed-wing aircraft **20a** is positioned forward of the rear engagers. As this occurs, the trailing edge engaging surfaces **6362a** of the bodies **6362** of the rear engagers **6360** gradually enter the trailing-edge receiving channels of the pivotable portions **6364**. As this occurs, the trailing-edge engaging surfaces **6362a** contact the trailing edge of the wings and force them out of the trailing edge receiving channels, thus releasing the fixed-wing aircraft **20a** from the saddle **300** (and the aircraft-launch apparatus **10**) into free flight.

As the fixed-wing aircraft **20a** rotates downward, its empennage rises relative to the aircraft-launch apparatus **10** as the nose of the fixed-wing aircraft **20a** drops. The rear engagers are configured such that the trailing edges of the wings of the fixed-wing aircraft **20a** are forced out of the trailing edge receiving channels before the empennage of the fixed-wing aircraft **20a** contacts the aircraft-launch apparatus **10**.

In another embodiment, the rear engagers include an ejector device (not shown) having an ejector plate movable from a loaded position to an eject position (and vice-versa). The ejector plate is biased to the eject position via a spring or other suitable biasing element. In this embodiment, the act of clamping the wings of the fixed-wing aircraft between the front and rear engagers causes the trailing edges of the wings of the fixed-wing aircraft to contact the ejector plate and overcome the biasing force of the biasing element to move the ejector plate to the loaded position, and hold it there while the wings are clamped. During release, once the front engager rotates clear of the wings, the biasing element moves the ejector plate from the loaded position to the eject position. While this occurs, the ejector plate contacts the trailing edges of the wings and forces them away from the saddle **300**.

In the embodiment described above with respect to FIGS. **4A-4I**, the leading edge engagers of the front engager rotate in a plane generally parallel to a longitudinal axis of the fuselage of the fixed-wing aircraft to attach the fixed-wing aircraft to the saddle **300** and to release the fixed-wing aircraft from the saddle **300**. In another embodiment, the leading edge engagers of the front engager rotate in a plane generally perpendicular to the longitudinal axis of the fuselage of the fixed-wing aircraft to attach the fixed-wing aircraft to the saddle **300** and to release the fixed-wing aircraft from the saddle **300**. For example, the free ends of the leading edge engagers may rotate inward, toward the fuselage, to move from the release rotational position to the attached rotational position and may rotate outward, away from the fuselage, to move from the attached rotational position to the release rotational position.

In certain embodiments, the leading-edge engagers (and particularly the leading-edge engaging surfaces) are sized, shaped, arranged, and otherwise configured to force the nose of the fixed-wing aircraft downward during release.

As noted above, this embodiment of the saddle **300** may be sized, shaped, arranged, and otherwise configured to attach to and release any suitable fixed-wing aircraft by clamping its wings between front and rear engagers. An operator could—without changing any other components of the aircraft-launch apparatus **10**—swap out one saddle base bracket, front engager, and rear engager combination (or the entire saddle including those components) configured for one type of aircraft with another saddle base bracket, front engager, and rear engager combination (or the entire saddle

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including those components) configured for a different type of aircraft. This adds yet another layer of modularity to the aircraft-launch apparatus **10** and enables it to carry many different types of fixed-wing aircraft without requiring any modification of those fixed-wing aircraft.

In other embodiments, the saddle may be the saddle described in U.S. Patent Application Publication No. 2017/0158318, the entire contents of which are incorporated herein by reference. That saddle is configured to attach to the fixed-wing aircraft **20b** via a hook of the fixed-wing aircraft **20b** (or any other fixed-wing aircraft including a suitable hook).

1.2 Arm Modules

The arm modules **400a** to **400d** are mechanically attachable to and mechanically lockable to the hub module **200** and include locking assemblies that lock the arm modules **400a** to **400d** to the hub module **100**. FIGS. **5A-5E** show the first arm module **400a** and components thereof. The other arm modules **400b**, **400c**, and **400d** are similar to the first arm module **400a** and are therefore not separately shown or described.

As best shown in FIG. **5A**, the first arm module **400a** includes a generally rectangular elongated tubular arm **410a**, a generally rectangular tubular first arm extension **410b**, a generally rectangular second arm extension **410c**, a locking assembly **420**, and a male blind mate connector **431**.

The first arm extension **410b** is attached to the arm **410a** such that part of the first arm extension **410b** is disposed within the arm **410a** and the remainder of the first arm extension **410b** extends from the arm **410a**. Similarly, the second arm extension **410c** is attached to the arm **410a** such that part of the second arm extension **410c** is disposed within the arm **410a** and the remainder of the arm extension **410c** extends from the arm **410a**. The locking assembly **420** is attached to the underside of the arm **410a** near the end of the arm **410a** from which the first arm extension **410b** extends. The male blind mate connector **431** is attached to the end of the arm **410a** from which the arm extension **410b** extends.

As best shown in FIGS. **5C-5E**, the male blind mate connector **431**—along with its counterpart female blind mate connector **231a** of the hub module **100**—facilitate mechanical attachment of the first arm module **400a** to the hub module **100**. The male blind mate connector **431** includes a plurality of pins **431a** configured to mate with the pin receptacles of the female blind mate connector **231a**.

To attach the first arm module **400a** to the hub module **100**, an operator inserts the arm extension **410b** into the first arm module receiving socket **214a** of the hub module **100** and slides the first arm module **400a** toward the hub module **100** with enough force to mate the pins of the male blind mate connector **431** with the pin receptacles of the female blind mate connector **231a** of the hub module **100**.

As best shown in FIGS. **5B-5E**, the locking assembly **420** includes a drawcatch **420a** and a drawcatch lock **420b** that facilitate attaching the first arm module **400a** to the hub module **100**, lock the first arm module **400a** to the hub module **100**, and facilitate detaching the first arm module **400a** from the hub module **100**.

As best shown in FIG. **5B**, the drawcatch **420a** includes a base **421**, a lever **422**, a claw **423**, a first fastener **424** (such as a clevis pin or other suitable fastener), and a second fastener **425** (such as a clevis pin or other suitable fastener). The drawcatch lock **420b** includes a base **426**, a lock/release device **427** having a locking shelf **427a**, a pin **428** (or other suitable connector), and a compression spring **429** (or other suitable biasing element).

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The base **421** is attached to the underside of the arm **410a**. The lever **422** is pivotably connected at one end to the base **421** via the first fastener **424**. The other end of the lever **422** includes a handle **422a**. The claw **423** is pivotably connected at one end to the lever **422** via the second fastener **425**. The other end of the claw includes a latch plate engager **423a**.

The base **426** is attached to the underside of the arm **410a**. The lock/release device **427** is pivotably connected to the base **426** via the pin **428**. The compression spring **429** is disposed between the base **426** and the lock/release device **427** and retained in place via cavities and/or projections defined in or extending from these components (not shown).

The lock/release device **427** is rotatable about the pin **428** from a lock rotational position to a release rotational position. The compression spring **429** biases the lock/release device **427** to the lock rotational position. To rotate the lock/release device **427** from the lock rotational position to the release rotational position, the operator pushes the lock/release device **427** inward with enough force to overcome the spring-biasing force and compress the compression spring **429**.

The operator uses the locking assembly **420** to lock the male blind mate connector **431** with the female blind mate connector **231a** as follows. The operator rotates the handle **422a** of the lever **422** around the first fastener **424** toward the latch plate **237** on the hollow support **210a** of the hub module **100** and engages the claw engager **238** of the latch plate **237** with the latch plate engager **423a** of the claw **423**. The operator then rotates the handle **422a** around the first fastener **424** and toward the lock/release device **427** until the handle **422a** contacts the lock/release device **427**. Continued rotation of the lever **422** forces the lock/release device **427** inward, which overcomes the spring-biasing force and begins compressing the compression spring **429**. This causes the lock/release device **427** to being rotating to the release rotational position. Once the handle **422** rotates past the locking shelf **427a**, the spring-biasing force of the compression spring **429** causes the lock/release device **427** to rotate back to the lock rotational position. At this point, the locking shelf **427a** prevents the handle **422** from rotating back toward the latch plate **237**, and the first arm module **400a** and the hub module **100** are locked together.

In addition to using the locking assembly **420** to lock the first arm module **400a** to the hub module **100**, the operator can use the locking assembly **420** to facilitate mating the male blind mate connector **431** with the female blind mate connector **231a**. If the male blind mate connector **431** and the female blind mate connector **231a** are only partially mated (or not mated at all) and the latch plate engager **423a** of the claw **423** is engaged to the claw engager **238** of the latch plate **237**, rotating the handle **422a** of the lever **422** around the first fastener **424** toward the lock/release device **427** to lock the handle **422a** will pull the first arm module **400a** and the hub module **100** toward one another and cause the male blind mate connector **431** to mate with the female blind mate connector **231a**.

As shown in FIGS. 5C-5E, the operator reverses this process to unlock the first arm module **400a** from the hub module **100**. The operator pushes the lock/release device **427** inward with enough force to overcome the spring-biasing force and to compress the compression spring **429**, which causes the lock/release device **427** to rotate to the release rotational position. This frees the handle **422a** to rotate. Once the handle **422a** rotates past the locking shelf **427a**, the operator rotates the handle **422a** of the lever **422** around the first fastener **424** toward the latch plate **237** and

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disengages the latch plate engager **423a** of the claw **423** from the claw engager **238** of the latch plate **237**.

At this point, the operator can either physically pull the first arm module **400a** and the hub module **100** apart to separate the male and female blind mate connectors **431** and **231a** or use the locking assembly **420** to aid in detachment. When using the locking assembly **420** to aid in detachment, as shown in FIG. 5D, after disengaging the latch plate engager **423a** from the claw engager **238**, the operator continues rotating the handle **422a** toward the latch plate **237** until the latch plate engager **423a** contacts the backstop **239** of the latch plate **237**. Afterward, continued rotation of the handle **422a** toward the latch plate **237** causes the latch plate engager **423a** to impose a pushing force against the backstop **239**, which forces the first arm module **400a** and the hub module **100** apart.

1.3 Front Landing Gear Modules

FIG. 6 shows the first front landing gear module **600a**. The front landing gear modules (along with the rear landing gear modules, described below) support the aircraft launch apparatus **10** when assembled but not flying, and facilitate launch and landing of the aircraft launch apparatus **10** without damaging the aircraft launch apparatus **10**. The second front landing gear module **600b** is similar to the first front landing gear module **600a** and is therefore not separately shown or described.

The first front landing gear module **600a** includes a base **640a**, a generally cylindrical leg **620a** attached to and extending from the base **640a**, and a generally rectangular tubular arm module receiving arm **610a** attached to and extending from the base **640a**. The leg **620a** terminates in a generally semicircular foot **630a**. The arm module receiving arm **610a** defines an arm module receiving socket (not labeled) sized to receive the first arm module **400a**.

The operator attaches the first front landing gear module **600a** to the first arm module **400a** by inserting the free end of the second arm extension **410c** into the arm module receiving socket of the arm module receiving arm **610a** of the first front landing gear module **600a**. The operator then locks these two modules together, such as via suitable fasteners.

1.4 Rear Landing Gear Modules

FIG. 7 shows the first rear landing gear module **600c**. The rear landing gear modules (along with the front landing gear modules, described above) support the aircraft launch apparatus **10** when assembled but not flying, and facilitate launch and landing of the aircraft launch apparatus **10** without damaging the aircraft launch apparatus **10**. The rear landing gear modules are shaped such that they act as vertical stabilizers (or fins) during flight, ensuring that the front of the aircraft launch apparatus **10** (and the nose of the fixed-wing aircraft **20**, if attached thereto) points generally into the airflow when in flight. The second rear landing gear module **600d** is similar to the first rear landing gear module **600c** and is therefore not separately shown or described.

The first rear landing gear module **600c** includes a body **670c** having a streamlined cross-section that tapers from front to back. The body **670c** transitions at its bottom into a generally circular foot **680c**. A generally rectangular tubular arm module receiving arm **690c** is attached to and extends through the body **670c**.

The operator attaches the first rear landing gear module **600c** to the third arm module **400c** by inserting the free end of the third arm extension into the arm module receiving socket of the arm module receiving arm **690a** of the first rear landing gear module **600c**. The operator then locks these two modules together, such as via suitable fasteners.

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Once attached, the rear landing gear modules are oriented such that the side surfaces of the bodies of the rear landing gear modules are substantially aligned with the saddle side brackets **612** and **614** of the saddle **300**. When the fixed-wing aircraft **20a** is attached to the aircraft launch apparatus **10**, these side surfaces of the rear landing gear modules are substantially parallel to a plane containing the roll axis of the fuselage of the fixed-wing aircraft **20a**. The relatively long length of these side surfaces of the rear landing gear modules cause the rear landing gear module to act as fins in flight. This weather vane effect ensures that the nose of the fixed-wing aircraft **20a** is oriented into the airflow when airborne.

The landing gear height is chosen to maintain clearance between the ground and the belly of the fixed-wing aircraft after an aborted launch sequence.

2. Storage and Launch System

The storage and launch system **2000** is shown in FIGS. **8A-8E**. The storage and launch system **2000** is usable to compactly store the modular aircraft launch apparatus **10** after disassembly into the nine modules and to facilitate launch of the fixed-wing aircraft **20a** into free, wing-borne flight by acting as a launch mount for the fixed-wing aircraft **20a**.

The storage and launch system **2000** includes a container bottom **2100a** to which several mounting brackets are attached and a container top **2100b** configured to removably attach to the container bottom **2100a** (such as via latches or in any other suitable manner) to enclose the mounting brackets.

The container bottom **2100a** includes a first side wall **2110**; a second side wall **2120** opposite the first side wall **2110**; a front wall **2130** extending between the first and second side walls **2110** and **2120**; a back wall **2140** opposite the front wall **2130** and extending between the first and second side walls **2110** and **2120**; and a bottom wall **2150** extending between the first and second side walls **2110** and **2120**, respectively, and the front and back walls **2130** and **2140**, respectively. Together these walls define a cavity.

A first wheel **2160a** is mounted to the first side wall **2110** near the back wall **2140** via an axle **2162a** and one or more bearings (not shown) such that the first wheel **2160a** is rotatable relative to the container bottom **2100a**. Similarly, a second wheel **2160b** is mounted to the second side wall **2120** near the back wall **2140** via an axle **2162b** and one or more bearings (not shown) such that the second wheel **2160b** is rotatable relative to the container bottom **2100a**. Several feet **2170** extend from the bottom wall **2150**.

A launch-assist bracket **2200** is attached to the container bottom **2100a** and facilitates launch of the fixed-wing aircraft **20a** by orienting the fixed-wing aircraft **20a** in a desired launch orientation and retaining the fixed-wing aircraft **20a** in that orientation until the operator desires to launch the fixed-wing aircraft **20a**.

More specifically, the launch-assist bracket **2200** is attached to and extends between the first and second side walls **2110** and **2120** of the container bottom **2100a**. The launch-assist bracket **2200** facilitates launch of the fixed-wing aircraft **20a** by serving as a mount for the fixed-wing aircraft **20a** and constraining its movement once mounted to the launch-assist bracket **2200**. To this end, the launch-assist bracket **2200** includes a first aircraft engager **2210a** and a second aircraft engager **2210b** spaced apart from the first aircraft engager **2210a**.

The first aircraft engager **2210a** includes a first aircraft-engaging wall **2212a**, a second aircraft-engaging wall **2214a**, and a slide-preventing device **2216a**. The first air-

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craft-engaging wall **2212a** is generally planar and is downwardly angled relative to the bottom wall **2150** of the container bottom **2100a** in the direction of the back wall **2140** of the container bottom **2100a** to the front wall **2130** of the container bottom **2100a**. The second aircraft-engaging wall **2214a** is connected to (such as integrally formed with) and generally perpendicular to the first aircraft-engaging wall **2212a**. The slide-preventing device **2216a**, here a screw, extends through the first aircraft-engaging wall **2212a** such that part of the slide-preventing device **2216a** protrudes above a top surface (not labeled) of the first aircraft-engaging wall **2212a**.

Similarly, the second aircraft engager **2210b** includes a first aircraft-engaging wall **2212b**, a second aircraft-engaging wall **2214b**, and a slide-preventing device **2216b**. The first aircraft-engaging wall **2212b** is generally planar and is downwardly angled relative to the bottom wall **2150** of the container bottom **2100a** in the direction of the back wall **2140** of the container bottom **2100a** to the front wall **2130** of the container bottom **2100a**. The second aircraft-engaging wall **2214b** is connected to (such as integrally formed with) and generally perpendicular to the first aircraft-engaging wall **2212b**. The slide-preventing device **2216b**, here a screw, extends through the first aircraft-engaging wall **2212b** such that part of the slide-preventing device **2216b** protrudes above a top surface (not labeled) of the first aircraft-engaging wall **2212b**.

In preparation for launch, the operator rests first and second launch-assist elements that extend below the wings of the fixed-wing aircraft **20a** on the first aircraft-engaging walls **2212a** and **2212b** of the first and second aircraft engagers **2210a** and **2210b**, respectively. The operator then enables the fixed-wing aircraft **20a** to slide down the first aircraft-engaging walls **2212a** and **2212b** (due to their sloped orientation) until the first and second launch-assist elements engage the slide-preventing devices **2216a** and **2216b** of the first and second aircraft engagers **2210a** and **2210b**, respectively. The slide-preventing devices **2216a** and **2216b** prevent the fixed-wing aircraft **20a** from sliding off of the first aircraft-engaging walls **2212a** and **2212b**, and thus retain the fixed-wing aircraft **20a** in the desired launch orientation.

To facilitate storage of the aircraft launch apparatus **10** in a single container (including the container top **2100b** and the container bottom **2100a**), the container bottom **2100a** includes first, second, third, and fourth mounting brackets **2300**, **2400**, **2500**, and **2600** at least partially positioned within the cavity defined by the container bottom **2100a**. The arm modules **400a-400d** and the front and rear landing gear modules **600a-600d** are mounted to these mounting brackets for storage.

The storage and launch apparatus includes an engine cooling module configured to force cooling airflow into the front of the aircraft engine during preflight. This enables the fixed-wing aircraft operator to perform complete engine run-up health checks and achieve thermal equilibrium of the fixed-wing aircraft engine prior to lift off.

3. Anchor System

The anchor system **3000** and components thereof is shown in FIGS. **9A-9H** and **10A-10D**. The anchor system **3000** is usable along with the rotorcraft **30**, the flexible capture member **5000** (described below), and the aircraft-landing device **8000** (described below) to retrieve the fixed-wing aircraft **20a** from free, wing-borne flight. Generally, the components of the anchor system **3000** operate together to impose a regulated force on the flexible capture member **5000** during the fixed-wing aircraft retrieval process. This

means that the anchor system **3000** is configured to regulate—i.e., maintain substantially constant—the tension in the flexible capture member **5000** while the rotorcraft **30** is station-keeping relative to the anchor system **3000** in preparation for retrieval of the fixed-wing aircraft **20a**. This simplifies the rotorcraft operation during the fixed-wing aircraft retrieval process by eliminating the need for the rotorcraft operator to control the tension in the flexible capture member **5000**. The rotorcraft operator simply climbs and maintains a constant hover height, that is deliberately less than the length of the paid out flexible capture member.

The anchor system **3000** includes an anchor system base **3100**, a first mounting bracket **3200**, a second mounting bracket **3300**, a separator bracket **3400**, and a flexible capture member payout and retract system (not labeled). The flexible capture member payout and retract system includes a drum assembly **3500**, a level wind system **3600**, a transition assembly **3700**, and a hydraulic system **7300**.

3.1 Anchor System Base and Brackets

The anchor system base **3100** serves as a mount for certain other elements of the anchor system **3000**. As best shown in FIGS. 9A-9E, the anchor system base **3100** includes two spaced-apart, generally parallel sides **3102** and **3104** and a top **3106** transverse (such as generally perpendicular) to, extending between, and connecting the sides **3102** and **3104**. As best shown in FIG. 9C, the top **3106** includes a surface **3106a** that defines a GPS antenna mounting opening through the top **3106** and a surface **3106b** that defines a lower sealing and mounting component opening through the top **3106**. The GPS antenna **3800** is attached to a mounting bracket (not labeled) that extends between the sides **3102** and **3104** such that the GPS antenna **3800** extends through the GPS antenna mounting opening of the top **3106**. As described below, a lower sealing and mounting component **8500** of the aircraft-landing device **8000** is attachable to the top **3106** of the anchor system base **3100** via the lower sealing and mounting component mounting opening to attach the aircraft-landing device **8000** to the anchor system base **3100**.

The first and second mounting brackets **3200** and **3300** serve as mounts for the drum assembly **3500** and part of the hydraulic system **7300**. As best shown in FIGS. 9D and 9E, the first and second mounting brackets **3200** and **3300** are generally planar and include respective cylindrical surfaces **3200a** and **3300a** that respectively define first and second mounting openings through the first and second mounting brackets **3200** and **3300**. The first mounting bracket **3200** is attached to the first side **3102** of the anchor system base **3100** via suitable fasteners (not shown), and the second mounting bracket **3300** is attached to the second side **3104** of the anchor system base **3100** via suitable fasteners (not shown). The separator bracket **3400** is attached to and extends between the first and second mounting brackets **3200** and **3300** via suitable fasteners (not shown) to maintain the spacing between these components.

3.2 Drum Assembly

The flexible capture member **5000** may be wound onto and off of the drum assembly **3500**. As best shown in FIG. 9G, the drum assembly **3500** includes a drum **3510** having a cylindrical exterior surface **3510a** and a cylindrical interior surface **3510b**; a first drum flange **3512** having a circular exterior surface **3512a**, a circular interior surface **3512b**, a cylindrical perimeter surface **3512c**, and a cylindrical mounting surface **3512d** that defines a mounting opening through the first flange **3512**; a second drum flange **3514** having a circular exterior surface **3514a**, a circular interior surface **3514b**, a cylindrical perimeter surface **3514c**, and a

cylindrical mounting surface **3514d** that defines a mounting opening through the second flange **3514**; a drum shaft **3520**; a coupler **3532** including a tubular coupler shaft **3532a** defining a shaft-receiving bore therethrough and a coupler flange **3532b** extending radially outwardly from the coupler shaft **3532a**; a first annular flange **3534**; a second annular flange **3536**; and a third annular flange **3537**.

The first and second drum flanges **3512** and **3514** are fixedly attached to opposing longitudinal ends (not labeled) of the drum **3510** via fasteners (not shown) such that the interior surface **3510b** of the drum **3510** and the interior surfaces **3512b** and **3514b** of the first and second drum flanges **3512** and **3514** define a cylindrical inner drum cavity (not labeled).

The coupler flange **3532b** and the first annular flange **3534** are fixedly attached to one another and to the first drum flange **3512** via fasteners (not shown) such that: (1) the coupler flange **3532b** contacts the exterior surface **3512a** of the first drum flange **3512**; (2) the first annular flange **3534** is within the inner drum cavity and contacts the interior surface **3512b** of the first drum flange **3512**; (3) the coupler flange **3532b** and the first annular flange **3534** sandwich part of the first drum flange **3512** therebetween; and (4) a first portion of the coupler shaft **3532a** is within the inner drum cavity while a second portion of the coupler shaft **3532a** is outside of the inner drum cavity.

The second annular flange **3536** and the third annular flange **3538** are fixedly attached to one another and to the second drum flange **3514** via fasteners (not shown) such that: (1) the third annular flange **3538** contacts the exterior surface **3514a** of the second drum flange **3514**; (2) the second annular flange **3536** is within the inner drum cavity and contacts the interior surface **3514b** of the second drum flange **3514**; and (3) the second annular flange **3536** and the third annular flange **3538** sandwich part of the second drum flange **3514** therebetween.

The drum shaft **3520** extends across the inner drum cavity such that a first end **3520a** of the drum shaft **3520** is received in the shaft-receiving bore defined through the coupler shaft **3532a** and a second end **3520b** of the drum shaft **3520** is outside of the inner drum cavity. The drum shaft **3520** is coupled to the coupler **3532** in any suitable manner such that the drum shaft **3520** is substantially axially fixed (i.e., cannot substantially move axially) relative to the coupler **3532** and such that the drum shaft **3520** and the coupler **3532** rotate together about the longitudinal axis of the drum shaft **3520**. That is, the drum shaft **3520** and the coupler **3532** are coupled such that rotation of the drum shaft **3520** causes the coupler **3532** to rotate, and vice-versa. In this embodiment, this coupling is achieved via a fastener (not shown) threadably received by the coupler **3532** and the drum shaft **3520**. This fixedly attaches the coupler **3532** and the drum shaft **3520**. In other embodiments, the drum shaft is keyed to the coupler (or vice-versa) such that they rotate together. In other embodiments, retaining rings, pins, clips, or other elements axially fix the drum shaft relative to the coupler.

The drum shaft **3520** is mounted to the second mounting bracket **3300**. Specifically, the second end **3520b** of the drum shaft **3520** extends through the second mounting opening defined through the second mounting bracket **3300** and is received in a drum shaft flange bearing **3910** attached to the second mounting bracket **3300**. This enables the drum shaft **3520** to rotate about its longitudinal axis relative to the second mounting bracket **3300**. The drum shaft **3520** is mounted to the first mounting bracket **3200** via the below-

described coupling of the coupler **3532** and a motor output shaft **7358a** of a hydraulic motor **7358** of the hydraulic system **7300**.

3.3 Level Wind System

The level wind system **3600** ensures that the flexible capture member **3600** is wound onto (and off of) the drum **3510** in a generally uniform manner. As best shown in FIG. 9F, the level wind system **3600** includes a level wind shaft **3610**, a first traveler **3620**, a second traveler **3630**, a guide shaft **3640**, a first pulley **3650**, a second pulley **3660**, and a belt **3670**.

The first and second travelers **3620** and **3630** are slidably mounted to the level wind shaft **3610** in a spaced-apart fashion such that their respective guide elements (not shown) are received in channels (not labeled) defined in the exterior surface of the level wind shaft **3610** around its circumference. The arrangement and shape of these grooves define how far and how fast the first and second travelers **3620** and **3630** slide back and forth relative to the level wind shaft **3610** as the level wind shaft **3610** rotates. The first and second travelers **3620** and **3630** are also slidably mounted to the guide shaft **3640** to prevent the first and second travelers **3620** and **3630** from about the longitudinal axis of the level wind shaft **3610**.

The level wind shaft **3610** is mounted to the sides **3102** and **3104** of the anchor system base **3100**. More specifically, the ends of the level wind shaft **3610** are received in respective level wind shaft flange bearings (not labeled) attached to the sides **3102** and **3104** of the anchor system base **3100** such that the level wind shaft **3610** can rotate about its longitudinal axis relative to the sides **3102** and **3104** of the anchor system base **3100**. Similarly, the guide shaft **3640** is mounted to the sides **3102** and **3104** of the anchor system base **3100**. More specifically, the ends of the guide shaft **3640** are received in respective guide shaft flange bearings (not labeled) attached to the sides **3102** and **3104** of the anchor system base **3100** such that the guide shaft **3640** can rotate about its longitudinal axis relative to the sides **3102** and **3104** of the anchor system base **3100**.

The first pulley **3650** is mounted to and coupled to the level wind shaft **3610** in any suitable manner such that the first pulley **3650** is substantially axially fixed (i.e., cannot substantially move axially) relative to the level wind shaft **3610** and such that the first pulley **3650** and the level wind shaft **3610** rotate together about the longitudinal axis of the level wind shaft **3610**. That is, the first pulley **3650** and the level wind shaft **3610** are coupled such that rotation of the first pulley **3650** causes the level wind shaft **3610** to rotate, and vice-versa. In this embodiment, this coupling is achieved via a fastener (not shown) threadably received by the first pulley **3650** and the level wind shaft **3610**. This fixedly attaches the first pulley **3650** to the level wind shaft **3610**. In other embodiments, the level wind shaft is keyed to the first pulley (or vice-versa) such that they rotate together. In other embodiments, retaining rings, pins, clips, or other elements axially fix the first pulley relative to the level wind shaft.

As best shown in FIG. 9G, the second pulley **3660** is mounted to and coupled to the drum shaft **3520** in any suitable manner such that the second pulley **3660** is substantially axially fixed (i.e., cannot substantially move axially) relative to the drum shaft **3520** and such that the second pulley **3660** and the drum shaft **3520** rotate together about the longitudinal axis of the drum shaft **3520**. That is, the second pulley **3660** and the drum shaft **3520** are coupled such that rotation of the drum shaft **3520** causes the second pulley **3660** to rotate, and vice-versa. In this embodiment,

this coupling is achieved via a fastener (not shown) threadably received by the second pulley **3660** and the drum shaft **3520**. This fixedly attaches the second pulley **3660** to the drum shaft **3520**. In other embodiments, the drum shaft is keyed to the second pulley (or vice-versa) such that they rotate together. In other embodiments, retaining rings, pins, clips, or other elements axially fix the second pulley relative to the drum shaft.

The belt **3670** fits around and operatively connects the first and second pulleys **3650** and **3660** such that rotation of one of the pulleys causes the other to rotate.

In operation, as the drum shaft **3520** of the drum assembly **3500** rotates, the second pulley **3660** rotates therewith. Rotation of the second pulley **3660** causes the first pulley **3650** to rotate due to their connection via the belt **3670**. Rotation of the first pulley **3650** causes the level wind shaft **3610** to rotate. Rotation of the level wind shaft **3610** causes the first and second travelers **3620** and **3630** to slide relative to the level wind shaft **3610** due to their guide elements being received in the grooves defined in the level wind shaft **3610**. This sliding of the first and second travelers **3620** and **3630** (which is keyed to rotation of the drum shaft **3520**) guides placement of the flexible capture member **5000** as it is wound onto (or off of) the drum **3510**.

3.4 Transition Assembly

The transition assembly **3700** is configured to route the flexible capture member **5000** from the aircraft-landing device **8000** to the level wind system **3600**. As best shown in FIG. 9C, the transition assembly **3700** includes a first transition assembly housing portion **3710**, a second transition assembly housing portion **3720**, a transition pulley **3730**, and a fastener **3740**. The first and second transition assembly housing portions **3710** and **3720** are attachable to one another via the fastener **3740**, and together define a transition pulley cavity and a flexible capture member receiving bore in fluid communication with the transition pulley cavity. The transition pulley **3730** is rotatably mounted on a spindle (not labeled) within the transition pulley cavity such that the transition pulley **3730** can rotate relative to the first and second transition assembly housing portions **3710** and **3720**. As described in detail below, the transition assembly **3700** is attachable to the lower sealing and mounting component **8500**, which in turn is slidably receivable on the anchor system base **3100**.

3.5 Hydraulic System

The hydraulic system **7300** is configured to regulate the tension in the flexible capture member **5000** during the fixed-wing aircraft retrieval process. As best shown in FIGS. 10A-10D, the hydraulic system **7300** includes an electric hydraulic pump **7350** (such as one of the PU-Series Hydraulic Economy Electric Pumps sold by Enerpac) having an inlet port and an outlet port, an accumulator **7352** (such as the Piston-Style Hydraulic Accumulator #6716K51 sold by McMaster-Carr) having an inlet/outlet port, a pressure relief valve **7356** (such as the Adjustable Stainless Steel Relief Valve #5027K11 sold by McMaster-Carr) having an inlet port and an outlet port, the hydraulic motor **7358** (such as the Pilot Flange Mount J Series Hydraulic Motor #SPZL3 sold by Grainger) having an inlet port and an outlet port, a hydraulic fluid tank **7362** (such as that included in one of the PU-Series Hydraulic Economy Electric Pumps sold by Enerpac) having an inlet port and an outlet port, and a pressure switch **7364** (such as the Extended-Life Pressure Switch #4735K46 sold by McMaster-Carr).

The hydraulic motor **7358** is attached to the first mounting bracket **3200** such that the motor output shaft **7358a** extends through the first mounting opening defined through the first

mounting bracket 3200 and is received in the shaft-receiving bore defined through the coupler shaft 3532a of the coupler 3532. The motor output shaft 7358a is coupled to the coupler 3532 in any suitable manner such that the motor output shaft 7358a and the coupler 3532 rotate together. That is, the motor output shaft 7358a and the coupler 3532 are coupled such that rotation of the motor output shaft 7358a causes the coupler 3532 to rotate, and vice-versa. In this embodiment, the motor output shaft 7358a is keyed to the coupler 3532.

The remaining components of the hydraulic system 7300 are attached to each other; the container housing the anchor system 3000; and/or the anchor base 3100, the first mounting bracket 3200, or the second mounting bracket 3300.

The inlet port of the electric hydraulic pump 7350 is in fluid communication with the outlet port of the tank 7362, and the outlet port of the electric hydraulic pump 7350 is in fluid communication with the inlet/outlet port of the accumulator 7352, the inlet port of the pressure relief valve 7356, and the inlet port of the hydraulic motor 7358. The inlet port of the hydraulic motor 7358 is in fluid communication with the inlet port of the pressure relief valve 7356. The outlet port of the hydraulic motor 7358 is in fluid communication with the outlet port of the pressure relief valve 7356 and the inlet port of the tank 7362. In this embodiment, these components are in fluid communication with one another via suitable flexible or rigid tubing (not shown), though any suitable lines, hoses, or tubing may be used to fluidically connect these components. The hydraulic system 7300 also includes various fittings and connectors (not shown) that facilitate fluidically connecting these components. These fittings and connectors are well-known in the art and are not described herein for brevity.

When electrically connected to a power source and powered on, the electric hydraulic pump 7350 draws hydraulic fluid (such as oil or any other suitable fluid) from the tank 7362 and through its inlet port and pumps the hydraulic fluid out of its outlet port at a pump outlet pressure (800 psi in this example embodiment).

In certain situations, as explained below, the accumulator 7352 receives hydraulic fluid at its inlet/outlet and stores hydraulic fluid at a particular pressure to reduce pressure switch chatter (as described below). The accumulator gas charge is preloaded to the pressure switch lower set point (650 psi in this example embodiment, as described below) to minimize pressure switch chatter frequency.

The pressure switch is configured to measure the pressure of hydraulic fluid at the accumulator 7352. The pressure switch 7364 selectively connects the electric hydraulic pump 7350 to a power source 7400 based on the pressure P1 of hydraulic fluid at the accumulator 7352. The pressure switch measures P1 and: (1) electrically connects the power source 7400 and the electric hydraulic pump 7350 when P1 is less than a pressure switch lower set point (650 psi in this example embodiment); and (2) electrically disconnects the power source 7400 and the electric hydraulic pump 7350 when P1 is greater than or equal to a pressure switch upper set point (800 psi in this example embodiment). The combination of the accumulator 7352 and the pressure switch 7364 ensures that the electric hydraulic pump 7350 only operates as needed to maintain the pressure of the hydraulic fluid in the accumulator 7352.

The pressure relief valve 7356 receives hydraulic fluid at its inlet port and prevents the hydraulic fluid from exiting its outlet port until the pressure of the hydraulic fluid reaches a pressure relief valve set point (850 psi in this example embodiment). In other words, the pressure relief valve 7356 is movable between a closed configuration in which the

pressure relief valve 7356 prevents the hydraulic fluid from flowing from its inlet port to its outlet port and an open configuration in which the pressure relief valve 7356 enables the hydraulic fluid to flow from its inlet port to its outlet port.

The pressure relief valve 7356 is biased to the closed configuration, and moves to the open configuration when the pressure of the hydraulic fluid reaches the pressure relief valve set point.

Depending on the scenario, the hydraulic motor 7358 receives hydraulic fluid at either its inlet port from the electric hydraulic pump 7350 or its outlet port from the pressure relief valve 7356. When the hydraulic motor 7358 receives hydraulic fluid at its inlet port from the electric hydraulic pump 7350, the hydraulic fluid flows through the hydraulic motor 7358 and exits its outlet port. The flow of the hydraulic fluid in this direction causes the output shaft of the hydraulic motor 7358 to rotate in a direction that, as described below, causes the flexible capture member to wrap around the drum 3510. On the other hand, when excessive force on the flexible capture member 5000 forces the drum 3510 to rotate in a manner that enables flexible capture member payout, the hydraulic motor 7358 receives hydraulic fluid at its outlet port from the pressure relief valve 7356, and the hydraulic fluid flows through the hydraulic motor 7358 and exits its inlet port. The flow of the hydraulic fluid in this direction is intentionally lossy, forming an energy sink for the kinetic energy of the aircraft being captured.

3.5.1 Flexible capture member haul-in phase

FIG. 10A is a schematic block diagram of part of the hydraulic system 7300 during the flexible capture member haul-in phase (sometimes called the “haul-in phase” for brevity) of the fixed-wing aircraft retrieval process. The haul-in phase is defined for the purposes of this section as occurring when the force F_{DRUM} the drum 3510 imposes on the flexible capture member (via the torque the hydraulic motor 7358 exerts on the coupler 3532) exceeds any force $F_{OPPOSING}$ imposed on the flexible capture member 5000 that opposes F_{DRUM} (such as when the flexible capture member is slack below a recently captured fixed-wing aircraft or when the multicopter is descending following capture of the fixed-wing aircraft).

During the haul-in phase, the pressure P1 of the hydraulic fluid at the accumulator 7352 is or falls below the 650 psi pressure switch lower set point. Accordingly, the pressure switch 7364 electrically connects the electric hydraulic pump 7350 to the power source 7400. The electric hydraulic pump 7350 draws hydraulic fluid from the tank 7362 and pumps the hydraulic fluid at the pump outlet pressure to the inlet/outlet port of the hydraulic accumulator 7352, the inlet port of the pressure relief valve 7356, and the inlet port of the hydraulic motor 7358.

Since at this point the pressure P1 of the hydraulic fluid at the accumulator 7352 is less than the 800 psi pressure switch upper set point, the pressure switch 7364 continues electrically connecting the electric hydraulic pump 7350 to the power source 7400 throughout the haul-in phase.

Since the pressure P1 at the accumulator 7352 is less than the 850 psi pressure relief valve set point, the pressure relief valve 7356 prevents the hydraulic fluid from flowing through it.

The hydraulic fluid instead flows through the hydraulic motor 7358 and exits the outlet port of the hydraulic motor 7358. The flow of the hydraulic fluid through the hydraulic motor 7358 in this direction (i.e., from inlet port to outlet port) causes the output shaft of the hydraulic motor 7358 to exert a counter-clockwise (from the viewpoint of FIG. 10A) torque on the coupler 3532, which transmits that torque to

the drum shaft 3520, which transmits that torque to the drum flanges 3512 and 3514, which transmits that torque to the drum 3510. This torque imposes a force F_{DRUM} on the flexible capture member 5000 via the drum 3510. Since the force $F_{OPPOSING}$ on the flexible capture member 5000 is less than F_{DRUM} , the torque the hydraulic motor 7358 exerts on the coupler 3532 causes the drum 3510 to rotate counter-clockwise (from the viewpoint of FIG. 10A) relative to the anchor system base 3100. This causes the flexible capture member 5000 to wrap around the drum 3510 (and decrease the amount of flexible capture member 5000 extending between the drum 3510 and the multicopter 10)).

The hydraulic fluid flows from the outlet port of the hydraulic motor 7358 to the inlet port of the tank 7362.

In this example embodiment, the components and set points are sized, shaped, arranged, set, or otherwise configured such that F_{DRUM} is about 80 pounds during the haul-in phase.

3.5.2 Neutral Phase

FIGS. 10B and 10C are schematic block diagrams of part of the hydraulic system 7300 during the flexible capture member neutral phase (sometimes referred to as the “neutral phase” for brevity) of the fixed-wing aircraft retrieval process. The neutral phase is defined for the purposes of this section as occurring when the force F_{DRUM} the drum 3510 imposes on the flexible capture member (via the torque the hydraulic motor 7358 exerts on the coupler 3532) equals a force $F_{OPPOSING}$ imposed on the flexible capture member 5000 that opposes F_{DRUM} (such as when the multicopter is station-keeping above the anchor system in preparation for fixed-wing aircraft retrieval).

During the neutral phase, the drum 3510 does not rotate relative to the anchor system base 3100. Even so, hydraulic fluid leaks through the hydraulic motor 7358 and drains into the tank 7362. The accumulator 7352 eliminates the need to constantly run the electric hydraulic pump 7350 during the neutral phase in response to this leakage and ensure F_{DRUM} remains constant to regulate the tension in the flexible capture member 5000.

As shown in FIG. 10B, once $F_{OPPOSING}$ equals F_{DRUM} , the electric hydraulic pump 7350 continues to operate because P1 is less than the 650 psi pressure switch lower set point. But since hydraulic fluid flow through the hydraulic rotor 7358 has been reduced to mere leakage, pressure P1 begins to build and the accumulator 7352 begins charging. As shown in FIG. 10C, once the pressure P1 reaches the 800 psi pressure switch upper set point, the accumulator 7352 is charged and the pressure switch 7364 electrically disconnects the electric hydraulic pump 7350 from the power source 7400. The accumulator 7352 begins discharging to replenish the hydraulic fluid leaking through the hydraulic motor 7358. Once the pressure P1 falls below the 650 psi pressure switch lower set point, the pressure switch 7364 electrically connects the electric hydraulic pump 7350 to the power source 7400 to again charge the accumulator 7352. The use of the accumulator 7352 and the pressure switch 7364 therefore ensures that leakage through the hydraulic motor 7358 is accounted for and that F_{DRUM} will not decrease as hydraulic fluid leaks through the hydraulic motor 7358.

In this example embodiment, the components and set points are sized, shaped, arranged, set, or otherwise configured such that F_{DRUM} is about 80 pounds during the neutral phase.

3.5.3 Flexible Capture Member Payout Phase

FIG. 10D is a schematic block diagram of part of the hydraulic system 7300 during the flexible capture member

payout phase (sometimes referred to as the “payout phase” for brevity) of the fixed-wing aircraft retrieval process. The payout phase is defined for the purposes of this section as occurring when the force F_{DRUM} the drum 3510 imposes on the flexible capture member (via the torque the hydraulic motor 7358 exerts on the coupler 3532) is less than a force $F_{OPPOSING}$ imposed on the flexible capture member 5000 that opposes F_{DRUM} (such as when the multicopter is climbing to prepare for fixed-wing aircraft retrieval or just after the fixed-wing aircraft captures and begins to deflect the flexible capture member).

During the payout phase, $F_{OPPOSING}$ causes the drum 3510 to spin clockwise (from the viewpoint of FIG. 10D) and pay out flexible capture member 5000 wrapped around the drum 3510 (and increase the amount of flexible capture member 5000 extending between the drum 3510 and the multicopter 10). This clockwise spinning of the drum 3510 forces hydraulic fluid to flow into the outlet port of the hydraulic motor 7358, through the hydraulic motor 7358, and exit the inlet port of the hydraulic motor 7358. Since hydraulic fluid cannot enter the outlet port of the electric hydraulic pump 7350, this causes the pressure P1 of the hydraulic fluid at the accumulator 7352 to increase. Once the pressure P1 reaches the 850 psi pressure relief valve set point, the pressure relief valve 7356 enables hydraulic fluid to flow through it. This causes hydraulic fluid to flow from the inlet port of the hydraulic motor 7358 to the inlet port of the pressure relief valve 7356 and from the outlet port of the pressure relief valve 7356 to the outlet port of the hydraulic motor 7358 until the drum 3510 stops rotating clockwise (from the viewpoint of FIG. 10D) and P1 drops below the 850 psi pressure relief valve set point.

During the payout phase, hydraulic fluid does not necessarily drain to the tank 7362, and the electric hydraulic pump 7350 thus doesn't need to replenish any drained hydraulic fluid. This means that P1 will not drop below the 650 psi pressure switch lower set point, and the pressure switch 7364 electrically disconnects the electric hydraulic pump 7350 from the power source 7400 during most (if not all) of the payout phase.

Accordingly, the relative positioning and configuration of the components of the hydraulic system enable the hydraulic motor to spin in either direction while maintaining torque on the drum shaft in the desired direction (counter-clockwise in the embodiment show in FIGS. 10A-10D) to maintain F_{DRUM} on the flexible capture member.

In this example embodiment, F_{DRUM} is controlled by the pressure relief valve set point (the higher the set point, the higher FORUM) and friction. In this example embodiment, F_{DRUM} is about 85 pounds during the payout phase (i.e., greater than FORUM in the haul-in and neutral phases).

4. Aircraft-Landing Device

Controlling the multicopter 10 post-capture to lower the fixed-wing aircraft 20a to the ground (or another non-compliant structure) risks damaging the fixed-wing aircraft 20a. For instance, the multicopter 10 could descend too quickly or stall while descending and drop, causing the fixed-wing aircraft 20a to impact the ground at high speed. Even a slow and well-controlled descent of the multicopter 10 could coincide with poorly timed pendulum swing of the fixed-wing aircraft 20a, resulting in damage when the fixed-wing aircraft 20a touches down on the surface.

In certain situations, a compliant aircraft-landing device 8000 is employed to gently receive the fixed-wing aircraft 20a post-capture and hold it in place above the ground (or other non-compliant surface) in a generally secure manner to facilitate retrieval at a later point. The use of this compliant

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aircraft-landing device **8000** minimizes potential impact damage to the fixed-wing aircraft **20a** and enables the multicopter **10** to land the fixed-wing aircraft **20a** on the aircraft-landing device **8000** and then land itself a safe distance away.

FIGS. 11A-11M illustrate one example embodiment of the aircraft-landing device **8000** and its components, which include: an inflatable aircraft-supporting body **8100**; multiple gussets **8105**; a tubular spacer guide **8110**; spaced-apart cylindrical inflatable supports **8200a**, **8200b**, **8200c**, and **8200d**; a guiding assembly **8300** including a spacer **8310** and an upper guiding component **8400** and an intermediate guiding component **8500** attached to the spacer **8310**; an inflation device **8600**; a deflation device **8700**; and a lower guiding and mounting component **8800**.

The aircraft-supporting body **8100** is formed from one or more pieces of fabric material (such as nylon, polyester, dacron, vinyl, or other composite laminate sheets) that are stitched, adhered, or otherwise fastened together in an airtight manner to generally form a frustoconical shape when inflated. The gussets **8105** and the tubular spacer guide **8110** are made of similar material. As best shown in FIGS. 11E-11G, the tubular spacer guide **8110** is attached to the aircraft-supporting body **8100** in a suitable manner (such as via stitching or adhesive) near its top and extends from there into the interior of the aircraft-supporting body **8100**. The gussets **8105** are attached to and extend radially between the spacer guide **8110** and an inner surface **8100a** of the aircraft-supporting body **8100**. These gussets **8105** and the spacer guide **8110** assist in maintaining the guiding assembly **8300** upright when the aircraft-supporting body **8100** is inflated.

Each support **8200a-8200d** is formed from one or more pieces of material (such as any of those listed above) that are stitched, adhered, or otherwise fastened together in an airtight manner to generally form cylinders when inflated. The supports are attached to the underside of the aircraft-supporting body **8100** via stitching, adhesive, or any other suitable manner. The interiors of the supports **8200a-8200d** are in fluid communication with the interior of the aircraft-supporting body **8100** to enable fluid (e.g., air) to flow among these components. This enables the aircraft-supporting body **8100** and the supports **8200a-8200d** to be inflated via a single inflator attached to the inflation device **8600**. The supports **8200a-8200d** have ballast weights, also referred herein as dumbbells **8205a-8205d**, respectively attached thereto. The dumbbells **8204a-8204d** add weight to the supports **8200a-8200d** to help maintain the aircraft-landing device **8000** upright as the fixed-wing aircraft **20a** contacts the flexible capture member **5000**, as described below. The dumbbells may be replaced with any suitable components that add weight to the supports. In one embodiment, the supports are partially filled with material, such as sand, to weigh them down. In other embodiments, stakes are used to anchor the supports to the ground instead of or in addition to weighted elements.

As best shown in FIGS. 11E-11G, the spacer **8310** of the guiding assembly **8300** extends through the spacer guide **8110** such that a first end **8310a** of the spacer **8310** is external to the aircraft-supporting body **8100** and an opposing second end **8310b** of the spacer **8310** is inside of the interior of the aircraft-supporting body **8100**. Hose clamps (not labeled) or any other suitable devices clamp the upper portion **8100a** of the aircraft-supporting body **8100** and the spacer guide **8110** to the exterior cylindrical surface **8310c** of the spacer **8310** to attach these components to one another. The spacer **8310** includes a cylindrical interior surface **8310d** that defines a flexible capture member receiv-

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ing bore. The upper guiding component **8400** is attached to the first end **8310a** of the spacer **8310** via suitable fasteners, and the intermediate guiding component **8500** is attached to the second end **8310b** of the spacer **8310** via suitable fasteners.

As best shown in FIGS. 11H and 11I, the upper guiding component **8400** includes a tubular body **8410**, a tubular mounting element **8420**, lower and upper roller bearings **8430a** and **8430b**, a retaining element **8440**, a needle bearing supporter **8450**, and multiple needle bearings **8460**.

The body **8410** defines a cylindrical interior surface **8412** that forms a flexible capture member receiving bore there-through. The mounting element **8420** surrounds part of the body **8410**. The upper roller bearing **8430b** surrounds part of the body **8410** and is positioned between an upper surface (not labeled) of the mounting element **8420** and a lip (not labeled) of the body **8410**. The lower roller bearing **8430a** surrounds part of the body **8410** and is positioned between a lower surface (not labeled) of the mounting element **8420** and the retaining element **8440**, which is disposed within a channel defined around the circumference of the body **8410**. The retaining element **8440** retains the body **8410**, the mounting element **8420**, and the roller bearings **8430a** and **8430b** in place relative to one another. The needle bearing supporter **8450** is attached to the body **8410** via fasteners, and the needle bearings **8460** are rotatably attached to the needle bearing supporter **8450** such that they can rotate relative to the needle bearing supporter **8450**.

The mounting element **8420** of the upper guiding component **8400** is fixedly attached to the first end **8310a** of the spacer **8310** of the guiding assembly **8300** via one or more fasteners. After attachment, the roller bearings **8430a** and **8430b** enable the body **8410** and the attached needle bearing supporter **8450** and needle bearings **8460** to rotate together about the longitudinal axis of the body **8410** relative to the mounting element **8420** and the guiding assembly **8300**.

As best shown in FIGS. 11J and 11K, the intermediate guiding component **8500** includes a body **8510** having an inner surface **8512**. Moving from top to bottom in FIG. 11K, the inner surface **8512** tapers radially inwardly into a cylindrical shape and then tapers back radially outwardly. The inner surface **8512** defines a flexible capture member receiving bore. The body **8510** is fixedly attached to the second end **8310b** of the spacer **8310** of the guiding assembly **8300** via one or more fasteners.

As best shown in FIGS. 11L and 11M, the lower guiding and mounting component **8800** includes a transition assembly receiving component **8810** connected to an anchor system base mounting component **8830**. The transition assembly receiving component **8810** is generally cylindrical and includes an exterior cylindrical aircraft-landing device attachment surface **8813** and interior cylindrical surfaces **8814** and **8818**. An annular lip **8816** that extends radially outwardly from the cylindrical surface **8818** separates the interior cylindrical surfaces **8814** and **8818**. The interior cylindrical surface **8814** defines a flexible capture member receiving bore, and the interior cylindrical surface **8818** defines a transition assembly receiving bore.

The anchor system base mounting component **8830** includes an upper portion **8832** and a lower portion **8834** spaced apart by a middle portion **8836**. The middle portion **8836** is partially recessed radially inward relative to the upper and lower portions **8832** and **8834**. This defines an anchor system base receiving channel (not labeled). As best shown in FIG. 11E, hose clamps (not labeled) clamp a lower portion (not labeled) of the aircraft-supporting body **8100** to the aircraft-landing device attachment surface **8813** of the

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transition assembly receiving component **8810** to attach these components to one another. The transition assembly receiving bore receives part of the transition assembly **3700** in the transition assembly receiving bore, and a fastener is used to attach the transition assembly **3700** to the transition assembly receiving bore. Once attached, the flexible capture member receiving bore of the lower guiding and mounting component **8800** is in fluid communication with the flexible capture member receiving bore of the transition assembly **3700**. The lower guiding and mounting component **8800** is attached to the anchor system base **3100** via the anchor system base receiving channel. That is, the anchor system base **3100** slidably receives the lower guiding and mounting component **8800**. A fastener may be used to further secure these elements together.

As best shown in FIG. 11D, the inflation device **8600** is attached to (such as via stitching, adhesive, or in any other suitable manner) and extends downward from the underside of the aircraft-supporting body **8100**. The inflation device **8600** is in fluid communication with the interior of the aircraft-supporting body **8100** (which is in fluid communication with the interiors of the supports **8200a-8200d**). The inflation device **8600** is sized, positioned, and otherwise configured to be attached to a suitable inflator (such as via a hose clamp or any other suitable manner of attachment) to enable inflation of the aircraft-supporting body **8100** and the supports **8200** and **8300** as described below.

As best shown in FIG. 11D, the deflation device **8700** is located on the underside of the aircraft-supporting body **8100**. The deflation device **8700** includes a deflation element, such as a removable cap or a valve, that is switchable between a deflation configuration in which the deflation element enables air to flow out of the aircraft-supporting body **8100** and a sealed configuration in which the deflation element does not enable air to flow out of the aircraft-supporting body **8100**. The deflation device **8700** enables an operator to quickly deflate the aircraft-supporting body **8100** and the supports **8200a-8200d** with minimal effort, such as by removing a cap or opening a valve.

In another embodiment, the aircraft-landing device does not include the intermediate guiding element. In this embodiment, the upper guiding element and the lower guiding and mounting element are attached to opposing ends of the spacer such that the spacer extends between the upper guiding element and the lower guiding and mounting element.

In another embodiment, the anchor system base threadably receives the lower guiding and mounting component.

In other embodiments, the aircraft-supporting body includes stabilizing ribs extending along its tapered walls. In further embodiments, the bottom of the aircraft-supporting body is stiff in bending.

In another embodiment, a plurality of tension members are attached to and extend between the interior of the aircraft-supporting body and the outer surface of the flexible capture member receiving tube. These tension members help support the weight/tension of the flexible capture member receiving tube and help maintain the apex of the aircraft-landing device erect.

In certain embodiments, tie-downs (such as ropes, bungees, and the like) may be used to secure the aircraft-landing device to the ground or to a suitable base structure, such as the above-described aircraft system base.

In other embodiments, the aircraft-supporting body is formed from compliant rods rather than inflatable tubes.

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5. Flexible Capture Member

As best shown in FIGS. 12F-12I, the flexible capture member **5000** is attachable to the rotorcraft **30** and the anchor system **3000** and threadable through the aircraft-landing device **8000** to facilitate retrieval of the fixed-wing aircraft **20a** from free, wing-borne flight. The flexible capture member may be a rope (such as a Spectra rope) or other similar element.

In some embodiments, the flexible capture member includes an elastic portion, such as a bungee or similar element, at the end attachable to the rotorcraft. The elastic portion may be rigged such that a portion of the strain energy is directed into a damping element such as a metal ring or a one-way pulley. By rigging the elastic portion as a compliant damper (as opposed to a spring), more energy is absorbed during capture, and undesirable ricochet is minimized.

In some embodiments, the flexible capture member includes a capture portion that is thicker near its ends (such as within 12 feet of each end) that it is in its center. In one embodiment, both ends of the capture portion terminate in a Brummel eye splice in which the buried tails constitute the thicker portion of the capture portion.

In some embodiments in which the flexible capture member includes a rope, the flexible capture member includes an elastic member inside the core of the rope. The elastic member shortens the rope as it slackens and is wound onto the drum. During payout, the elastic member allows the rope to lengthen as it leaves the drum, and a lossy payout device is formed.

6. Accessories Container and Other Components

As best shown in FIG. 9H, the anchor system **3000** is attached to the container bottom **4000a** of an anchor system and accessory storage container to enable easy and compact storage of the anchor system **3000** and various accessories, such as (but not limited to): a generator; the flexible capture member **5000**; an R/C transmitter stand that helps enforce geo-referenced joystick commands of the R/C controller; a fire extinguisher; shovels; hard hats. Further, certain components of the hydraulic system **7300** are attached to the container bottom **4000a**.

7. Methods of Operation

As described in detail below: (1) the aircraft launch apparatus **10**, the rotorcraft **30**, and the storage and launch system **2000** are usable to facilitate launch of the fixed-wing aircraft **20a** into free, wing-borne flight; and (2) the rotorcraft **30**, the anchor system **3000**, the flexible capture member **5000**, and the aircraft-landing device **8000** are usable to facilitate retrieval of the fixed-wing aircraft **20a** from free, wing-borne flight.

7.1 Rotorcraft-Assisted Fixed-Wing Aircraft Launch Method

FIGS. 12A-12E diagrammatically show launch of the fixed-wing aircraft **20a** into free, wing-borne flight via use of the aircraft launch apparatus **10**, the rotorcraft **30**, and the storage and launch system **2000**.

The rotorcraft-assisted launch method for the fixed-wing aircraft **20a** begins with the aircraft launch apparatus **10** disassembled and stored in the storage and launch system **2000**. The aircraft launch apparatus operator unpacks the nine modules and then mounts the fixed-wing aircraft **20a** to the launch-assist bracket **2200** by: (1) resting the first and second launch-assist elements that extend below the wings of the fixed-wing aircraft **20a** on the first aircraft-engaging walls **2212a** and **2212b** of the first and second aircraft engagers **2210a** and **2210b**, respectively; and (2) enabling the fixed-wing aircraft **20a** to slide down the first aircraft-engaging walls **2212a** and **2212b** (due to their sloped orientation) until the first and second launch-assist elements

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engage the slide-preventing devices **2216a** and **2216b** of the first and second aircraft engagers **2210a** and **221b**, respectively. At this point, the aircraft launch apparatus operator can release the fixed-wing aircraft **20a** because the launch-assist bracket **2200** retains the fixed-wing aircraft **20a** in the desired launch orientation. FIG. 12A shows the fixed-wing aircraft **20a** mounted to the launch-assist bracket **2200**.

The aircraft launch apparatus operator attaches the hub module **100** to the fixed-wing aircraft **20a** by: (1) operating the front engager servo motor **6341** (either manually or remotely via the R/C controller) to rotate the front engager **6320** to the release rotational position; (2) inserting the trailing edges of the wings of the fixed-wing aircraft **20a** into the trailing edge receiving channels **6364a** of the pivotable portions **6364** of the rear engagers **6360**; (3) positioning the saddle **300** relative to the fixed-wing aircraft **20a** such that the leading edge engaging surfaces **6323b** and **6326b** of the front engager **6320** are adjacent the leading edges of the wings of the fixed-wing aircraft **20a**; (4) operating the front engager servo motor **6341** (either manually or remotely via the R/C controller) to rotate the front engager **6320** to the attached rotational position such that the leading edge engaging surfaces **6323b** and **6326b** of the front engager **6320** contact the leading edges of the wings of the fixed-wing aircraft **20a**; and (5) operating the lock servo motor **6345** (either manually or remotely via the R/C controller) to rotate the lock arm **6346a** into the front engager rotation-preventing rotational position so the locking extension **6346a** on the end of the lock arm **6346** engages the front engager arm lock device **6342a** of the front engager arm **6342**.

At this point the fixed-wing aircraft **20a** is attached to the saddle **300** because the front engager **6320** and the rear engagers **6360** engage the wings of the fixed-wing aircraft **20a** therebetween. The pivotable portions **6364** of the rear engagers **6360** are rotationally positioned relative to the bodies **6362** of the rear engagers **6360** such that the trailing-edge engaging surfaces **6362a** are not within the trailing-edge receiving channels of the pivotable portions **6364**. The positioning of the servo spacer **6344b** and the fact that the locking extension **6346a** is engaged to the front engager arm lock device **6342a** of the front engager arm **6342** ensure the front engager servo motor **6341** cannot rotate the front engager **6320** from the attached rotational position to the release rotational position. This prevents undesired release of the fixed-wing aircraft **20a** from the saddle **300** (and the aircraft launch apparatus **10**).

After the hub module **100** is attached to the fixed-wing aircraft **20a**, the aircraft launch apparatus operator attaches the front and rear landing gear modules **600a** to **600d** to their respective arm modules **400a** to **400d** and attaches and locks the arm modules **400a** to **400d** to the hub module **100** to complete assembly of the aircraft launch apparatus **10**. The aircraft launch apparatus operator attaches one end of the snag-prevention member **299** to the snag-prevention member attachment device **284** and the other end of the snag-prevention member **299** to a rotorcraft flexible member **30a**, such as a suitable rope. The aircraft launch apparatus operator attaches the other end of the rotorcraft flexible member **30a** to the rotorcraft **30**, such as via a carabiner or other suitable attachment mechanism. The aircraft launch apparatus operator begins the engine start-up procedure for the fixed-wing aircraft **20a**. FIG. 12B shows the assembled aircraft launch apparatus **10** attached to the fixed-wing aircraft **20a** and to the rotorcraft **30** (via the rotorcraft flexible member **30a**). The guard **282** prevents the snag-prevention member **299** from contacting the empennage or

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propeller of the fixed-wing aircraft **20a**, and the snag-prevention member **299** helps keep the rotorcraft flexible member **30a** from contacting the empennage or propeller of the fixed-wing aircraft **20a**.

The rotorcraft operator controls the rotorcraft **30** to climb from its downwind pre-launch position, travel upwind until the rotorcraft **30** is above the aircraft launch apparatus **10** (and attached fixed-wing aircraft **20a**), and ascend a safe altitude (about 700 feet or any other suitable distance) above ground level to lift the aircraft launch apparatus **10** (and attached fixed-wing aircraft **20a**) from the launch-assist bracket **2200**, as shown in FIG. 12C.

The rotorcraft operator controls the rotorcraft **30** to travel horizontally until reaching about 30 to 40 knots-indicated airspeed (or any other suitable knots-indicated airspeed), as shown in FIG. 12D. As the rotorcraft **30** travels horizontally, the rear landing gear of the aircraft launch apparatus **10** act as vertical stabilizers (or fins), which ensures that the front of the aircraft launch apparatus **10** and the nose of the attached fixed-wing aircraft **20a** point generally into the airflow.

At this point, the aircraft launch apparatus operator controls the aircraft launch apparatus **10** to release the fixed-wing aircraft **20a** from the saddle **300**, as shown in FIG. 12E. Releasing the fixed-wing aircraft **20a** from the saddle **300** is a two-step process. Releasing the fixed-wing aircraft **20a** from the saddle **300** while the rotorcraft **30** is airborne is a two-step process. To release the fixed-wing aircraft **20a** from the saddle **300** (and the aircraft launch apparatus **10**), the operator first remotely controls the lock servo motor **6345** (via the R/C controller) to rotate the lock arm **6346** into the front engager rotation-enabling rotational position. Second, the operator remotely controls the front engager servo motor **6341** (via the R/C controller) to rotate the front engager **6320** from the attached rotational position to the release rotational position. As the front engager servo motor **6341** rotates the front engager **6320** from the attached rotational position to the release rotational position, the first and second leading edge engaging surfaces **6323b** and **6326b** of the front engager **6320** rotate away from and begin to lose contact with the leading edge of the wing of the fixed-wing aircraft **20a**. As the front engager **6320** continues to rotate clear of the wings of the fixed-wing aircraft **20a**, the pivotable portions **6364** of the rear engagers **6360** enable the fixed-wing aircraft **20a** to freely pivot relative to the saddle base bracket **6310**, the first and second saddle side brackets **6312** and **6314**, and the bodies **6362** of the rear engagers **6360** as gravity pulls the nose of the fixed-wing aircraft **20a** downward. As this occurs, the trailing edge engaging surfaces **6362a** of the bodies **6362** of the rear engagers **6360** gradually enter the trailing-edge receiving channels of the pivotable portions **6364**. As this occurs, the trailing-edge engaging surfaces **6362a** contact the trailing edge of the wings and force them out of the trailing edge receiving channels, thus releasing the fixed-wing aircraft **20a** from the saddle **300** (and the aircraft launch apparatus) into free flight. The trailing edge disengagement occurs before the empennage rotates into the aircraft launch apparatus support structure.

After release, the rotorcraft operator controls the rotorcraft **30** to travel to an aircraft launch apparatus landing area. The rotorcraft operator controls the rotorcraft **30** to descend until the aircraft launch apparatus **10** lands at the aircraft launch apparatus landing area. Afterwards, a ground crew may detach the snag-prevention member **299** from the rotorcraft flexible member **30a**, thereby detaching the aircraft launch apparatus **10** from the rotorcraft **30**. In certain embodiments, the aircraft launch apparatus **10** includes

flexible members (such as ropes) that the ground crew can catch and hold to stop the aircraft launch apparatus 10 from spinning and/or swinging before it lands. The rotorcraft operator then controls the rotorcraft 30 to land elsewhere at a rotorcraft landing area.

If launch is aborted, the fixed-wing aircraft 30 is held securely by the aircraft launch apparatus 10 and held safely above the landing surface by virtue of the landing gear of the aircraft launch apparatus 10.

In other embodiments in which the saddle is that described in U.S. Patent Application Publication No. 2017/0158318, the fixed-wing aircraft launch method incorporates the procedure for releasing the fixed-wing aircraft from the saddle described in U.S. Patent Application Publication No. 2017/0158318.

7.2 Rotorcraft-Assisted Fixed-Wing Aircraft Retrieval Method

FIGS. 12F-12I diagrammatically show retrieval of the fixed-wing aircraft 20a from free, wing-borne flight via use of the rotorcraft 30, the anchor system 3000, the flexible capture member 5000, and the aircraft-landing device 8000. Although not shown below, a substantially similar process may be used to retrieve the fixed-wing aircraft 20b from free, wing-borne flight. FIG. 12J is a graph 7900 of the pressure P1 of the hydraulic fluid at the accumulator 7352 of the hydraulic system 7300 over time during the fixed-wing aircraft retrieval process. For simplicity, in this example embodiment P1 is assumed to be 0 psi at time T0.

To retrieve the fixed-wing aircraft 20a from free, wing-borne flight, the anchor system operator positions the anchor system 3000 at a retrieval location. Before time T0, while the electric hydraulic pump 7350 is switched off, the anchor system operator pulls some of the flexible capture member 5000 off of the drum 3510 and feeds it through the level wind system 3600 and around the transition pulley 3730 of the transition assembly 3700. From there, the anchor system operator feeds the flexible capture member 5000 through the flexible capture member receiving bores of the transition assembly 3700, the lower guiding and mounting component 8800, the intermediate guiding component 8500, and the upper guiding component 8400 such that the free end of the flexible capture member 5000 exits the upper guiding component 8400. The anchor system operator then attaches the free end of the flexible capture member 5000 to one end of the rotorcraft flexible member 30a attached to the rotorcraft 30. Since the flexible capture member 5000 is slack between the drum 7312 and the rotorcraft flexible member 30a, $F_{OPPOSING}$ is negligible at time T0. The anchor system operator activates a blower (not shown), which inflates the aircraft-landing device 8000.

At time T0, the anchor system operator switches the electric hydraulic pump 7350 on to begin a haul-in phase of the fixed-wing aircraft retrieval process to take up the slack in the flexible capture member 5000. Since P1 is 0 psi—i.e., less than the 400 psi pressure switch lower set point—the pressure switch 7364 electrically connects the power source 7400 and the electric hydraulic pump 7350. As described above, the electric hydraulic pump 7350 pumps hydraulic fluid at the 100 psi pump outlet pressure to drive the hydraulic motor 7358 to rotate the drum 3510 counter-clockwise (from the viewpoint in FIG. 10A) and take up the slack in the flexible capture member 5000.

At time T1, all of the slack in the flexible capture member 5000 has wound around the drum 7312, and $F_{OPPOSING}$ equals F_{DRUM} . This begins a neutral phase of the fixed-wing aircraft retrieval process before rotorcraft climb. Flow through the hydraulic motor 7358 slows to mere leakage,

and electric hydraulic pump 7350 begins charging the accumulator 7352. Once P1 reaches the 550 psi pressure switch upper set point, the pressure switch 7364 electrically disconnects the power source 7400 and the electric hydraulic pump 7350. The accumulator 7352 begins discharging to compensate for the hydraulic fluid leaking through the hydraulic motor 7358. The pressure switch 7364 continues alternating between electrically connecting and electrically disconnecting the power source 7400 and the electric hydraulic pump 7350 during the neutral phase so P1 alternates between 400 and 550 psi.

At time T2, the rotorcraft operator begins controlling the rotorcraft 30 to ascend to a retrieval position above the anchor system 3000. This begins a payout phase of the fixed-wing aircraft retrieval process. The climbing rotorcraft 30 exerts a force $F_{OPPOSING}$ on the flexible capture member 5000 that exceeds F_{DRUM} , which causes the drum 7312 to spin clockwise (from the viewpoint in FIG. 12D) and payout the flexible capture member 5000. As described above, this increases P1 to (or even above) the 600 psi pressure relief valve set point. Once the rotorcraft 30 reaches its desired height (just before time T3), the rotorcraft operator controls the rotorcraft 30 to stop climbing and begin station-keeping relative to the anchor system 3000. Since $F_{OPPOSING}$ equals F_{DRUM} , P1 decreases to 550 psi.

At time T3, as shown in FIG. 12E, the rotorcraft operator controls the rotorcraft 30 to station-keep relative to the anchor system 3000, at which point $F_{OPPOSING}$ equals F_{DRUM} . This begins a neutral phase of the fixed-wing aircraft retrieval process, described above with respect to T1 through T2.

At time T4, as shown in FIG. 12G, the fixed-wing aircraft operator controls the fixed-wing aircraft 20a to contact and capture the flexible capture member 5000 extending between the rotorcraft flexible member 30a and the drum 7312. This begins a payout phase of the fixed-wing aircraft retrieval process. The impact of the fixed-wing aircraft 20a on the flexible capture member 5000 exerts a force $F_{OPPOSING}$ on the flexible capture member 5000 that exceeds F_{DRUM} , which causes the drum 7312 to spin clockwise (from the viewpoint in FIG. 10D) and payout the flexible capture member 5000. As described above, this increases P1 to (or even above) 600 psi—i.e., the pressure relief valve set point. In the payout phase, P1 maintains its 1,000 psi value as of time T4. Once the movement of the fixed-wing aircraft 20a has dampened such that $F_{OPPOSING}$ no longer exceeds F_{DRUM} (just before time T5), P1 decreases to 550 psi.

At time T5, as shown in FIG. 12H, the rotorcraft operator controls the rotorcraft 30 to descend toward the aircraft-landing device 8000, and there is slack in the flexible capture member 5000 extending between the captured fixed-wing aircraft 20a and the drum 7312. Accordingly, $F_{OPPOSING}$ is less than F_{DRUM} , and the haul-in phase begins, as described above for time T0 through T1.

At time T6, as shown in FIG. 12I, after the fixed-wing aircraft 20a has reached and is resting on the aircraft-landing device 8000, the rotorcraft operator controls the rotorcraft 30 to hover, and $F_{OPPOSING}$ equals F_{DRUM} . This begins a neutral phase of the fixed-wing aircraft retrieval process, described above with respect to T1 through T2.

As the rotorcraft operator controls the rotorcraft 30 to hover, the ground crew detaches the rotorcraft flexible member 30a from the flexible capture member 5000. The rotorcraft operator controls the rotorcraft 30 to land clear of the aircraft-landing device 8000 and the fixed-wing aircraft 20a.

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The anchor system **3000** is therefore configured to quickly and automatically modify its operation to regulate the force **FORUM** applied to the flexible capture member as the fixed-wing aircraft retrieval process switches between the haul-in, neutral, and payout phases.

Various changes and modifications to the presently preferred embodiments described herein will be apparent to those skilled in the art. These changes and modifications can be made without departing from the spirit and scope of the present subject matter and without diminishing its intended advantages. It is intended that such changes and modifications be covered by the appended claims.

The invention claimed is:

1. A method for capturing a fixed-wing aircraft from wing-borne flight, the method comprising:
 - positioning an anchor system at a retrieval location;
 - extending a flexible capture member from the anchor system through a first receiving bore and a second receiving bore of an aircraft landing device, wherein the aircraft landing device includes a bearing positioned proximate the first receiving bore and configured to contact the flexible capture member;
 - attaching the flexible capture member to a rotorcraft;
 - ascending the rotorcraft to a retrieval height above the retrieval location;
 - intercepting the fixed-wing aircraft via the flexible capture member; and
 - lowering the fixed-wing aircraft onto the aircraft landing device.
2. The method of claim 1, including operating the anchor system to payout and haul in the flexible capture member based on one or more forces acting on the flexible capture member.
3. The method of claim 1, including operating the anchor system to reel in the flexible capture member to remove slack from the flexible capture member after attaching the flexible capture member to the rotorcraft and prior to ascending the rotorcraft to the retrieval height.
4. The method of claim 1, including operating the anchor system to maintain a threshold force acting on the flexible capture member from the anchor system, after attaching the flexible capture member to the rotorcraft.
5. The method of claim 1, including operating the anchor system to pay out the flexible member responsive to an impact force on the flexible capture member caused by the fixed-wing aircraft.
6. The method of claim 1, including extending the flexible capture member from a drum through a level wind system of the anchor system.
7. The method of claim 1, including extending the flexible capture member from the anchor system through an aperture defined by the aircraft landing device.
8. The method of claim 1, including centering the aircraft landing device on the retrieval location.

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9. The method of claim 1, including inflating the aircraft landing device prior to lowering the fixed-wing aircraft onto the aircraft landing device.

10. A fixed-wing aircraft capturing system comprising:

- an aircraft landing device that defines a first receiving bore and a second receiving bore, wherein the aircraft landing device includes a bearing positioned proximate the first receiving bore;

an anchor system positionable at a retrieval location; and
 a flexible capture member extendable from the anchor system through the first receiving bore and the second receiving bore of the aircraft landing device and couplable to a rotorcraft, wherein the bearing of the aircraft landing device is configured to contact the flexible capture member;

wherein the flexible member is configured to intercept a fixed-wing aircraft, and wherein the aircraft landing device is configured to support the fixed-wing aircraft after it has been intercepted by the flexible capture member.

11. The system of claim 10, wherein the anchor system comprises a hydraulic system configured to payout and haul in the flexible capture member based on one or more forces acting on the flexible capture member.

12. The system of claim 10, wherein the flexible capture member comprises a compliant damping element.

13. The system of claim 12, wherein the compliant damping element is configured to reduce peak forces acting on the rotorcraft during the intercept of the fixed-wing aircraft via the flexible capture member.

14. The system of claim 10, wherein the flexible capture member is extendable from the anchor system through the aircraft landing device, such that the aircraft landing device is collocated with the anchor system at the retrieval location.

15. The system of claim 10, wherein the anchor system includes a drum and a level wind system.

16. The system of claim 15, wherein the flexible capture member is extendable from the drum through the level wind system.

17. The system of claim 10, wherein the aircraft landing device is inflatable.

18. The system of claim 10, wherein an upper surface of the aircraft landing device forms a cone shape.

19. The system of claim 17, wherein the aircraft landing device has an internal support to maintain height against the weight of the fixed-wing aircraft.

20. The system of claim 10, wherein the aircraft landing device includes legs that straddle the anchor system.

21. The system of claim 10, wherein the aircraft landing system includes at least one ballast weight to stabilize against side loads.

22. The system of claim 10, wherein payout tension is arranged to minimize forces on the rotorcraft during impact, but sufficiently high to prevent payout after the fixed-wing aircraft has been lowered to the aircraft landing device.

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